

Hybrid High-Order methods for diffusion problems on polytopes and curved elements

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MAFELAP, 19 June 2019



Features

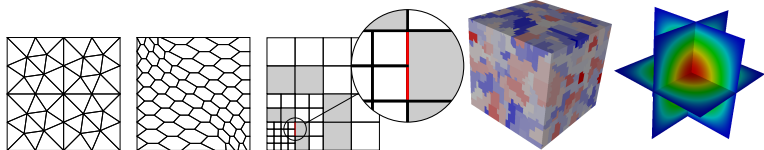


Figure: Examples of supported meshes $\mathcal{M}_h = (\mathcal{T}_h, \mathcal{F}_h)$ in 2d and 3d

- Capability of handling **general polyhedral meshes**
- Construction valid for **arbitrary space dimensions**
- Arbitrary **approximation order** (including $k = 0$)
- **Physical fidelity** leading to robustness in singular limits
- Natural extension to **nonlinear problems**
- Reduced **computational cost** after static condensation

- HHO for pure diffusion [DP, Ern, Lemaire, 2014]
- Curved faces and comparison with DG [Botti and DP, 2018]
- Optimal approximation for projectors [DP and Droniou, 2017ab]

New book!

D. A. Di Pietro and J. Droniou

The Hybrid High-Order Method for Polytopal Meshes

Design, Analysis, and Applications

516 pages, <http://hal.archives-ouvertes.fr/hal-02151813>

Model problem

- Let $\Omega \subset \mathbb{R}^d$, $d \geq 1$, denote a bounded connected polyhedral domain
- For $f \in L^2(\Omega)$, we consider the **Poisson problem**

$$\begin{aligned} -\Delta u &= f && \text{in } \Omega \\ u &= 0 && \text{on } \partial\Omega \end{aligned}$$

- In weak form: Find $u \in U := H_0^1(\Omega)$ s.t.

$$a(u, v) := \int_{\Omega} \nabla u \cdot \nabla v = \int_{\Omega} f v \quad \forall v \in U$$

Projectors on local polynomial spaces

- With $X \in \mathcal{T}_h \cup \mathcal{F}_h$, the L^2 -projector $\pi_X^{0,\ell} : L^2(X) \rightarrow \mathbb{P}^\ell(X)$ is s.t.

$$\int_X (\pi_X^{0,\ell} v - v) w = 0 \text{ for all } w \in \mathbb{P}^\ell(X)$$

- The elliptic projector $\pi_T^{1,\ell} : H^1(T) \rightarrow \mathbb{P}^\ell(T)$ is s.t.

$$\int_T \nabla(\pi_T^{1,\ell} v - v) \cdot \nabla w = 0 \text{ for all } w \in \mathbb{P}^\ell(T) \text{ and } \int_T (\pi_T^{1,\ell} v - v) = 0$$

- Both have optimal approximation properties in $\mathbb{P}^\ell(T)$

Computing $\pi_T^{1,k+1}$ from L^2 -projections of degree k

- Recall the following IBP valid for all $v \in H^1(T)$ and all $w \in C^\infty(\bar{T})$:

$$\int_T \nabla v \cdot \nabla w = - \int_T v \Delta w + \sum_{F \in \mathcal{F}_T} \int_F v \nabla w \cdot \mathbf{n}_{TF}$$

- Specializing it to $w \in \mathbb{P}^{k+1}(T)$, we can write

$$\int_T \nabla \pi_T^{1,k+1} v \cdot \nabla w = - \int_T \pi_T^{0,k} v \Delta w + \sum_{F \in \mathcal{F}_T} \int_F \pi_F^{0,k} v \nabla w \cdot \mathbf{n}_{TF}$$

- Moreover, it can be easily seen that

$$\int_T (\pi_T^{1,k+1} v - v) = \int_T (\pi_T^{1,k+1} v - \pi_T^{0,k} v) = 0$$

- **Hence, $\pi_T^{1,k+1} v$ can be computed from $\pi_T^{0,k} v$ and $(\pi_F^{0,k} v)_{F \in \mathcal{F}_T}$!**

Discrete unknowns

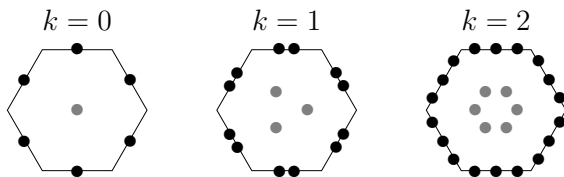


Figure: \underline{U}_T^k for $k \in \{0, 1, 2\}$

- Let a polynomial degree $k \geq 0$ be fixed
- For all $T \in \mathcal{T}_h$, we define the **local space of discrete unknowns**

$$\underline{U}_T^k := \{ \underline{v}_T = (v_T, (v_F)_{F \in \mathcal{F}_T}) : v_T \in \mathbb{P}^k(T) \text{ and } v_F \in \mathbb{P}^k(F) \quad \forall F \in \mathcal{F}_T \}$$

- The **local interpolator** $\underline{I}_T^k : H^1(T) \rightarrow \underline{U}_T^k$ is s.t., for all $v \in H^1(T)$,

$$\underline{I}_T^k v := (\pi_T^{0,k} v, (\pi_F^{0,k} v)_{F \in \mathcal{F}_T})$$

Local potential reconstruction

- Let $T \in \mathcal{T}_h$. We define the local **potential reconstruction** operator

$$r_T^{k+1} : \underline{U}_T^k \rightarrow \mathbb{P}^{k+1}(T)$$

s.t., for all $\underline{v}_T \in \underline{U}_T^k$, $\int_T (r_T^{k+1} \underline{v}_T - v_T) = 0$ and

$$\int_T \nabla r_T^{k+1} \underline{v}_T \cdot \nabla w = - \int_T v_T \Delta w + \sum_{F \in \mathcal{F}_T} \int_F v_F \nabla w \cdot \mathbf{n}_{TF} \quad \forall w \in \mathbb{P}^{k+1}(T)$$

- By construction, we have

$$r_T^{k+1} \circ \underline{I}_T^k = \pi_T^{1,k+1}$$

- $(r_T^{k+1} \circ \underline{I}_T^k)$ has therefore **optimal approximation properties** in $\mathbb{P}^{k+1}(T)$

- We would be tempted to approximate

$$a|_T(u, v) \approx a|_T(r_T^{k+1} \underline{u}_T, r_T^{k+1} \underline{v}_T)$$

- This choice, however, is **not stable** in general. We consider instead

$$a_T(\underline{u}_T, \underline{v}_T) := a|_T(r_T^{k+1} \underline{u}_T, r_T^{k+1} \underline{v}_T) + s_T(\underline{u}_T, \underline{v}_T)$$

- The role of s_T is to ensure **$\|\cdot\|_{1,T}$ -coercivity** with

$$\|\underline{v}_T\|_{1,T}^2 := \|\nabla v_T\|_{L^2(T)^d}^2 + \sum_{F \in \mathcal{F}_T} \frac{1}{h_F} \|v_F - v_T\|_{L^2(F)}^2 \quad \forall \underline{v}_T \in \underline{U}_T^k$$

Assumption (Stabilization bilinear form)

The bilinear form $s_T : \underline{U}_T^k \times \underline{U}_T^k \rightarrow \mathbb{R}$ satisfies the following properties:

- **Symmetry and positivity.** s_T is symmetric and positive semidefinite.
- **Stability.** It holds, with hidden constant independent of h and T ,

$$a_T(\underline{v}_T, \underline{v}_T)^{\frac{1}{2}} \simeq \|\underline{v}_T\|_{1,T} \quad \forall \underline{v}_T \in \underline{U}_T^k.$$

- **Polynomial consistency.** For all $w \in \mathbb{P}^{k+1}(T)$ and all $\underline{v}_T \in \underline{U}_T^k$,

$$s_T(\underline{I}_T^k w, \underline{v}_T) = 0.$$

- The following stable choice **violates polynomial consistency**:

$$s_T^{\text{hdg}}(\underline{u}_T, \underline{v}_T) := \sum_{F \in \mathcal{F}_T} h_F^{-1} \int_F (u_F - u_T) (v_F - v_T)$$

- To circumvent this problem, we penalize the **high-order differences**

$$(\delta_T^k \underline{v}_T, (\delta_{TF}^k \underline{v}_T)_{F \in \mathcal{F}_T}) := \underline{r}_T^k \underline{r}_T^{k+1} \underline{v}_T - \underline{v}_T$$

- The classical HHO stabilization bilinear form reads

$$s_T(\underline{u}_T, \underline{v}_T) := \sum_{F \in \mathcal{F}_T} h_F^{-1} \int_F (\delta_T^k - \delta_{TF}^k) \underline{u}_T (\delta_T^k - \delta_{TF}^k) \underline{v}_T$$

Discrete problem

- Define the **global space** with single-valued interface unknowns

$$\underline{U}_h^k := \left\{ \underline{v}_h = ((v_T)_{T \in \mathcal{T}_h}, (v_F)_{F \in \mathcal{F}_h}) : \right. \\ \left. v_T \in \mathbb{P}^k(T) \quad \forall T \in \mathcal{T}_h \text{ and } v_F \in \mathbb{P}^k(F) \quad \forall F \in \mathcal{F}_h \right\}$$

and its subspace with **strongly enforced boundary conditions**

$$\underline{U}_{h,0}^k := \{ \underline{v}_h \in \underline{U}_h^k : v_F = 0 \quad \forall F \in \mathcal{F}_h^b \}$$

- The discrete problem reads: Find $\underline{u}_h \in \underline{U}_{h,0}^k$ s.t.

$$\mathbf{a}_h(\underline{u}_h, \underline{v}_h) := \sum_{T \in \mathcal{T}_h} \mathbf{a}_T(\underline{u}_T, \underline{v}_T) = \sum_{T \in \mathcal{T}_h} \int_T f v_T \quad \forall \underline{v}_h \in \underline{U}_{h,0}^k$$

- Well-posedness** follows from coercivity and discrete Poincaré

Convergence

Theorem (Energy-norm error estimate)

Assume $u \in H_0^1(\Omega) \cap H^{k+2}(\mathcal{T}_h)$. The following energy error estimate holds:

$$\|\nabla_h(r_h^{k+1}\underline{u}_h - u)\| + |\underline{u}_h|_{s,h} \lesssim h^{k+1} |u|_{H^{k+2}(\mathcal{T}_h)}$$

with $(r_h^{k+1}\underline{u}_h)|_T := r_T^{k+1}\underline{u}_T$ for all $T \in \mathcal{T}_h$ and $|\underline{u}_h|_{s,h}^2 := \sum_{T \in \mathcal{T}_h} s_T(\underline{u}_T, \underline{u}_T)$.

Theorem (Superclose L^2 -norm error estimate)

Further assuming *elliptic regularity* and $f \in H^1(\mathcal{T}_h)$ if $k = 0$,

$$\|r_h^{k+1}\underline{u}_h - u\| \lesssim h^{k+2} \mathcal{N}_k,$$

with $\mathcal{N}_0 := \|f\|_{H^1(\mathcal{T}_h)}$ and $\mathcal{N}_k := |u|_{H^{k+2}(\mathcal{T}_h)}$ for $k \geq 1$.

Numerical examples

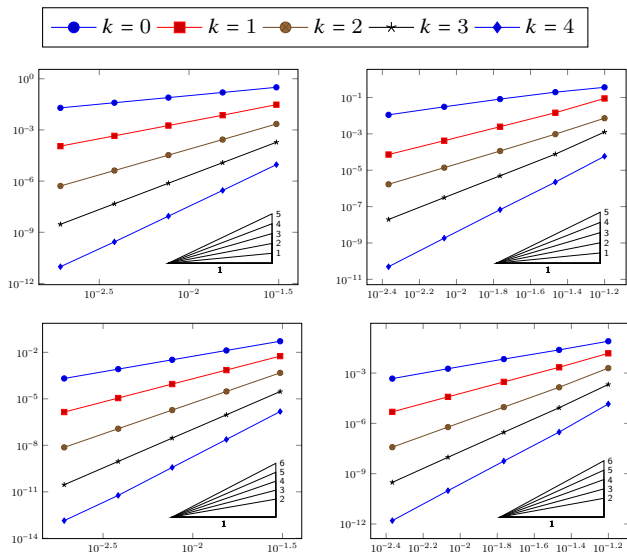


Figure: Trigonometric solution, energy norm (top) and L^2 -norm vs. h (bottom) for triangular (left) and polygonal (right) mesh sequences

Extension to curved faces I

- Let $F \in \mathcal{F}_h$ denote a mesh face
- Let σ be **reference face** and Ψ_F an **invertible mapping** s.t.

$$F = \Psi_F(\sigma)$$

- We assume that $\Psi_F \in \mathbb{M}_{d-1}^m(\sigma)^d$ with $m \geq 1$ and

$$\mathbb{M}_{d-1}^m(\sigma) \in \{\mathbb{P}_{d-1}^m(\sigma), \mathbb{S}_{d-1}^m(\sigma), \mathbb{Q}_{d-1}^m(\sigma)\}$$

- The **effective mapping order** is the smallest integer \tilde{m} s.t.

$$\Psi_F \in \mathbb{P}_{d-1}^{\tilde{m}}(\sigma)^d$$

Extension to curved faces II

- Given an integer $l \geq k$, consider the **modified HHO space**:

$$\underline{U}_h^{k,l} := \left\{ v_T = (v_T, (v_\sigma)_{\Psi_F(\sigma) \in \mathcal{F}_T}) : \right. \\ \left. v_T \in \mathbb{P}^k(T) \quad \forall T \in \mathcal{T}_h \text{ and } v_\sigma \in \mathbb{P}_{d-1}^l(\sigma) \quad \forall \Psi_F(\sigma) \in \mathcal{F}_h \right\}$$

- We interpolate at faces mapping $v : F \rightarrow \mathbb{R}$ on $\pi_\sigma^l v \in \mathbb{P}_{d-1}^l(\sigma)$ s.t.

$$\int_\sigma (v \circ \Psi_F - \pi_\sigma^l v) z |J_{\Psi_F}| = 0 \quad \forall z \in \mathbb{P}_{d-1}^k(\sigma)$$

- For all $T \in \mathcal{T}_h$, $r_T^{k+1} : \underline{U}_T^{k,l} \rightarrow \mathbb{P}^{k+1}(T)$ is s.t., for all $w \in \mathbb{P}^{k+1}(T)$,

$$\int_T \nabla r_T^{k+1} \underline{v}_T \cdot \nabla w = - \int_T v_T \Delta w + \sum_{F=\Psi_F(\sigma) \in \mathcal{F}_T} \int_F (v_\sigma \circ \Psi_F^{-1}) \nabla w \cdot \mathbf{n}_{TF}$$

- What about the commutation with the elliptic projector?**

Extension to curved faces III

Proposition (Comparison with the elliptic projector)

It holds, for all $T \in \mathcal{T}_h$:

- If $\tilde{m} = 1$ then, for all $v \in H^1(T)$,

$$r_T^{k+1} \underline{I}_T^{k,l} v = \pi_T^{1,k+1} v \quad \forall l \geq k;$$

- If $\tilde{m} > 1$, for all $v \in H^{\tilde{k}+1}(T)$ with $\tilde{k} := \lfloor l/\tilde{m} \rfloor$,

$$\|\nabla(r_T^{k+1} \underline{I}_T^{k,l} v - \pi_T^{1,k+1} v)\|_T \lesssim h_T^{\tilde{k}} |v|_{H^{\tilde{k}+1}(T)}.$$

Optimal error estimates are obtained with the following choice:

$$l_{\text{opt}} = \begin{cases} k & \text{if } \tilde{m} = 1, \\ \tilde{m}(k+1) & \text{if } \tilde{m} > 1. \end{cases}$$

Numerical examples

$d = 2$, tri3 and tri6 meshes, quadratic solution

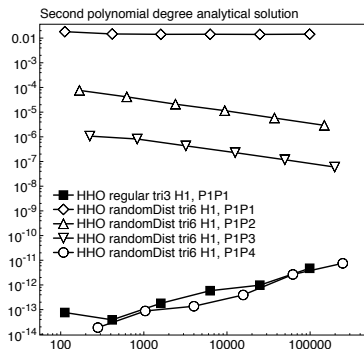
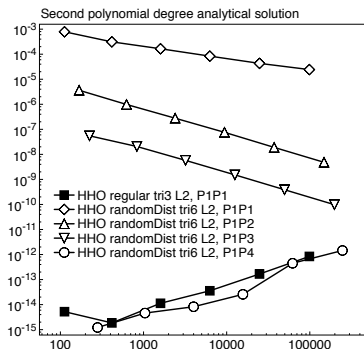
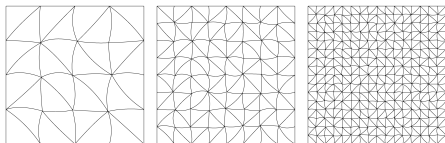


Figure: Error versus number of DOFs for HHO discretizations of the Poisson equation on regular 3-node ($\tilde{m} = 1$) and randomly distorted 6-node triangular grids ($\tilde{m} = 2 \implies l_{\text{opt}} = 2(k + 1)$).

Machine error precision expected and observed for $l = 4$.

Numerical examples

$d = 2$, tri3 and tri6 meshes, cubic solution

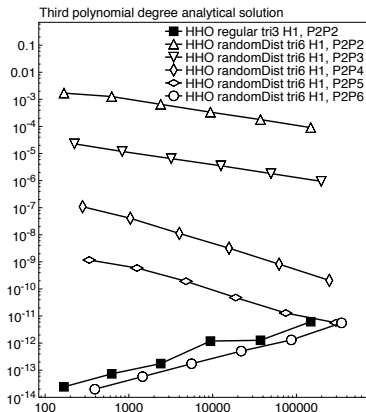
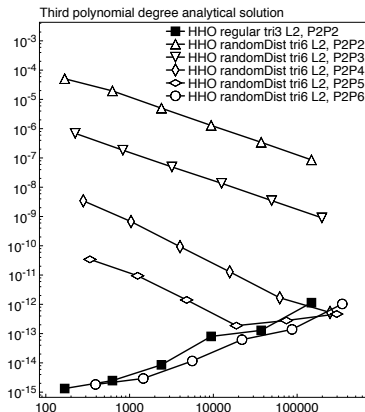


Figure: Error versus number of DOFs for HHO discretizations of the Poisson equation on regular 3-node ($\tilde{m} = 1$) and randomly distorted 6-node triangular grids ($\tilde{m} = 2 \implies l_{\text{opt}} = 2(k + 1)$).

Machine error precision expected and observed for $l = 6$.

Numerical examples

$d = 3$, tri3 and tri6 meshes, quadratic solution

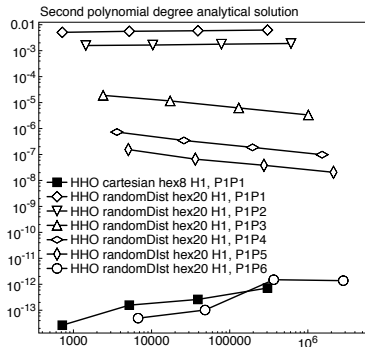
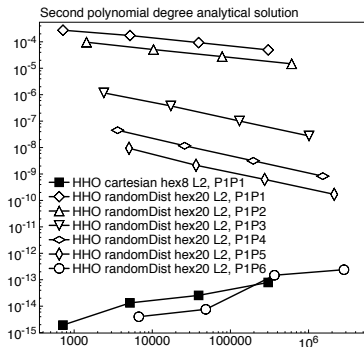
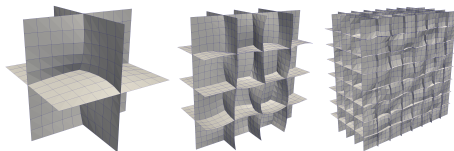


Figure: Error versus number of DOFs for HHO discretizations of the Poisson equation on regular 8-node ($\bar{m} = 1$) and randomly distorted 20-node hexahedral grids ($\bar{m} = 3 \implies l_{\text{opt}} = 3(k + 1)$). Machine error precision expected and observed for $l = 6$.

Thank you for your attention!

- **Wed1425** L. Botti, p -multilevel solution strategies for HHO
- **Wed1450** J. Droniou, HHO methods for the Brinkman model
- **Wed1515** D. Castanon-Quiroz, Pressure-robust HHO methods

References



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