

Structure-preserving spectral elements

Institut d'études scientifiques de Cargèse:
Advanced Numerical Methods for Partial Differential Equations

Organized by
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Outline of these lectures

Spectral element methods are based on **orthogonal polynomials** for the basis functions.

Instead of h -refinement (a finer mesh), spectral methods use **p -enrichment**, i.e. leave the elements unaltered, but **increase the polynomial degree**.

For sufficiently smooth problem, spectral methods display **exponential convergence**.

This short course on mimetic spectral elements consists of 2 lectures:

5 September, Lecture 1: Incidence matrices and dual grids

6 September, Lecture 2: Spectral basis functions and scalar Laplace equations

For more detail: *Mimetic framework on curvilinear quadrilaterals of arbitrary order*,
+<https://arxiv.org/abs/1111.4304>

Just a little game I

- Consider the 2D grid shown on the right.
- Number all the vertices in the mesh
- Number all edges in the mesh
- Number all volumes in the mesh

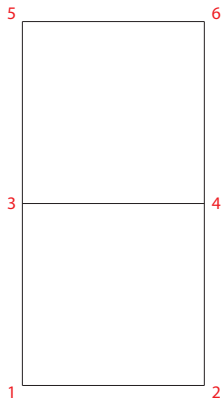
- Give the vertices a default orientation
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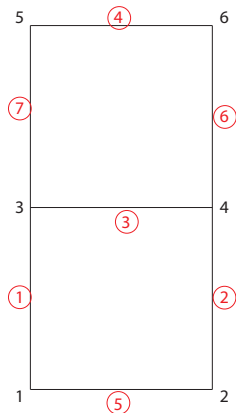
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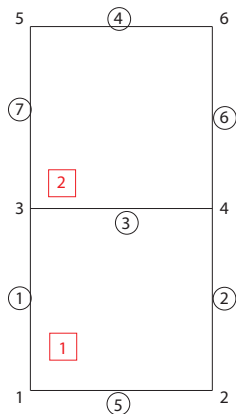
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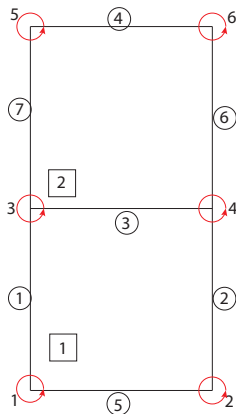
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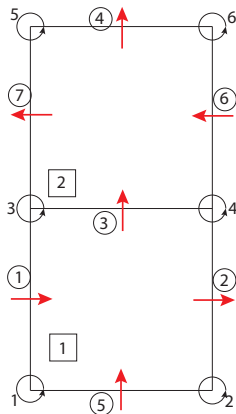
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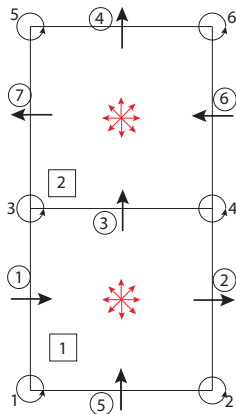
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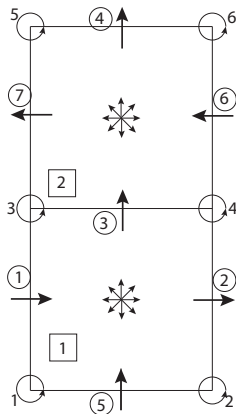
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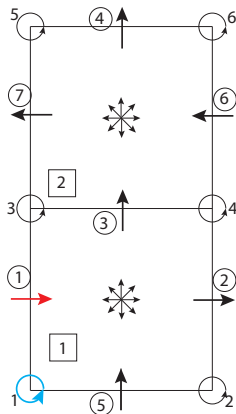
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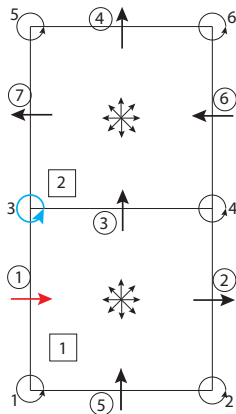
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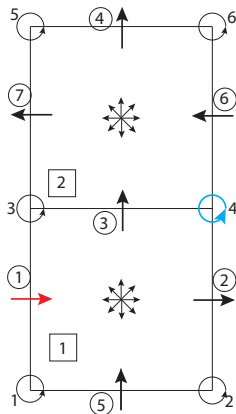
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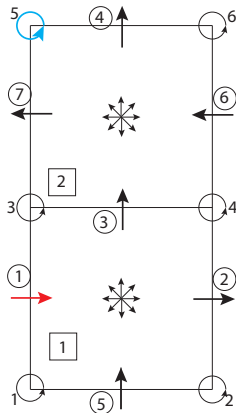
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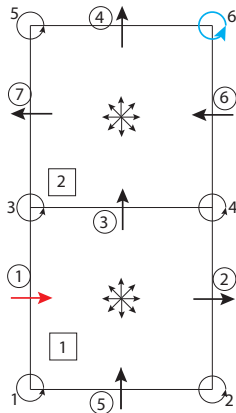
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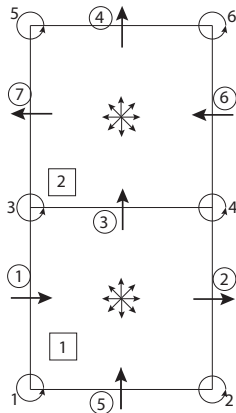
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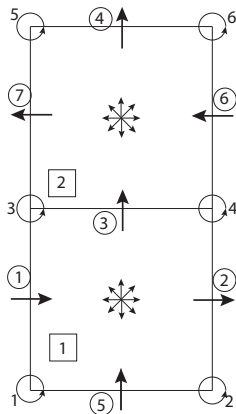
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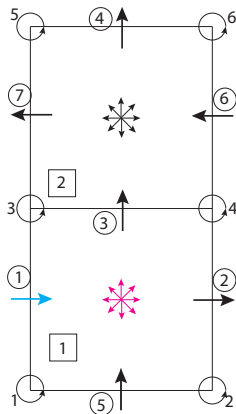
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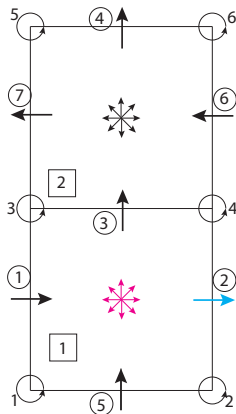
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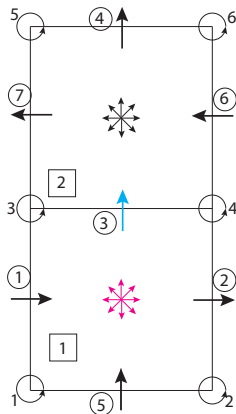
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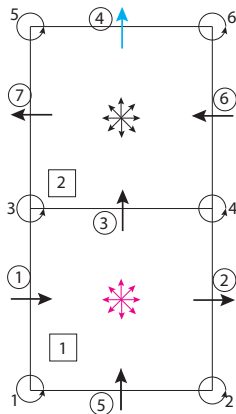
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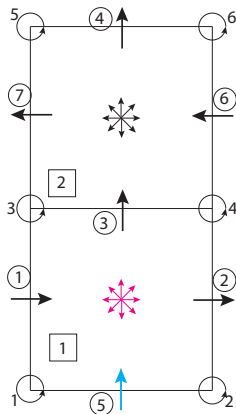
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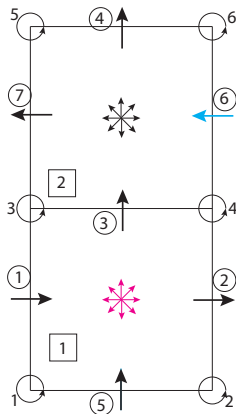
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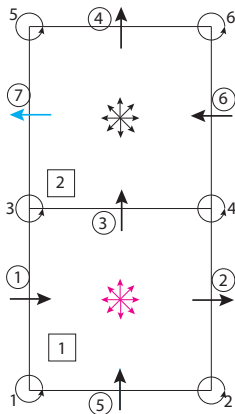
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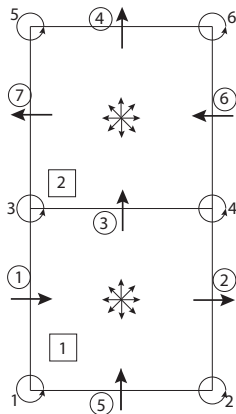
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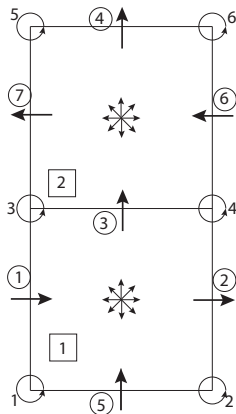


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The matrices $\mathbb{E}^{1,0}$ and $\mathbb{E}^{2,1}$ are called **incidence matrices**. The incidence matrices only contain entries -1 , 0 and 1 .



Just a little game II

$$\mathbb{E}^{2,1} = \begin{pmatrix} -1 & 1 & 1 & 0 & -1 & 0 & 0 \\ 0 & 0 & -1 & 1 & 0 & -1 & 1 \end{pmatrix} \quad \mathbb{E}^{1,0} = \begin{pmatrix} -1 & 0 & 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & -1 \\ 1 & -1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & 0 & -1 & 0 \end{pmatrix}$$

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Exercise: Calculate the product $\mathbb{E}^{2,1} \cdot \mathbb{E}^{1,0}$

AUDIENCE PARTICIPATION

Just a little game II

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Exercise: Calculate the product $\mathbb{E}^{2,1} \cdot \mathbb{E}^{1,0}$

$$\mathbb{E}^{2,1} \cdot \mathbb{E}^{1,0} = \mathbf{0}$$

This implies that $\mathcal{R}(\mathbb{E}^{1,0}) \subseteq \mathcal{N}(\mathbb{E}^{2,1})$
 In this particular case $\mathcal{R}(\mathbb{E}^{1,0}) \equiv \mathcal{N}(\mathbb{E}^{2,1})$.

Just a little game II

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 In this particular case $\mathcal{R}(\mathbb{E}^{1,0}) \equiv \mathcal{N}(\mathbb{E}^{2,1})$.

We also have that $\mathbb{E}^{1,0^T} \cdot \mathbb{E}^{2,1^T} = \mathbf{0} \implies \mathcal{R}(\mathbb{E}^{2,1^T}) \equiv \mathcal{N}(\mathbb{E}^{1,0^T})$

Just a little game III

$$\mathbb{E}^{1,0} = \begin{pmatrix} -1 & 0 & 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & -1 \\ 1 & -1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & 0 & -1 & 0 \end{pmatrix}$$

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Just a little game III

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The property $\mathbb{E}^{2,1} \cdot \mathbb{E}^{1,0} = \mathbf{0}$ also implies that $\mathcal{R}(\mathbb{E}^{1,0}) \perp \mathcal{R}(\mathbb{E}^{2,1T})$

Just a little game III

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Because for arbitrary $\mathbf{a} \in \mathbb{R}^6$ and $\mathbf{b} \in \mathbb{R}^2$ we have

$$(\mathbb{E}^{1,0} \mathbf{a}, \mathbb{E}^{2,1^T} \mathbf{b}) = (\mathbb{E}^{2,1} \cdot \mathbb{E}^{1,0} \mathbf{a}, \mathbf{b}) = 0$$

Just a little game III

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$$\left(\mathbb{E}^{1,0} \mathbf{a}, \mathbb{E}^{2,1^T} \mathbf{b} \right) = \left(\mathbb{E}^{2,1} \cdot \mathbb{E}^{1,0} \mathbf{a}, \mathbf{b} \right) = 0$$

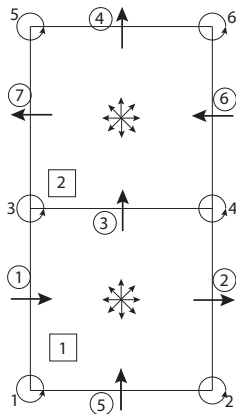
Let $H = \mathcal{N}(\mathbb{E}^{2,1}) / \mathcal{R}(\mathbb{E}^{1,0})$ then any element $\mathbf{x} \in \mathbb{R}^7$ can be uniquely written as

$$\mathbf{x} = \mathbb{E}^{1,0} \mathbf{a} + \mathbb{E}^{2,1^T} \mathbf{b} + \mathbf{c}, \quad \mathbf{a} \in \mathbb{R}^6, \quad \mathbf{b} \in \mathbb{R}^2 \text{ and } \mathbf{c} \in H$$

"Hodge decomposition"

Just a little game IV

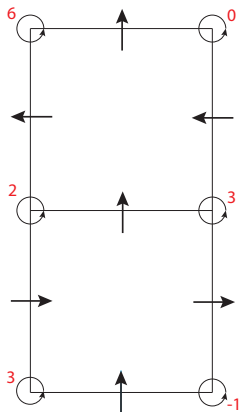
What do the vectors $\mathbf{a} \in \mathbb{R}^6$ actually represent?



Just a little game IV

What do the vectors $\mathbf{a} \in \mathbb{R}^6$ actually represent?

Suppose I assign to the vertices the value $\psi = (3, -1, 2, 3, 6, 0)^T$. Physically this could represent the **stream function** in the points.

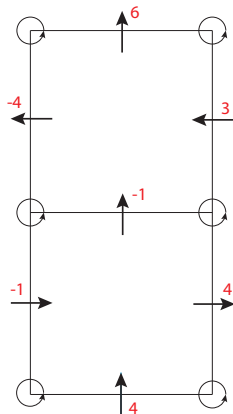


Just a little game IV

What do the vectors $\mathbf{a} \in \mathbb{R}^6$ actually represent?

Suppose I assign to the vertices the value $\psi = (3, -1, 2, 3, 6, 0)^T$. Physically this could represent the **stream function** in the points.

Then $\mathbb{E}^{1,0}\psi = \mathbf{m} = (-1, 4, -1, 6, 4, 3, -4)^T$ denotes the **mass flux** over the edges in the **direction of the default positive orientation**.



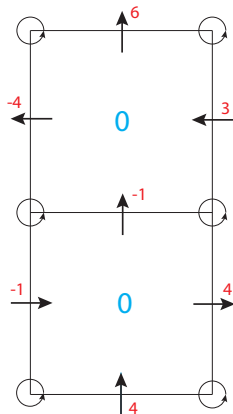
Just a little game IV

What do the vectors $\mathbf{a} \in \mathbb{R}^6$ actually represent?

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Just a little game IV

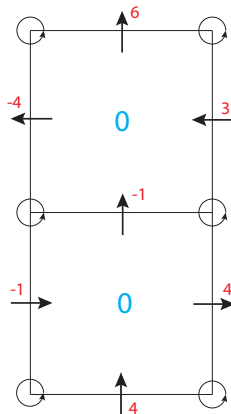
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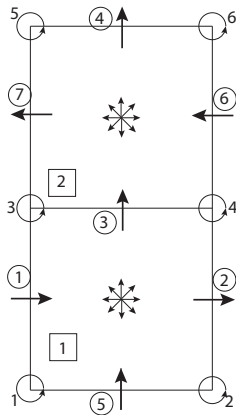
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So \mathbf{a} could represent the **stream function** and $\mathbb{E}^{1,0}\mathbf{a}$ its associated **divergence-free velocity field**.



Just a little game V

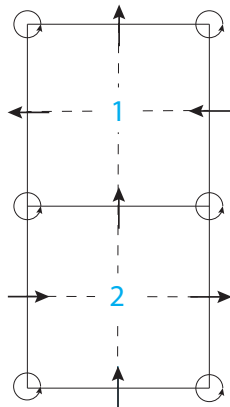
What does the vectors $\mathbf{b} \in \mathbb{R}^2$ then represent?



Just a little game V

What does the vectors $\mathbf{b} \in \mathbb{R}^2$ then represent?

Suppose I assign to the cells the value $\phi = (2, 1)^T$. Physically this could represent the **velocity potential** in the cells.

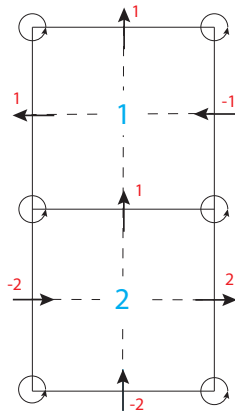


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Suppose I assign to the cells the value $\phi = (2, 1)^T$. Physically this could represent the **velocity potential** in the cells.

Then $\mathbb{E}^{2,1^T} \phi = \dot{\mathbf{u}} = (-2, 2, 1, 1, -2, -1, 1)^T$ denotes the **circulation** along the edges.



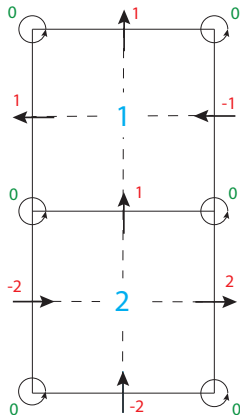
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Just a little game V

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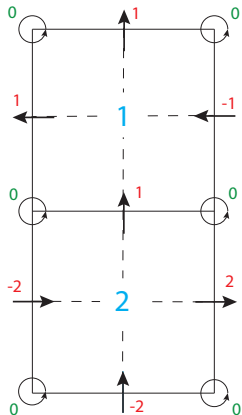
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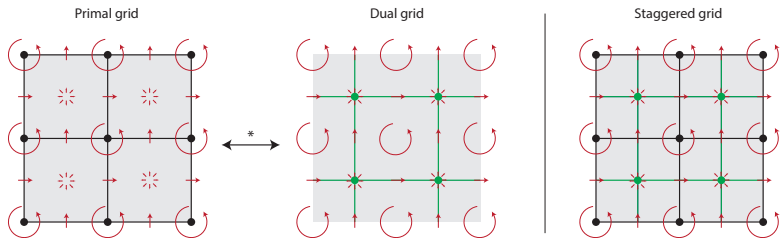
Then $\mathbb{E}^{1,0^T} \dot{\mathbf{u}} = \mathbb{E}^{1,0^T} \mathbb{E}^{2,1^T} \phi = (0, 0, 0, 0, 0, 0)^T$ denotes **vorticity** in the vertices.

So \mathbf{b} could represent the **velocity potential** and $\mathbb{E}^{2,1^T} \mathbf{b}$ its associated **irrotational flow**.

I tacitly drawn dashed lines in the figure. This a dual mesh. The combination of primal and dual grids leads to **staggered schemes**.



Just a little game VI



$$H(\text{curl}; \Omega)$$



$$H(\text{div}; \Omega)$$



$$L^2(\Omega)$$

$$H_0(\text{div}; \Omega)$$

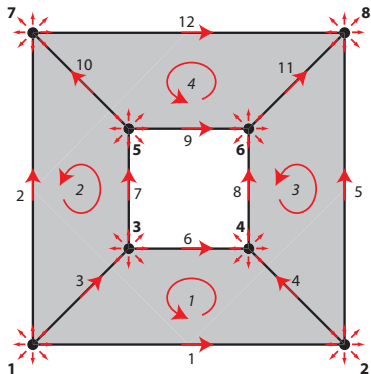


$$H_0(\text{curl}; \Omega)$$



$$H_0^1(\Omega)$$

Just a little game VII



Note that $\mathcal{R}(\mathbb{E}^{1,0}) \subseteq \mathcal{N}(\mathbb{E}^{2,1})$ is always true, but $\mathcal{R}(\mathbb{E}^{1,0}) = \mathcal{N}(\mathbb{E}^{2,1})$ only on **contractible domains**, (Poincaré Lemma). In the above example there is a curl-free flow field which is **not** the gradient of a potential. This is a **harmonic solution** and we need an **additional boundary condition** to fix this harmonic solution (Kutta condition).

Just a little game VIII

We have in 3D

$$\mathbb{R} \longrightarrow H_P \xrightarrow{\mathbb{E}^{1,0}} H_E \xrightarrow{\mathbb{E}^{2,1}} H_S \xrightarrow{\mathbb{E}^{3,2}} H_V \longrightarrow 0$$

Just a little game VIII

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$$0 \longleftarrow H_{\tilde{V}} \xleftarrow{\mathbb{E}^{1,0^T}} H_{\tilde{S}} \xleftarrow{\mathbb{E}^{2,1^T}} H_{\tilde{E}} \xleftarrow{\mathbb{E}^{3,2^T}} H_{\tilde{P}} \longleftarrow \mathbb{R}$$

and on the dual grid

Just a little game VIII

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and on the dual grid **How do we discretize the Poisson/steady diffusion equation?**

Just a little game IX

The physical interpretation can be depicted as

$$\begin{array}{ccccc}
 \psi \in P & \xrightarrow[\nabla^\perp]{\mathbb{E}^{1,0}} & \dot{\mathbf{m}} \in E & \xrightarrow[\nabla \cdot]{\mathbb{E}^{2,1}} & \phi_S, d\dot{\mathbf{m}}/dt \in S \\
 T_{\tilde{S}V} \parallel & & T_{\tilde{E}E} \parallel & & T_{\tilde{V}S} \parallel \\
 \xi \in \tilde{S} & \xleftarrow[\nabla \times]{\mathbb{E}^{1,0^T}} & \mathbf{u} \in \tilde{E} & \xleftarrow[\nabla]{\mathbb{E}^{2,1^T}} & \phi_{\tilde{V}} \in \tilde{V}
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Just a little game IX

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This sequence is called the **double DeRham sequence**

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The particular numerical scheme that we use determines the transformations $T_{\tilde{S}V}$, $T_{\tilde{E}E}$, $T_{\tilde{V}S}$. This is where the **basis functions enter the scene**.

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$$\text{Staggered finite volume: } \dot{\mathbf{m}} = \mathbb{E}^{1,0} \psi + T_{\tilde{E}E}^{-1} \mathbb{E}^{2,1^T} T_{\tilde{V}S} \phi_S$$

Just a little game IX

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$$\text{Finite element methods: } T_{\tilde{E}E} \dot{\mathbf{m}} = T_{\tilde{E}E} \mathbb{E}^{1,0} \psi + \mathbb{E}^{2,1^T} T_{\tilde{V}S} \phi_S$$

One dimensional nodal basis functions

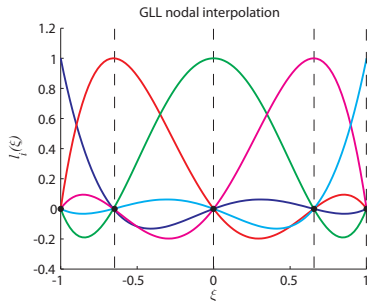
Consider the interval $[-1, 1] \subset \mathbb{R}$ and the partitioning $-1 = \xi_0 < \xi_1 < \dots < \xi_{N-1} < \xi_N = 1$. Let $h_i(\xi)$ be the **Lagrange polynomials** through these nodes

$$h_i(\xi_j) = \begin{cases} 1 & \text{if } i = j \\ 0 & \text{if } i \neq j \end{cases}$$

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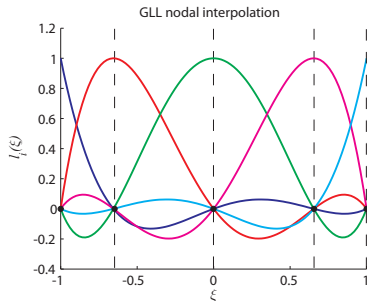
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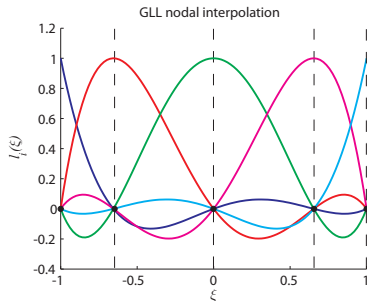


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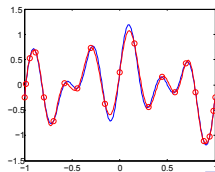
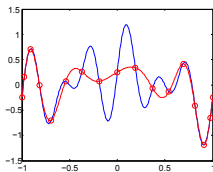
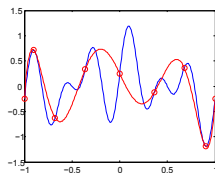
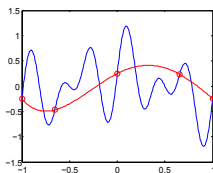


$$f(\xi) = \sum_{i=0}^N a_i h_i(\xi) \implies f(\xi_j) = a_j$$

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One dimensional edge basis functions

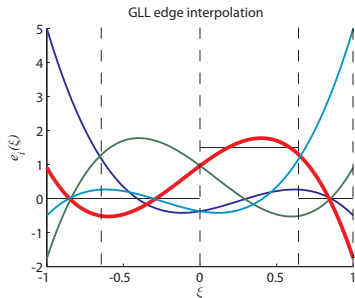
Next consider the **edge polynomials**, $e_i(\xi)$, defined by

$$e_i(\xi) = - \sum_{k=0}^{i-1} \frac{dh_k(\xi)}{d\xi} d\xi = - \sum_{k=0}^{i-1} dh_k(\xi) \quad \int_{\xi_{j-1}}^{\xi_j} e_i(\xi) = \begin{cases} 1 & \text{if } i = j \\ 0 & \text{if } i \neq j \end{cases}$$

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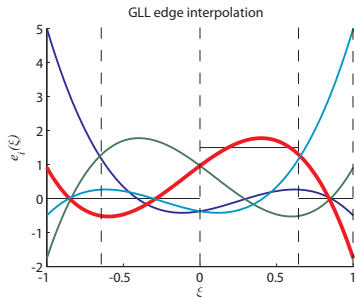
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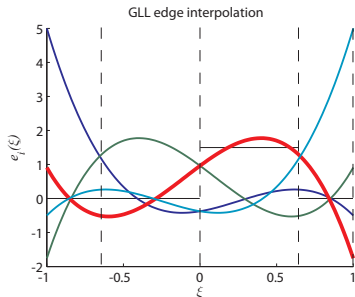


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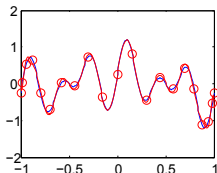
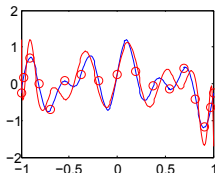
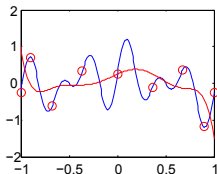
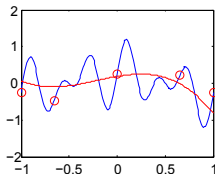


$$f(\xi) = \sum_{i=1}^N b_i e_i(\xi) \implies \int_{\xi_{j-1}}^{\xi_j} f(\xi) d\xi = b_j$$

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Derivative of nodal function

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Two dimensional expansion – nodal

Consider $[-1, 1]^2 \subset \mathbb{R}^2$. We will use tensor products of nodal expansions to construct a finite dimensional subspace.

Consider of the span of $\{h_i(\xi)h_j(\eta)\}$, $i, j = 0, \dots, N$. Any element $\psi^h(\xi, \eta)$ can be written as

$$\psi^h(\xi, \eta) = \sum_{i=0}^N \sum_{j=0}^N \psi_{i,j} h_i(\xi) h_j(\eta) .$$

with $\psi_{i,j} = \psi(\xi_i, \eta_j)$.

Let φ^h in the same space, then the L^2 -inner product is given by

$$\begin{aligned} (\varphi^h, \psi^h) &= \int_{-1}^1 \int_{-1}^1 \varphi^h \psi^h \, d\xi d\eta \\ &= [\varphi_{0,0} \ \dots \ \varphi_{N,N}] \mathbb{M}^{(0)} \begin{bmatrix} \psi_{0,0} \\ \vdots \\ \psi_{N,N} \end{bmatrix} , \end{aligned}$$

where $\mathbb{M}^{(0)}$ is the **nodal mass matrix** given by

$$\mathbb{M}^{(0)} = \int_{-1}^1 \int_{-1}^1 h_i(\xi) h_j(\eta) h_k(\xi) h_l(\eta) \, d\xi d\eta .$$

Two dimensional expansion – edge

If we apply the perpendicular gradient ∇^\perp to this nodal expansion of ψ^h we obtain

$$\begin{aligned} \nabla^\perp \psi^h &= \begin{pmatrix} \sum_{i=0}^N \sum_{j=1}^N (\psi_{i,j} - \psi_{i,j-1}) h_i(\xi) \mathbf{e}_j(\eta) \\ \sum_{i=1}^N \sum_{j=0}^N (\psi_{i-1,j} - \psi_{i,j}) \mathbf{e}_i(\xi) h_j(\eta) \end{pmatrix} \\ &= \begin{bmatrix} h_0(\xi) \mathbf{e}_1(\eta) & \dots & h_N(\xi) \mathbf{e}_N(\eta) & 0 & \dots & 0 \\ 0 & \dots & 0 & \mathbf{e}_1(\xi) h_0(\eta) & \dots & \mathbf{e}_N(\xi) h_N(\eta) \end{bmatrix} \mathbb{E}^{1,0} \begin{bmatrix} \psi_{0,0} \\ \vdots \\ \psi_{N,N} \end{bmatrix} \end{aligned}$$

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If we apply the perpendicular gradient ∇^\perp to this nodal expansion of ψ^h we obtain

$$\begin{aligned} \nabla^\perp \psi^h &= \begin{pmatrix} \sum_{i=0}^N \sum_{j=1}^N (\psi_{i,j} - \psi_{i,j-1}) h_i(\xi) \mathbf{e}_j(\eta) \\ \sum_{i=1}^N \sum_{j=0}^N (\psi_{i-1,j} - \psi_{i,j}) \mathbf{e}_i(\xi) h_j(\eta) \end{pmatrix} \\ &= \begin{bmatrix} h_0(\xi) \mathbf{e}_1(\eta) & \dots & h_N(\xi) \mathbf{e}_N(\eta) & 0 & \dots & 0 \\ 0 & \dots & 0 & \mathbf{e}_1(\xi) h_0(\eta) & \dots & \mathbf{e}_N(\xi) h_N(\eta) \end{bmatrix} \mathbb{E}^{1,0} \begin{bmatrix} \psi_{0,0} \\ \vdots \\ \psi_{N,N} \end{bmatrix} \end{aligned}$$

If \mathbf{v}^h can be expanded as

$$\begin{aligned} \mathbf{v}^h &= \begin{pmatrix} \sum_{i=0}^N \sum_{j=1}^N u_{i,j} h_i(\xi) \mathbf{e}_j(\eta) \\ \sum_{i=1}^N \sum_{j=0}^N v_{i,j} \mathbf{e}_i(\xi) h_j(\eta) \end{pmatrix} \\ &= \begin{bmatrix} h_0(\xi) \mathbf{e}_1(\eta) & \dots & h_N(\xi) \mathbf{e}_N(\eta) & 0 & \dots & 0 \\ 0 & \dots & 0 & \mathbf{e}_1(\xi) h_0(\eta) & \dots & \mathbf{e}_N(\xi) h_N(\eta) \end{bmatrix} \begin{bmatrix} u_{0,1} \\ \vdots \\ u_{N,N} \\ v_{1,0} \\ \vdots \\ v_{N,N} \end{bmatrix} \end{aligned}$$


Two dimensional expansion – edge

If we apply the perpendicular gradient ∇^\perp to this nodal expansion of ψ^h we obtain

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Then the equation $\mathbf{v}^h = \nabla^\perp \psi^h$ implies

$$\mathbb{E}^{1,0} \begin{bmatrix} \psi_{0,0} \\ \vdots \\ \psi_{N,N} \end{bmatrix} = \begin{bmatrix} u_{0,1} \\ \vdots \\ u_{N,N} \\ v_{1,0} \\ \vdots \\ v_{N,N} \end{bmatrix} \quad \leftarrow \quad \text{Same as Slide 6}$$

So we **preserve the discrete structure between stream function and mass fluxes!** This result is **independent of the basis functions, shape and coarseness of the grid!** 

Two dimensional expansion – edge

If we take an arbitrary \mathbf{a}^h expanded as

$$\mathbf{a}^h = \begin{pmatrix} \sum_{k=0}^N \sum_{l=1}^N a_{k,l} h_k(\xi) e_l(\eta) \\ \sum_{k=1}^N \sum_{l=0}^N b_{k,l} e_k(\xi) h_l(\eta) \end{pmatrix},$$

and take the L^2 inner product with $\nabla^\perp \psi^h$ we obtain

$$\begin{aligned} (\mathbf{a}^h, \nabla^\perp \psi^h)_{\mathbf{D}^h} &= \int_{-1}^1 \int_{-1}^1 (\mathbf{a}^h, \nabla^\perp \psi^h) d\xi d\eta \\ &= [a_{0,1} \dots a_{N,N} \ b_{1,0} \dots b_{N,N}] \mathbb{M}^{(1)} \mathbb{E}^{1,0} \begin{bmatrix} \psi_{0,0} \\ \vdots \\ \psi_{N,N} \end{bmatrix} \end{aligned}$$

where the mass matrix $\mathbb{M}^{(1)}$ is given by

$$\mathbb{M}^{(1)} = \begin{pmatrix} \int_{-1}^1 \int_{-1}^1 h_i(\xi) e_j(\eta) h_k(\xi) e_l(\eta) d\xi d\eta & 0 \\ 0 & \int_{-1}^1 \int_{-1}^1 e_p(\xi) h_q(\eta) e_r(\xi) h_s(\eta) d\xi d\eta \end{pmatrix};$$

Two dimensional expansion – surface

Let \mathbf{u}^h be expanded as

$$\mathbf{u}^h = \begin{pmatrix} \sum_{i=0}^N \sum_{j=1}^N u_{i,j} h_i(\xi) \mathbf{e}_j(\eta) \\ \sum_{i=1}^N \sum_{j=0}^N v_{i,j} \mathbf{e}_i(\xi) h_j(\eta) \end{pmatrix}$$

Then $\nabla \cdot \mathbf{u}^h$ is given by

$$\begin{aligned} \nabla \cdot \mathbf{u}^h &= \sum_{i=1}^N \sum_{j=1}^N (u_{i,j} - u_{i-1,j} + v_{i,j} - v_{i,j-1}) \mathbf{e}_i(\xi) \mathbf{e}_j(\eta) \\ &= [\mathbf{e}_1(\xi) \mathbf{e}_1(\eta) \dots \mathbf{e}_N(\xi) \mathbf{e}_N(\eta)] \mathbb{E}^{2,1} \begin{bmatrix} u_{0,1} \\ \vdots \\ u_{N,N} \\ v_{1,0} \\ \vdots \\ v_{N,N} \end{bmatrix}. \end{aligned}$$

Two dimensional expansion – surface

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Since the basis functions $\mathbf{e}_i(\xi) \mathbf{e}_j(\eta)$ are linearly independent, $\nabla \cdot \mathbf{u}^h = 0$ reduces to

$$\mathbb{E}^{2,1} \begin{bmatrix} u_{0,1} \\ \vdots \\ u_{N,N} \\ v_{1,0} \\ \vdots \\ v_{N,N} \end{bmatrix} = 0 \quad \leftarrow \quad \text{Same as Slide 6}$$

Two dimensional expansion – surface

Let q^h can be expanded as

$$q^h(\xi, \eta) = \sum_{k=1}^N \sum_{l=1}^N q_{k,l} \mathbf{e}_k(\xi) \mathbf{e}_l(\eta) .$$

With this expansion we can write $(q^h, \nabla \cdot \mathbf{u}^h)_{S^h}$ as

$$(q^h, \nabla \cdot \mathbf{u}^h)_{S^h} = [q_{1,1} \ \dots \ q_{N,N}] \mathbb{M}^{(2)} \mathbb{E}^{2,1} \begin{bmatrix} u_{0,1} \\ \vdots \\ u_{N,N} \\ v_{1,0} \\ \vdots \\ v_{N,N} \end{bmatrix} ,$$

where $\mathbb{M}^{(2)}$ is the mass matrix on S^h given by

$$\mathbb{M}^{(2)} := \int_{-1}^1 \int_{-1}^1 \mathbf{e}_i(\xi) \mathbf{e}_j(\eta) \mathbf{e}_k(\xi) \mathbf{e}_l(\eta) \, d\xi d\eta$$

Two dimensional Hodge decomposition

With these basis functions we can write for the **Hodge decomposition** of the velocity field $\mathbf{u}^h \in H_0(\text{div})$

$$\mathbf{u}^h = \nabla^\perp \psi^h + \nabla \phi^h$$

Multiplying with any finite dimensional $\mathbf{v}^h \in H_0(\text{div})$ and integrating over the domain gives

$$\begin{aligned} (\mathbf{v}^h, \mathbf{u}^h) &= (\mathbf{v}^h, \nabla^\perp \psi^h) + (\mathbf{v}^h, \nabla \phi^h) \\ &= (\mathbf{v}^h, \nabla^\perp \psi^h) + (-\nabla \cdot \mathbf{v}^h, \phi^h) \end{aligned}$$

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$$\vec{v}^T \mathbb{M}^{(1)} \vec{u} = \vec{v}^T \mathbb{M}^{(1)} \mathbb{E}^{1,0} \vec{\psi} + \vec{v}^T \mathbb{E}^{2,1} \mathbb{M}^{(2)} \vec{\phi}$$

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$$\vec{u} = \mathbb{E}^{1,0} \vec{\psi} + \mathbb{M}^{(1)-1} \mathbb{E}^{2,1 T} \mathbb{M}^{(2)} \vec{\phi}$$

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$$\|\mathbf{u}^h\|_0^2 = \vec{u}^T \mathbb{M}^{(1)} \vec{u} = \vec{\psi}^T \underbrace{\mathbb{E}^{1,0} \mathbb{M}^{(1)} \mathbb{E}^{1,0}}_{-\Delta} \vec{\psi} + \vec{\phi}^T \underbrace{\mathbb{M}^{(2)} \mathbb{E}^{2,1} \mathbb{M}^{(1)-1} \mathbb{E}^{2,1} \mathbb{M}^{(2)}}_{-\Delta} \vec{\phi}$$

Nodal Laplace problem

Consider the scalar Laplace problem for $\psi \in H_0^1(\Omega)$ with $\Omega = [-1, 1]^2$

$$-\Delta\psi = f \quad \text{in } \Omega$$

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Multiply this equation with any $\tilde{\psi} \in H_0^1(\Omega)$ and integrate over the domain Ω

$$\int_{\Omega} -\Delta\psi \tilde{\psi} \, d\Omega = \int_{\Omega} (\nabla\psi, \nabla\tilde{\psi}) \, d\Omega = \int_{\Omega} f \tilde{\psi} \, d\Omega$$

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If we restrict ourselves to the conforming subspace spanned by the nodal functions

$$\psi^h = \sum_{i=0}^N \sum_{j=0}^N \psi_{i,j} h_i(\xi) h_j(\eta)$$

we obtain the discrete Laplace equation

$$\mathbb{E}^{1,0T} \mathbb{M}^{(1)} \mathbb{E}^{1,0} \vec{\psi} = \mathbb{M}^{(0)} \vec{f}$$

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Note that the discrete Laplacian only consists of a **mass matrix** and **incidence matrix**.

Volumetric Laplace problem I

Consider the scalar Laplace problem for $\phi \in L^2(\Omega)$ with $\Omega = [-1, 1]^2$

$$-\Delta\phi = f \quad \text{in } \Omega$$

with $\partial\phi/\partial n = 0$

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If we ϕ^h in terms of edge functions, like

$$\phi^h = \sum_{i=1}^N \sum_{j=1}^N \phi_{i,j} \mathbf{e}_i(\xi) \mathbf{e}_j(\eta)$$

Now the derivative of an edge function $\mathbf{e}_i(\xi)$ does not exist. We therefore have to go to the **mixed formulation**

$$\begin{cases} \mathbf{u} - \nabla\phi & = & \mathbf{0} \\ \nabla \cdot \mathbf{u} & & f \end{cases}$$

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$$\begin{cases} \mathbf{u} - \nabla\phi = 0 \\ \nabla \cdot \mathbf{u} = f \end{cases}$$

If we multiply the first equation by $\mathbf{v} \in H_0(\text{div}; \Omega)$ and the second equation by $q \in L^2(\Omega)$, we obtain

$$\begin{aligned} (\mathbf{v}, \mathbf{u}) - (\mathbf{v}, \nabla\phi) &= 0 \\ (q, \nabla \cdot \mathbf{u}) &= (q, f) \end{aligned}$$

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$$\begin{pmatrix} (\mathbf{v}, \mathbf{u}) \\ (q, \nabla \cdot \mathbf{u}) \end{pmatrix} + \begin{pmatrix} (\nabla \cdot \mathbf{v}, \phi) \\ (q, f) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

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$$\begin{aligned} (\mathbf{v}, \mathbf{u}) + (\nabla \cdot \mathbf{v}, \phi) &= 0 \\ (q, \nabla \cdot \mathbf{u}) &= (q, f) \end{aligned}$$

Inserting our expansions gives

$$\begin{aligned} \mathbb{M}^{(1)} \vec{u} + \mathbb{E}^{2,1T} \mathbb{M}^{(2)} \vec{\phi} &= 0 \\ \mathbb{M}^{(2)} \mathbb{E}^{2,1} \vec{u} &= \mathbb{M}^{(2)} \vec{f} \end{aligned}$$

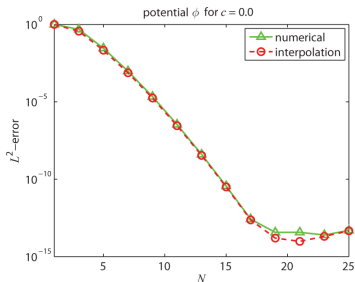
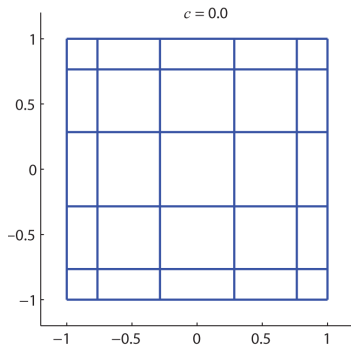
Volumetric Laplace problem II

$$\begin{array}{ccc} \mathbb{M}^{(1)}\vec{u} & + & \mathbb{E}^{2,1T}\mathbb{M}^{(2)}\vec{\phi} = \mathbf{0} \\ \mathbb{M}^{(2)}\mathbb{E}^{2,1}\vec{u} & & \mathbb{M}^{(2)}\vec{f} \end{array}$$

If we eliminate \mathbf{u} again, we obtain

$$\mathbb{M}^{(2)}\mathbb{E}^{2,1}\mathbb{M}^{(1)-1}\mathbb{E}^{2,1T}\mathbb{M}^{(2)}\vec{\phi} = \mathbb{M}^{(2)}\vec{f}$$

Again, this system matrix only consists of **mass matrices** and an **incidence matrix**.



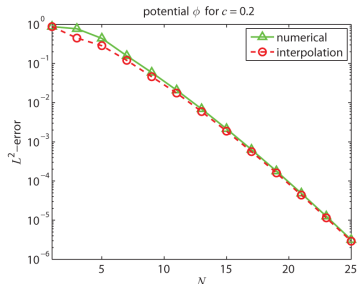
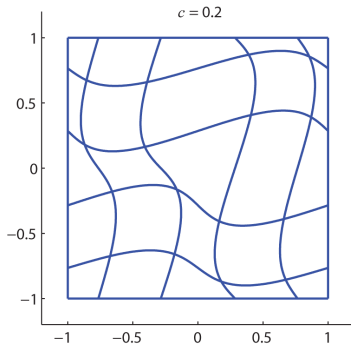
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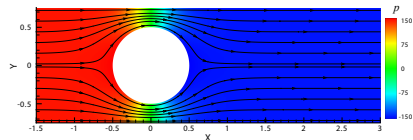
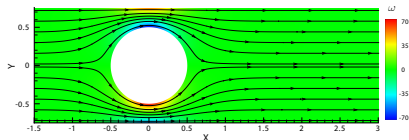
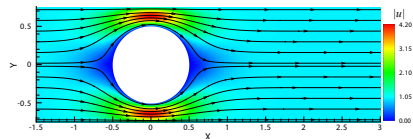
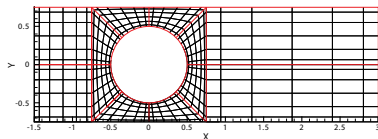
Stokes

$$\left\{ \begin{array}{ll} \nabla \times \mathbf{u} - \omega = 0 & \text{in } \Omega \\ \nabla \times \omega + \nabla p = \mathbf{f} & \text{in } \Omega \\ \nabla \cdot \mathbf{u} = 0 & \text{in } \Omega \end{array} \right. ,$$

Using the same approach, we can discretize this as

$$\begin{pmatrix} \mathbf{M}^{(0)} & \mathbf{E}^{1,0T} \mathbf{M}^{(1)} & \mathbf{0} \\ \mathbf{M}^{(1)} \mathbf{E}^{1,0} & \mathbf{0} & \mathbf{E}^{2,1T} \mathbf{M}^{(2)} \\ \mathbf{0} & \mathbf{M}^{(2)} \mathbf{E}^{2,1} & \mathbf{0} \end{pmatrix} \begin{pmatrix} \tilde{\omega} \\ \tilde{\mathbf{u}} \\ \tilde{p} \end{pmatrix} = \begin{pmatrix} \mathbf{0} \\ \mathbf{M}^{(1)} \tilde{\mathbf{f}} \\ \mathbf{0} \end{pmatrix}$$

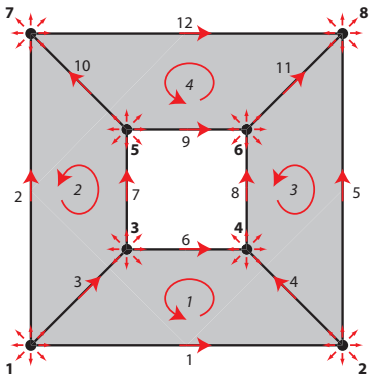
Stokes flow around cylinder



[Jasper Kreeft, JCP 2014]

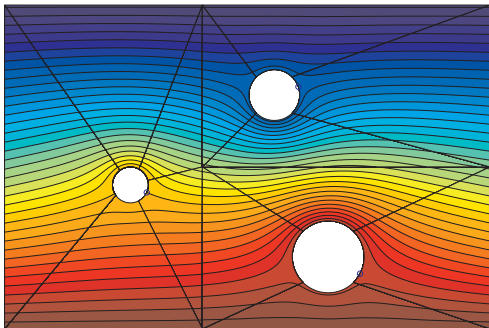
Domain with holes I

If we have **holes** in the domain, there exist vectors in the null space of $\mathbb{E}^{2,1}$ which is not in the range of $\mathbb{E}^{1,0}$



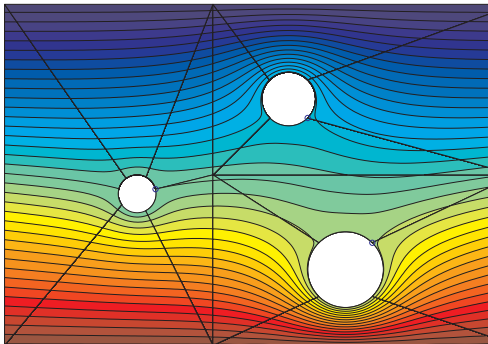
Domain with holes II

Application: Potential flow around 3 cylinders (Isogeometric)



Domain with holes II

Application: Potential flow around 3 cylinders (Isogeometric)



Final Remarks

- Further reading: Consult papers of this week's speakers!
- Do it yourself!
- See work by: Mikhail Shashkov, Enzo Tonti, Alain Bossavit, Matthieu Desbrun (DEC), Arnold, Falk & Winther (FEEC), Jerome Bonelle, Pierre Cantin & Alexandre Ern (CO schemes), Franco Brezzi, Stanly Steinberg, Mac Hyman & Pavel Bochev
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Thank you for your attention and enjoy the remainder of the summer school.