Theory of matroids and applications : I

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A matroid *M* is an ordered pair (E, \mathcal{I}) where *E* is a finite set $(E = \{1, ..., n\})$ and \mathcal{I} is a family of subsets of *E* verifying the following conditions :

- $(I1) \ \emptyset \in \mathcal{I},$
- (12) If $I \in \mathcal{I}$ and $I' \subset I$ then $I' \in \mathcal{I}$,
- (13) If $I_1, I_2 \in \mathcal{I}$ and $|I_1| < |I_2|$ then there exists $e \in I_2 \setminus I_1$ such that $I_1 \cup e \in \mathcal{I}$.

The members in \mathcal{I} are called the independents of M. A subset in E not belonging to \mathcal{I} is called dependent.

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 $|I_2| \le dim(W) \le |I_1| < |I_2|$!!!

Let A be the following matrix with coefficients in \mathbb{R} .

$$A = \begin{pmatrix} 1 & 2 & 3 & 4 & 5 \\ 1 & 0 & 0 & 1 & 1 \\ 0 & 1 & 0 & 0 & 1 \end{pmatrix}$$

 $\{\emptyset, \{1\}, \{2\}, \{4\}, \{4\}, \{5\}, \{1,2\}, \{1,5\}, \{2,4\}, \{2,5\}, \{4,5\}\} \subseteq \mathcal{I}(M)$

A matroid obtained form a matrix A with coefficients in \mathbb{F} is denoted by M(A) and is called representable over \mathbb{F} or \mathbb{F} -representable.

Circuits

A subset $X \subseteq E$ is said to be minimal dependent if any proper subset of X is independent. A minimal dependent set of matroid M is called circuit of M. We denote by C the set of circuits of a matroid.

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- A subset $X \subseteq E$ is said to be minimal dependent if any proper subset of X is independent. A minimal dependent set of matroid M is called circuit of M.
- We denote by C the set of circuits of a matroid.
- ${\cal C}$ is the set of circuits of a matrid on E if and only if ${\cal C}$ verifies the following properties :
- (C1) $\emptyset \notin C$,
- (C2) $C_1, C_2 \in \mathcal{C}$ and $C_1 \subseteq C_2$ then $C_1 = C_2$,
- (C3) (elimination property) If $C_1, C_2 \in C, C_1 \neq C_2$ and $e \in C_1 \cap C_2$ then there exists $C_3 \in C$ such that $C_3 \subseteq \{C_1 \cup C_2\} \setminus \{e\}$.

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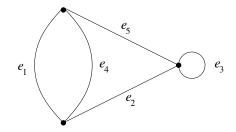
Proof : Verify (C1), (C2) and (C3).

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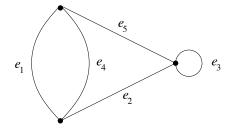
Proof : Verify (C1), (C2) and (C3).

A subset of edges $I \subset \{e_1, \ldots, e_n\}$ of G is independent if the graph induced by I does not contain a cycle.



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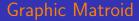
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It can be checked that M(G) is isomorphic to M(A) (under the bijection $e_i \rightarrow i$).

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Theorem A graphic matroid is always representable over \mathbb{R} .

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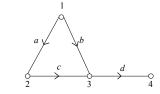
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Proof (idea) Let G = (V, E) be an oriented graph and let $\{x_i, i \in V\}$ be the canonical base of $\mathbb{R}^{|V|}$.

Exercice : Verify that the graph G = (V, E) gives the same matroid that the one given by the set of vectors $y_e = x_i - x_j$ where $e = (i, j) \in E$.

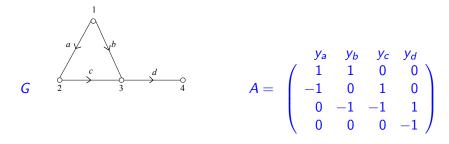


 $A = \begin{pmatrix} y_a & y_b & y_c & y_d \\ 1 & 1 & 0 & 0 \\ -1 & 0 & 1 & 0 \\ 0 & -1 & -1 & 1 \\ 0 & 0 & 0 & -1 \end{pmatrix}$

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G

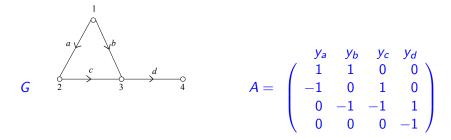
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M(G) is isomorphic to M(A) $(a \rightarrow y_a, b \rightarrow y_b, c \rightarrow y_c, d \rightarrow y_d)$.

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M(G) is isomorphic to M(A) $(a \rightarrow y_a, b \rightarrow y_b, c \rightarrow y_c, d \rightarrow y_d)$. The cycle formed by the edges $a = \{1, 2\}, b = \{1, 3\}$ et $c = \{2, 3\}$ in the graph correspond to the linear dependency $y_b - y_a = y_c$.

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If \mathcal{I} is the family of subsets contained in a set of \mathcal{B} then $(\mathcal{E}, \mathcal{I})$ is a matroid.



Proof of (B2) : Let B_1, B_2 two bases. Then $B_1 \setminus x \in \mathcal{I}$ with $|B_1 \setminus x| < |B_2|$.

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Theorem \mathcal{B} is the set of basis of a matroid if and only if it verifies (*B*1) and (*B*2).

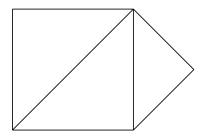
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Bases

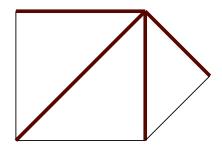
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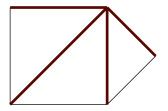
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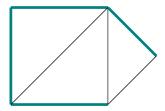




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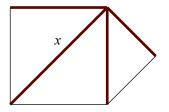


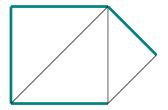




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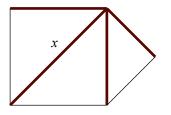


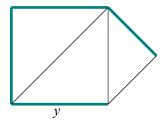




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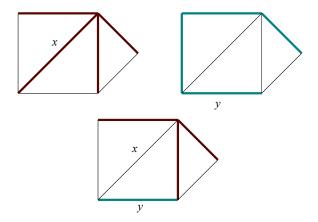






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Rank

The rank of a set $X \subseteq E$ is defined by

 $r_M(X) = \max\{|Y| : Y \subseteq X, Y \in \mathcal{I}\}.$

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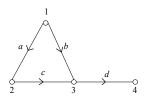
$$r_{\mathcal{M}}(X) = \max\{|Y| : Y \subseteq X, Y \in \mathcal{I}\}.$$

 $r = r_M$ is the rank function of a matroid (E, \mathcal{I}) (where $\mathcal{I} = \{I \subseteq E : r(I) = |I|\}$) if and only if r verifies the following conditions :

$$\begin{array}{ll} (R1) & 0 \leq r(X) \leq |X|, \text{ for all } X \subseteq E, \\ (R2) & r(X) \leq r(Y), \text{ for all } X \subseteq Y, \\ (R3) & (\textit{sub-modulairity}) \ r(X \cup Y) + r(X \cap Y) \leq r(X) + r(Y) \text{ for all } \\ & X, Y \subset E. \end{array}$$



Let M be a graphic matroid obtained from G

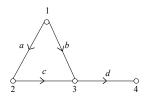


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Rank

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It can be verified that : $r_M(\{a, b, c\}) = r_M(\{c, d\}) = r_M(\{a, d\}) = 2$ et $r(M(G)) = r_M(\{a, b, c, d\}) = 3$.

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Greedy Algorithm

Let \mathcal{I} be a set of subsets of E verifying (11) and (12). Let $w: E \to \mathbb{R}$, and let $w(X) = \sum_{x \in X} w(x), X \subseteq E, w(\emptyset) = 0$.

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Greedy Algorithm

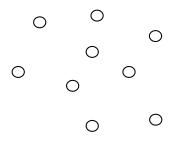
Let \mathcal{I} be a set of subsets of E verifying (11) and (12). Let $w : E \to \mathbb{R}$, and let $w(X) = \sum_{x \in X} w(x), X \subseteq E, w(\emptyset) = 0$. An optimization problem consist of finding a maximal set B of \mathcal{I} with maximal weight (or minimal).

> Greedy algorithm for (\mathcal{I}, w) $X_0 = \emptyset$ j = 0 **While** $e \in E \setminus X_j : X_j \cup \{e\} \in \mathcal{I}$ **do** Choose an element e_{j+1} of maximal weight $X_{j+1} \leftarrow X_j \cup \{e_{j+1}\}$ $j \leftarrow j + 1$ $B_G \leftarrow X_j$ Return B_G

Theorem (\mathcal{I}, E) is a matroid if and only if the following conditions are verified :

- (11) $\emptyset \in \mathcal{I}$,
- $(I2) \ I \in \mathcal{I}, I' \subseteq I \Rightarrow I' \in \mathcal{I},$
- (G) For any function $w : E \to \mathbb{R}$, the greedy algorithm gives a maximal set of \mathcal{I} of maximal weight.

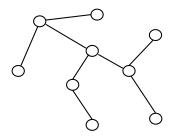
We want to construct a network (of minimal cost) connecting the 9 cities.



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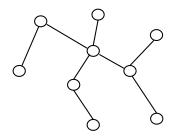
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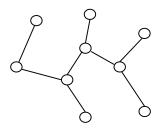
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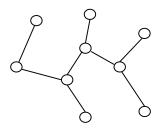
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Theorem (Caley) There exist n^{n-2} labeled trees on *n* vertices.

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Theorem (Kruskal) Given a complete graph with weights on the edges there exist a polynomial time algorithm that finds a spanning tree of minimal weight.

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Indeed, the greedy algorithm returns a base (maximal independent) of minimal weight by considering the graphic matroid associated to a complete graph and w(e), $e \in E(G)$ is the the weight of each edge.

Let $S = \{e_1, \ldots, e_n\}$ and let $\mathcal{A} = \{A_1, \ldots, A_k\}, A_i \subseteq S, n \geq k$.

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Let $S = \{e_1, \ldots, e_n\}$ and let $\mathcal{A} = \{A_1, \ldots, A_k\}, A_i \subseteq S, n \ge k$. A transversal of \mathcal{A} is a subset $\{e_{j_1}, \ldots, e_{j_k}\}$ of S such that $e_{j_i} \in A_i$.

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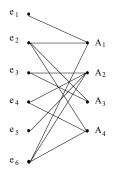
Let G = (S, A; E) be a bipartite graph constructed from $S = \{e_1, \ldots, e_n\}$ and $A = \{A_1, \ldots, A_k\}$ and two vertices $e_i \in S$, $A_i \in A$ are adjacent if and only if $e_i \in A_i$.

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$$E = \{e_1, \dots, e_6\} \text{ et } \mathcal{A} = \{A_1, A_2, A_3, A_4\} \text{ with } A_1 = \{e_1, e_2, e_6\}, A_2 = \{e_3, e_4, e_5, e_6\}, A_3 = \{e_2, e_3\} \text{ and } A_4 = \{e_2, e_4, e_6\}.$$

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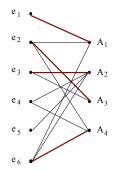
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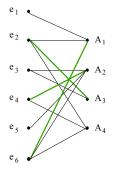
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$$\{e_1, e_3, e_2, e_6\}$$
 is a transversal of \mathcal{A} .

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$$E = \{e_1, \dots, e_6\} \text{ et } \mathcal{A} = \{A_1, A_2, A_3, A_4\} \text{ with } A_1 = \{e_1, e_2, e_6\}, \\ A_2 = \{e_3, e_4, e_5, e_6\}, A_3 = \{e_2, e_3\} \text{ et } A_4 = \{e_2, e_4, e_6\}.$$



 $X = \{e_6, e_4, e_2\}$ is a partial transversal of \mathcal{A} since X is a transversal of $\{A_1, A_2, A_3\}$.

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Theorem Let $S = \{e_1, \ldots, e_n\}$ and $\mathcal{A} = \{A_1, \ldots, A_k\}, A_i \subseteq S$. Then, the set of partial transversals of \mathcal{A} is the set of independents of a matroid.

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Proof Exercise.

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Theorem Let $S = \{e_1, \ldots, e_n\}$ and $\mathcal{A} = \{A_1, \ldots, A_k\}, A_i \subseteq S$. Then, the set of partial transversals of \mathcal{A} is the set of independents of a matroid.

Proof Exercise.

Such matroid is called transversal matroid.

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- The tasks are all done at the same time (and thus each agent can perform one task at the time).
- Problem : Assign the tasks to the agents in an optimal way (maximizing the priorities).

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- priorities : $w(t_1) = 10, w(t_2) = 3, w(t_3) = 3$ et $w(t_4) = 5$.

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- Transversal Matroid $M = (\mathcal{I}, \{t_1, t_2, t_3, t_4\})$ where \mathcal{I} is given by the set of matchings of the bipartite graph G = (U, V; E) with $U = \{t_1, t_2, t_3, t_4\}, V = \{e_1, e_2, e_3\}.$

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- By applying the greedy algorithm to M we have $X_0 = \emptyset, X_1 = \{t_1\}, X_2 = \{t_1, t_4\}$ and $X_3 = \{t_1, t_4, t_2\}.$