

Intensity estimation for spatial point processes observed with noise

Lionel Cucala

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Outline

- Perturbed point processes.
- The deconvolution method.
- An asymptotic study.
- The bandwidth selection procedure.
- A simulation study.

Perturbed point processes

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- Goal: estimate $\lambda_Y(s)$ for every point $s \in D$.

Kernel intensity estimator

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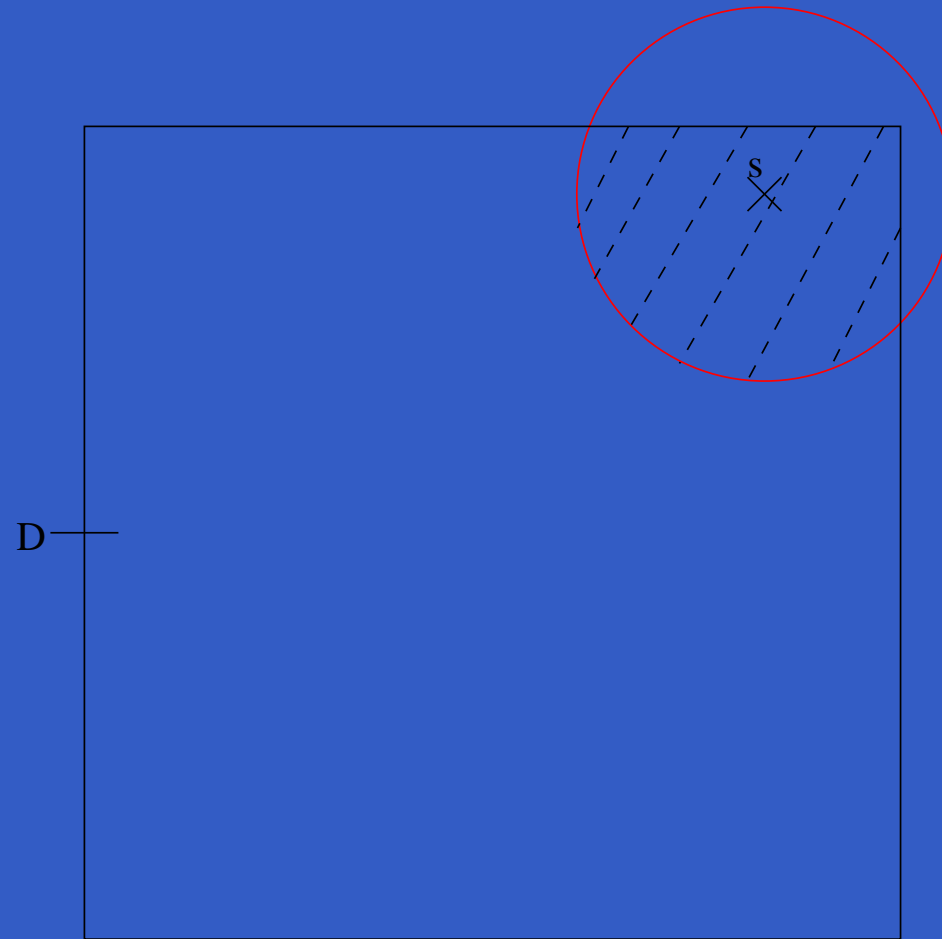
$$\begin{aligned}\forall s \in \mathbb{R}^2, \hat{\lambda}_{Z,h}(s) &= \frac{\sum_{j=1}^n \frac{1}{h^2} K\left(\frac{s-z_j}{h}\right)}{\int_D \frac{1}{h^2} K\left(\frac{s-u}{h}\right) \nu(du)} \\ &= \frac{\sum_{j=1}^n \frac{1}{h^2} K\left(\frac{s-z_j}{h}\right)}{p_h(s)}\end{aligned}$$

Kernel intensity estimator

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$$z_i = y_i + \epsilon_i, \quad i = 1, \dots, n$$

$$\Rightarrow \lambda_Z = \lambda_Y * g$$

$$\Rightarrow \mathcal{F}(\lambda_Z)(\cdot) = \mathcal{F}(\lambda_Y)(\cdot) \mathcal{F}(g)(\cdot)$$

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Deconvolution kernel estimators

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- No edge-correction:

Deconvolution kernel estimators

- No edge-correction:

$$\begin{aligned}\lambda_{Y,h}^*(s) &= \sum_{j=1}^n \frac{1}{(2\pi)^2} \int_{\mathbb{R}^2} e^{is't} \left\{ \int_{\mathbb{R}^2} e^{-it'z} \frac{1}{h^2} K\left(\frac{z - z_j}{h}\right) \right. \\ &\quad \left. \nu(dz) / \mathcal{F}(g)(t) \right\} \nu(dt) \\ &= \sum_{j=1}^n \frac{1}{h^2} K_h^*\left(\frac{s - z_j}{h}\right),\end{aligned}$$

where $K_h^*(t) = \frac{1}{(2\pi)^2} \int_{\mathbb{R}^2} e^{it'y} \mathcal{F}(K)(y) / \mathcal{F}(g)(y/h) dy$.

Deconvolution kernel estimators

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Deconvolution kernel estimators

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Deconvolution kernel estimators

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$$\lambda_{Y,h}^{**}(s) = \frac{\lambda_{Y,h}^*(s)}{p_h^*(s)}.$$

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- reduces to Diggle estimator when no measurement error.

The bandwidth selection

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Adaptation of the gaussian reference rule to the bidimensional noisy case.

A band-limited kernel

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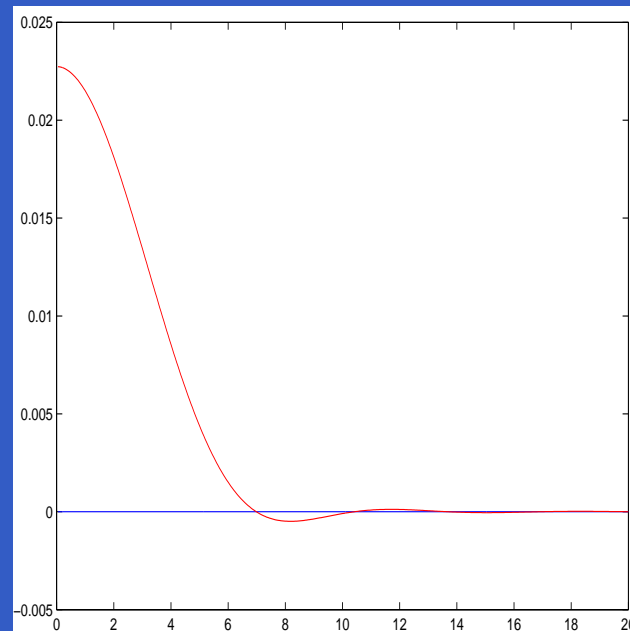


Figure 3: Profile of the kernel K_0

The Fourier transforms

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- $\mathcal{F}(g)$ usually explicit.
- Inverse Fourier transforms obtained by a numerical Simpson procedure

A simulation study

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- $\{y_i, i = 1, \dots, n\}$ from an inhomogeneous P.P with intensity

$$\lambda_Y(s) = C \left[1 + 0.7 \cos \left(2\pi (\|s\| - 0.5) \right) \right].$$

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$$ISE^{**} = \int_{[0,1]^2} \left(\lambda_{Y, h^*}^{**}(s) - \lambda_Y(s) \right)^2 \nu(ds).$$

A simulation study

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Table 3: Gaussian error, $\sigma=0.02$

	<i>ISE</i>	<i>ISE*</i>	<i>ISE**</i>
1st quartile ($\times 10^3$)	1.0600	1.6745	0.9038
median ($\times 10^3$)	1.3939	1.9613	1.0279
3rd quartile ($\times 10^3$)	1.5899	2.2432	1.3158

A simulation study

Table 5: Gaussian error, $\sigma=0.02$

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Table 6: Gaussian error, $\sigma=0.05$

	<i>ISE</i>	<i>ISE*</i>	<i>ISE**</i>
1st quartile ($\times 10^3$)	0.8185	1.4153	0.6655
median ($\times 10^3$)	1.2474	1.7199	0.9298
3rd quartile ($\times 10^3$)	1.5281	1.8908	1.2138

A simulation study

A simulation study

Table 9: Laplace error, $\sigma=0.02$

	<i>ISE</i>	<i>ISE</i> *	<i>ISE</i> **
1st quartile ($*10^3$)	1.0444	1.4676	0.8274
median ($*10^3$)	1.4129	1.7275	1.0025
3rd quartile ($*10^3$)	2.1357	1.9753	1.2334

A simulation study

Table 11: Laplace error, $\sigma=0.02$

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Table 12: Laplace error, $\sigma=0.05$

	<i>ISE</i>	<i>ISE*</i>	<i>ISE**</i>
1st quartile ($\cdot 10^3$)	0.7869	1.1814	0.7689
median ($\cdot 10^3$)	1.4859	1.4223	1.1308
3rd quartile ($\cdot 10^3$)	2.0375	1.5114	1.4210

A simulation study

A simulation study

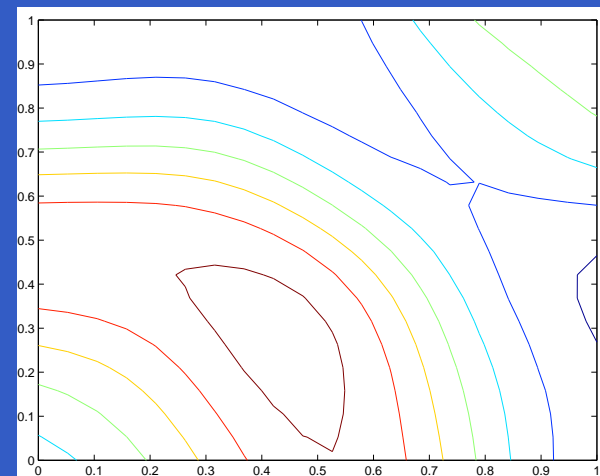
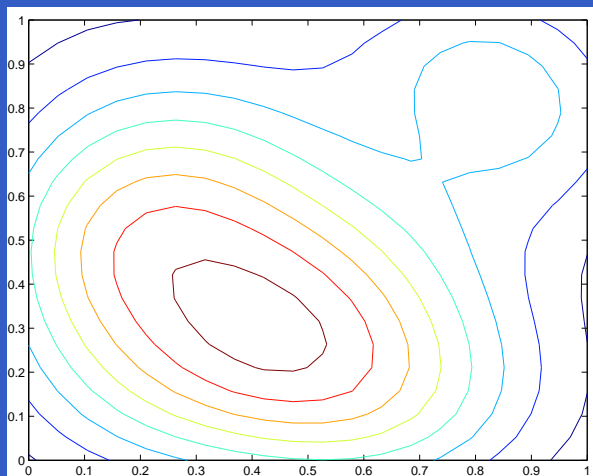
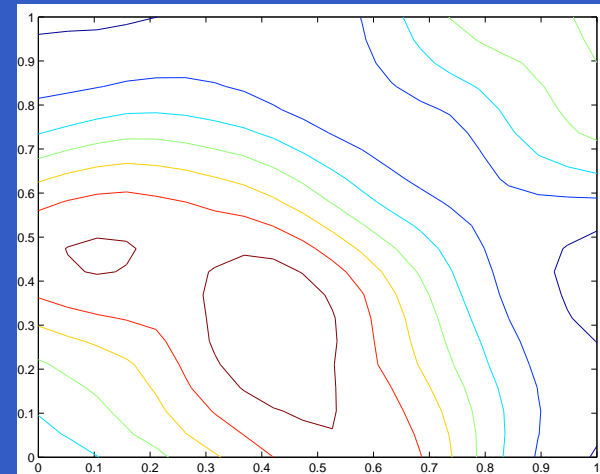
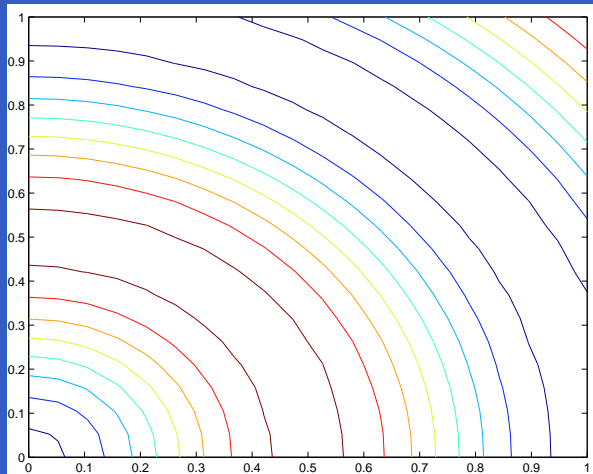


Figure 3 : Up-left figure: Contours of λ_Y . Up-right figure: Contours of $\hat{\lambda}_{Z, h_{opt}}$. Down-left figure: Contours of λ_{Y, h^*}^* . Down-right figure: Contours of λ_{Y, h^*}^{**} .