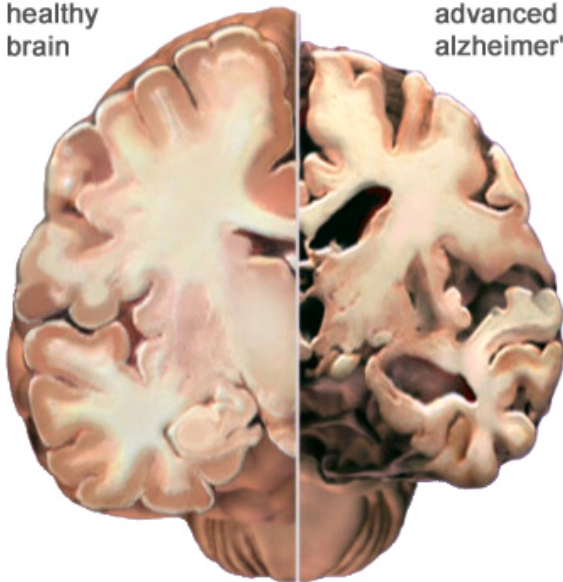


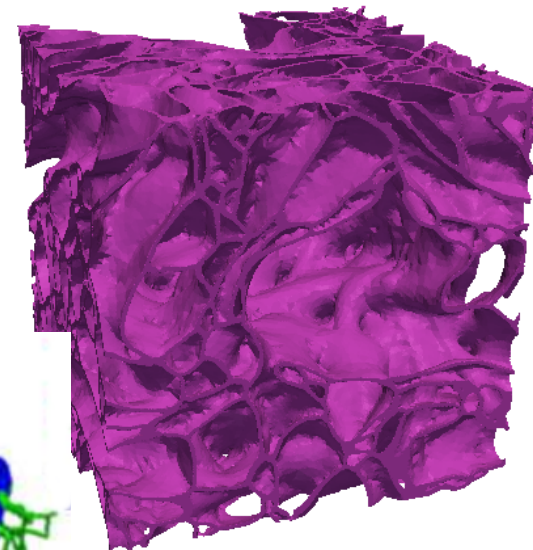
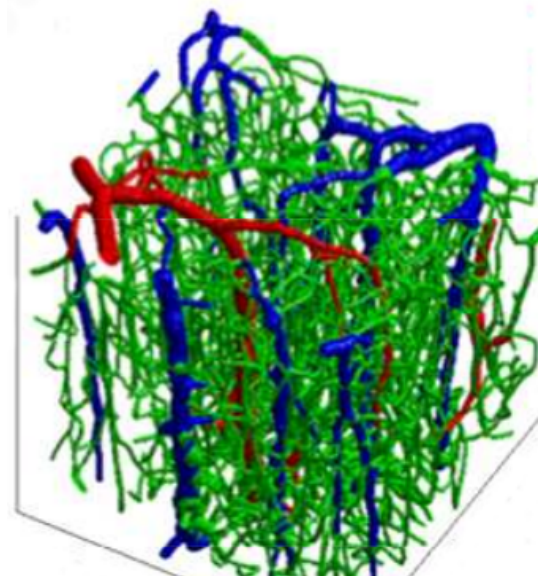
# Preconditioners for monolithic multi-physics problems – with applications toward the biomechanics of the brain

Kent-Andre Mardal  
University of Oslo /  
Simula Research Laboratory

healthy  
brain



advanced  
alzheimer's



MWNDEA 2020

Monash Workshop on Numerical Differential Equations and Applications 2020

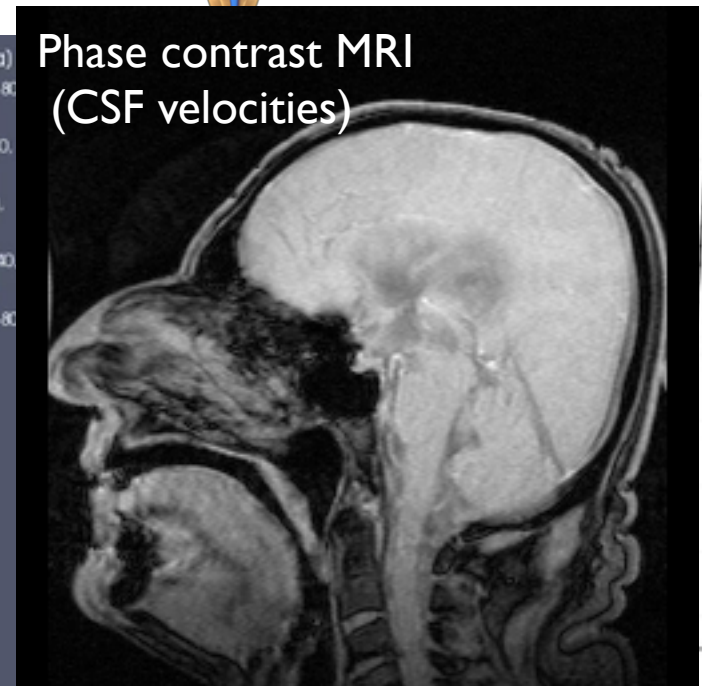
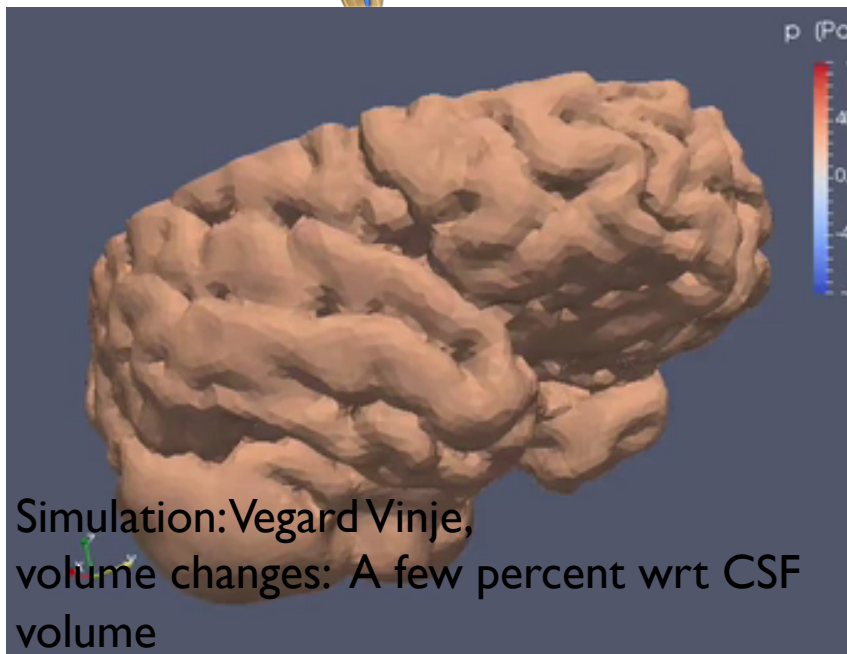
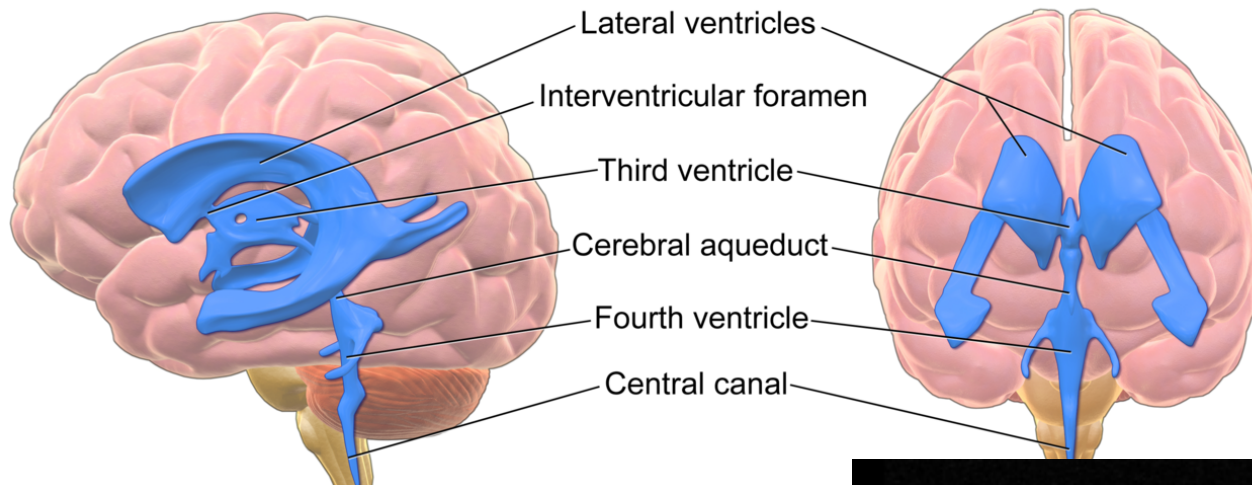
# Outline

- Alzheimer's disease & the glymphatic system
- Modeling of the glymphatics and brain mechanics: controversies, previous attempts
- Preconditioning of multi-physics / multi-scale models

# The greying of Europe

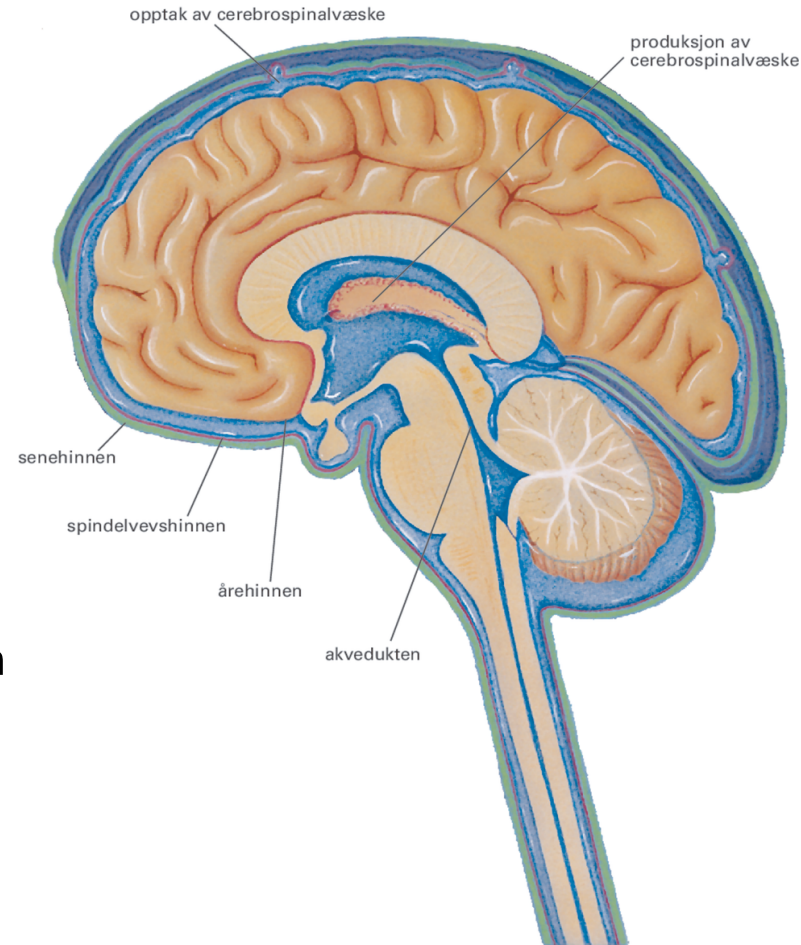
- Cost of Alzheimer's disease in Europe amounts to about 1% of GDP and will increase
- The disease develops over decades and early treatment has significant potential
- Little effort spent by the computational or biomechanics community compared to sophisticated models that have been developed for cardiovascular diseases
- The hallmark feature of the disease is accumulation of metabolic waste (amyloid beta) (as is also common for other types of dementia)

# Overview of the poro-elastic brain

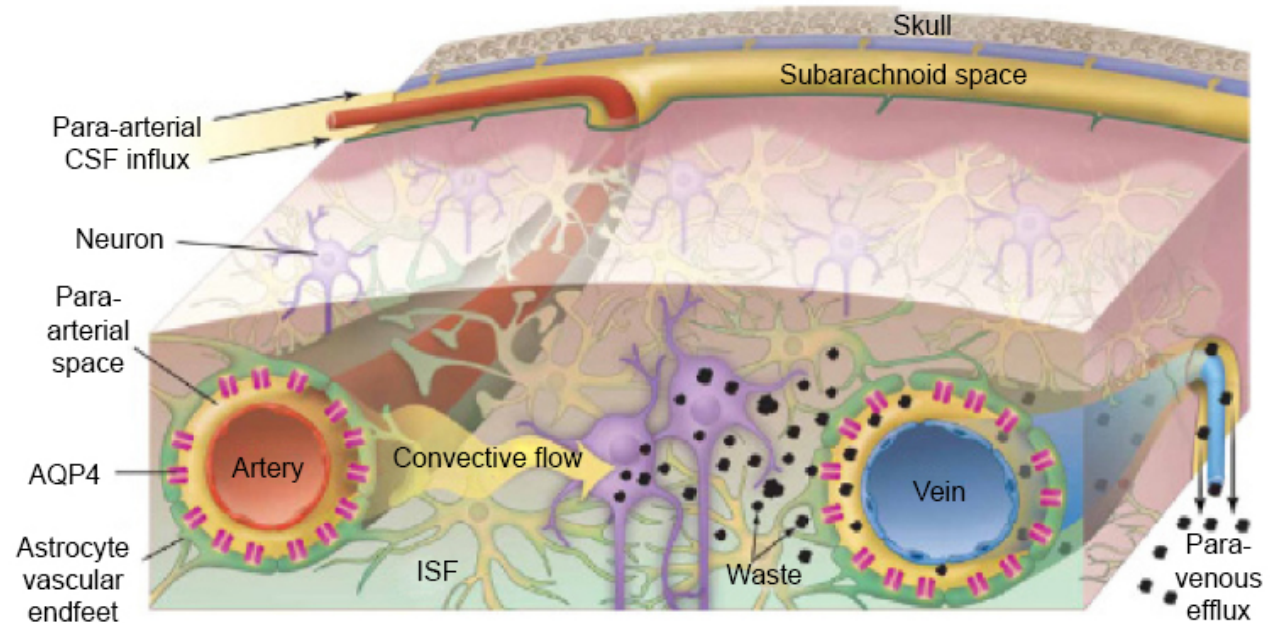


# Basic facts about the brain's metabolism

- The brain occupies 1-2% of the body in volume / weight
- The brain consumes around 10-20% of the body's energy, oxygen
- Elsewhere in the body, the lymphatic system plays a central role in the disposal of waste
- The brain does not have a lymph system and how the brain clears waste is currently unknown
- Comment: The brain is special because it is bathed in water (cerebrospinal fluid).



# Glymphatic system: the garbage truck of the brain

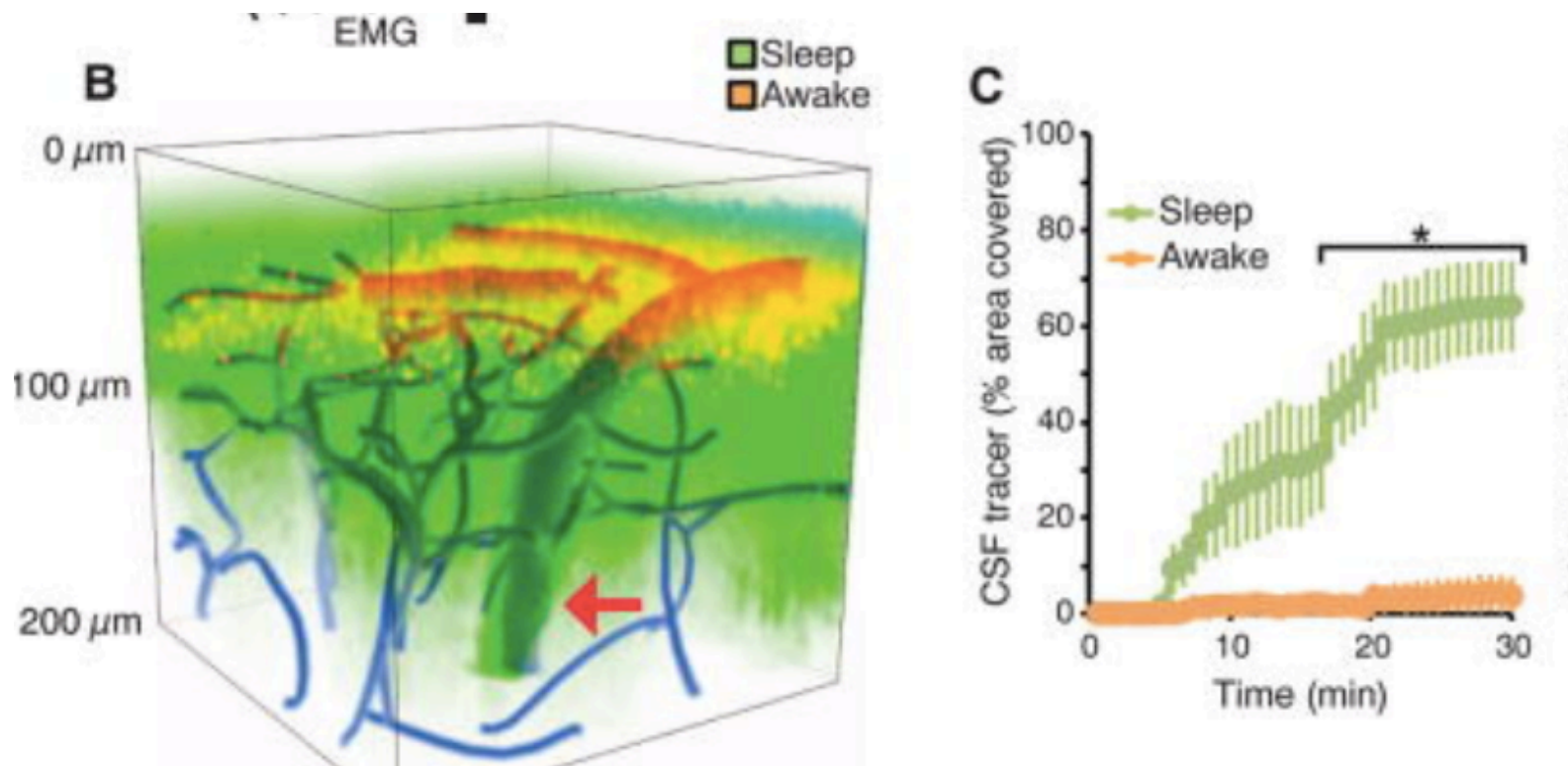


The new pathway:

- the paravascular space that surrounds the arteries/arterioles are connected with the CSF that surrounds the brain. This space facilitates a bulk flow (**viscous flow**)
- the hydrostatic pressure gradient between the arterial and venous sites facilitates a bulk flow through the interstitium (**porous flow**)
- the waste is then removed on the venous site (**viscous flow**)

Nedergaard M. Garbage truck of the brain. Science. 2013

# The glymphatic system is hyperactive during sleep because the extracellular volume increases

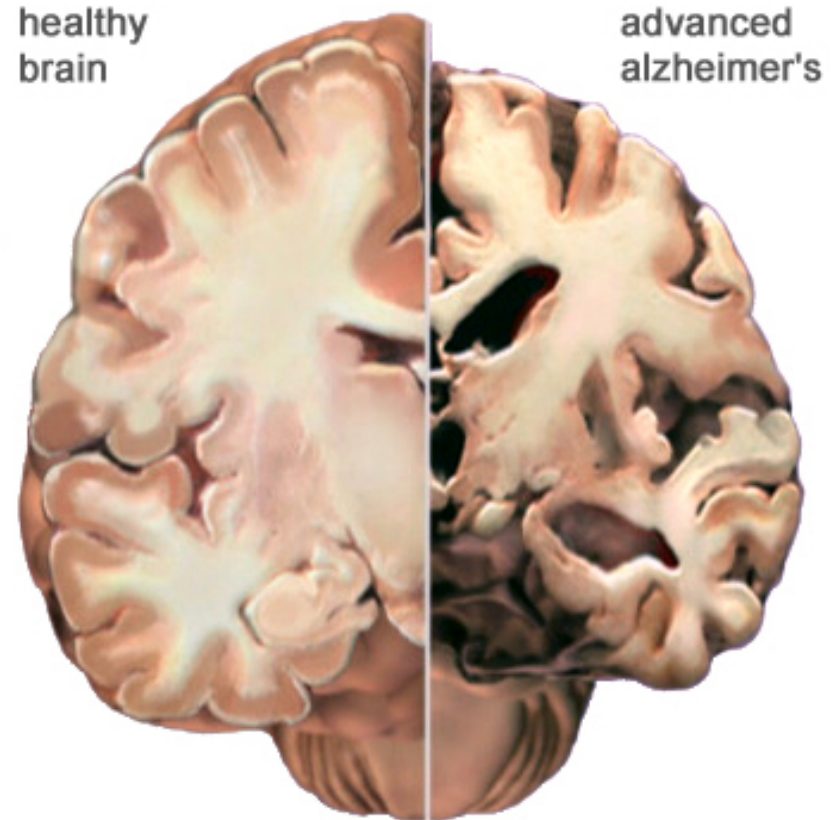


Xie, Lulu, et al. "Sleep drives metabolite clearance from the adult brain."  
Science 2013

3 kDa Texas Red Dextran typically penetrated 100-200  $\mu\text{m}$  in about 20 minutes

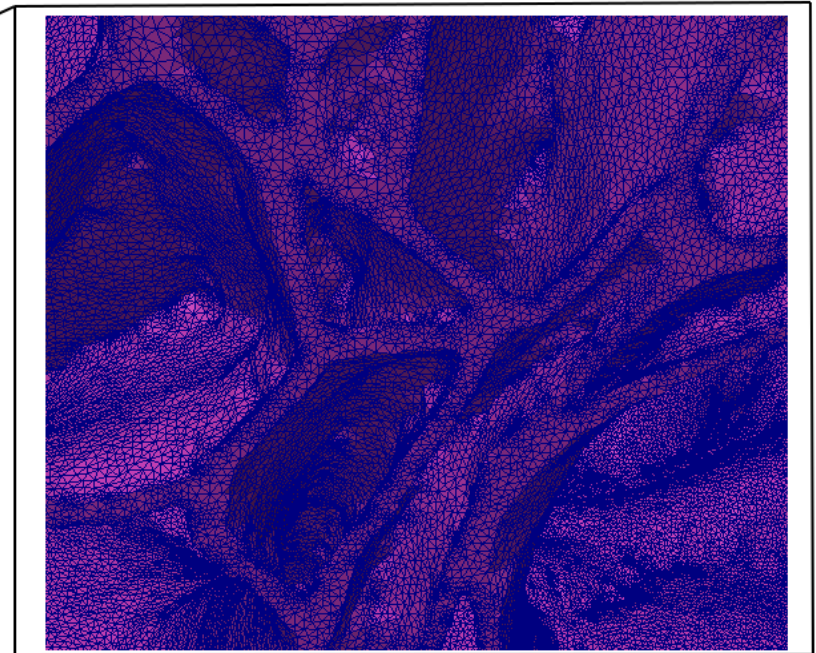
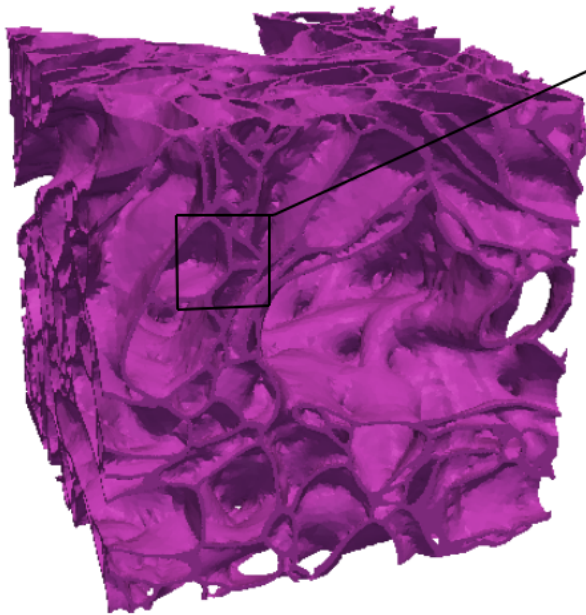
# Characteristics of Alzheimer's disease from a modeling point of view

- Massive brain shrinkage
- Accumulation of waste (amyloid beta) leading to cell death
- The accumulation of waste suggests that the glymphatic system is malfunctioning
- Hence, a proper understanding of this system may have significant potential





# Extracellular flow driven by a hydrostatic gradient: What is the effective permeability, flow and pressure?



Piece of grey matter from rat,  $\sim (5 \text{ micron})^3$

Meshes 54-84 M cells

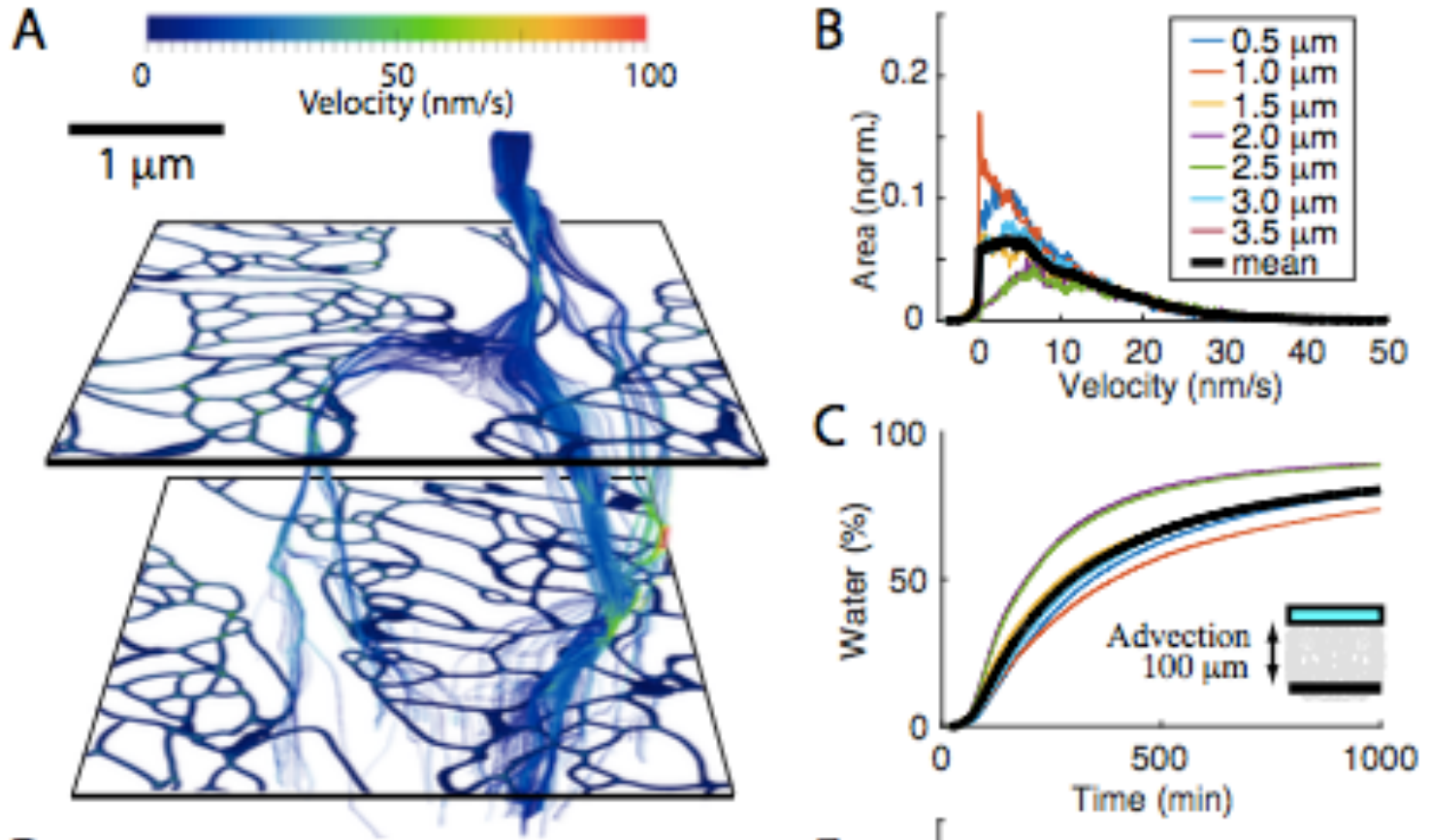
Extracellular space 10-20%

Pressure drop: 1 mmHg / mm

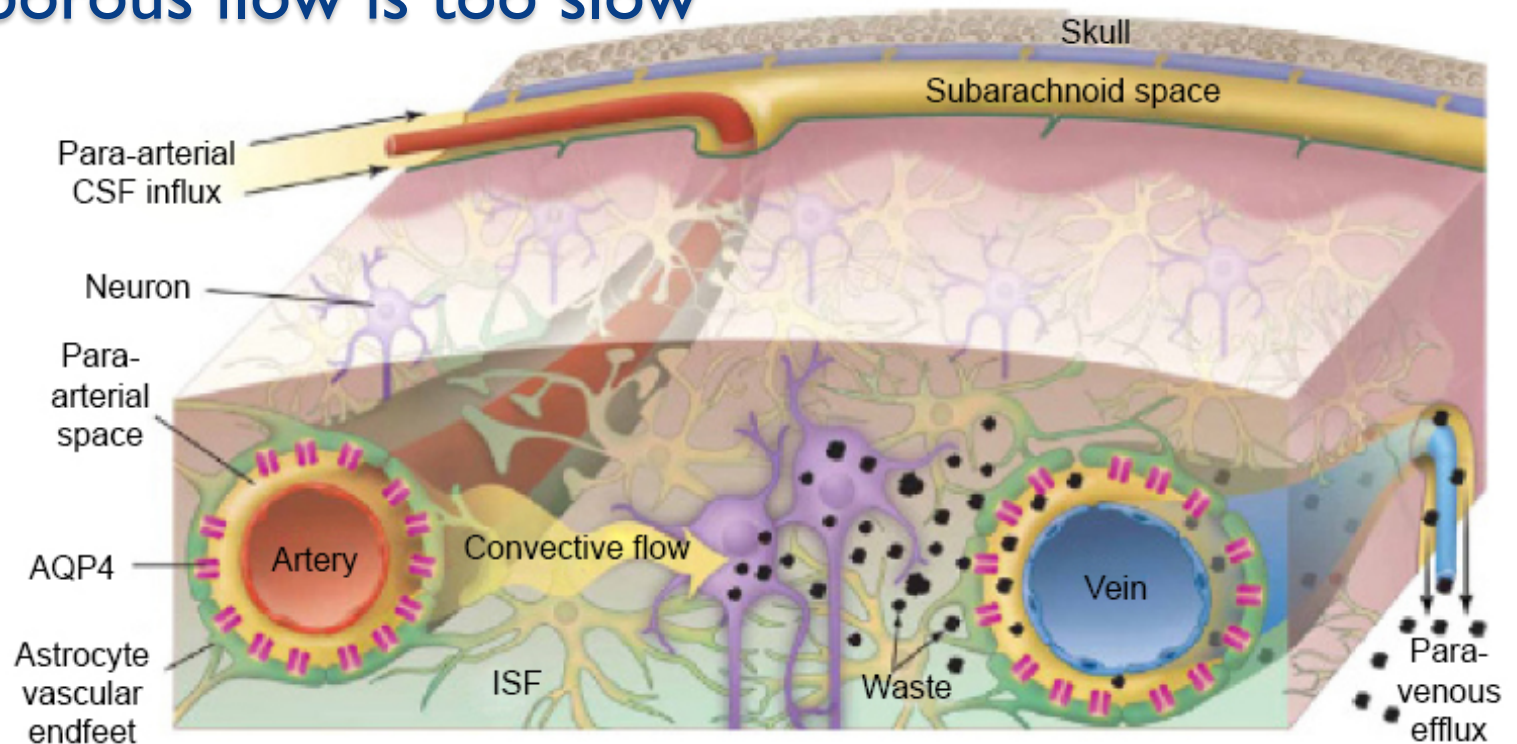
Stokes flow simulations:  $\sim 500$  CPU hours / 3 hours real-time

Kinney et.al , J of comparative  
neurology, 2013

Velocities are 100 times slower, permeability also 100 times smaller than expected, and diffusion dominates:



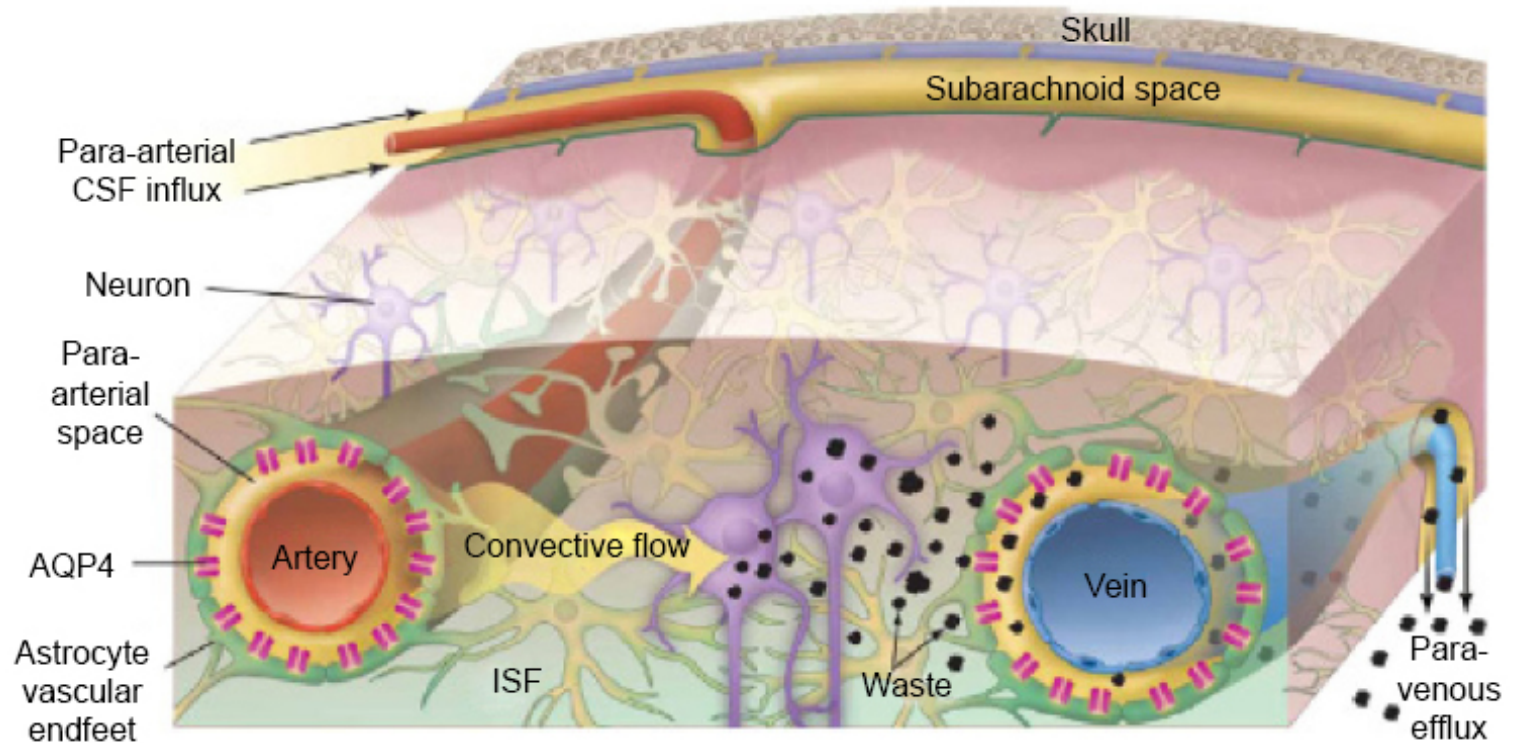
# Computational models suggest no bulk flow: diffusion dominates in the interstitium – the porous flow is too slow



Jin BJ, Smith AJ, Verkman AS. Spatial model of convective solute transport in brain extracellular space does not support a “glymphatic” mechanism. *The Journal of general physiology*. 2016

Holter KE, Kehlet B, Devor A, Sejnowski TJ, Dale AM, Omholt SW, Ottersen OP, Nagelhus EA, Mardal KA, Pettersen KH. Interstitial solute transport in 3D reconstructed neuropil occurs by diffusion rather than bulk flow. *Proceedings of the National Academy of Sciences*. 2017

# Glymphatic system: the garbage truck of the brain – the viscous flow is too slow ...

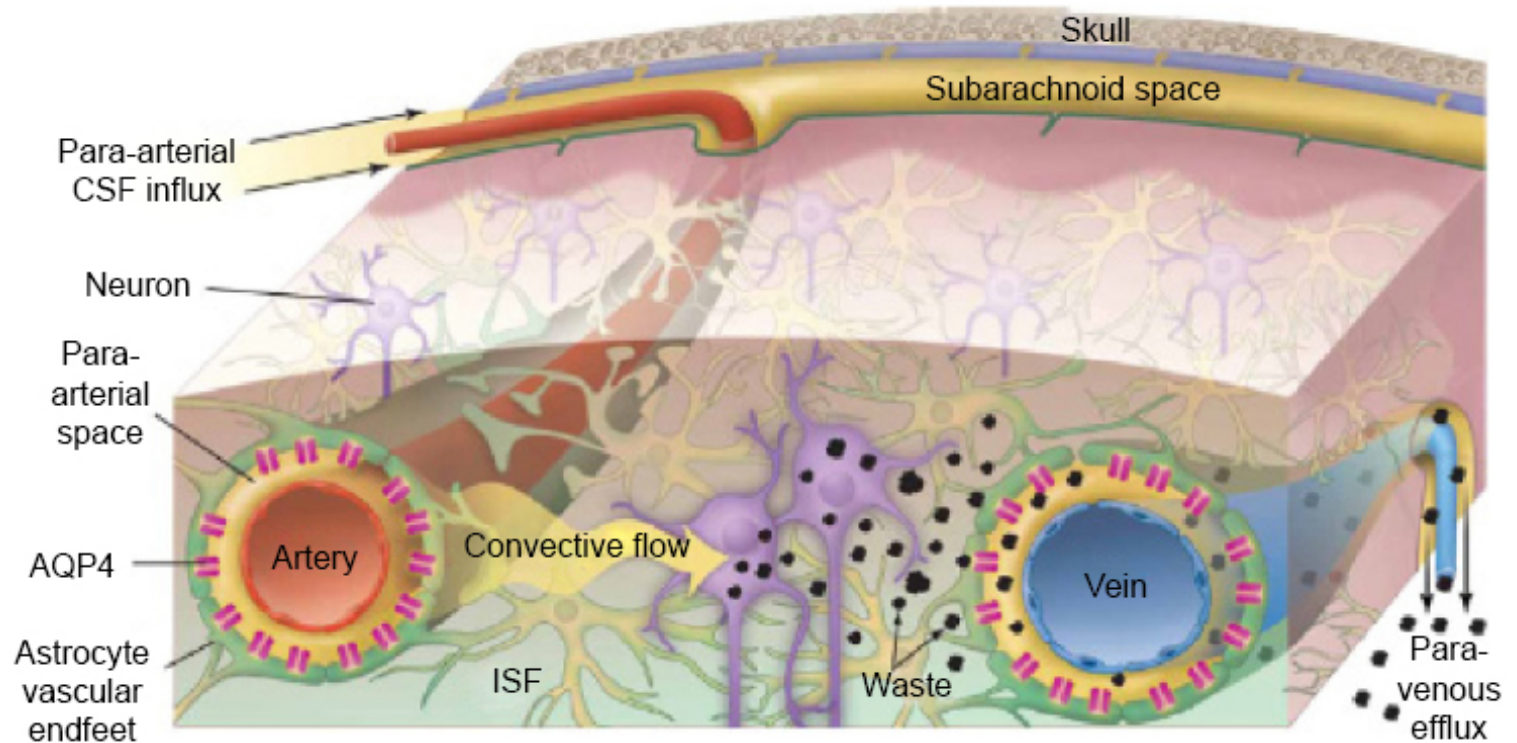


M. K. Sharp, R. Carare, and B. Martin, "Dispersion in porous media in oscillatory flow between flat plates: Applications to intrathecal, periarterial and paraarterial solute transport in the central nervous system," *Journal of Fluid Mechanics*, Accepted

M. Asgari, D. De Zelicourt, and V. Kurtcuoglu, "Glymphatic solute transport does not require bulk flow," *Scientific reports*, vol. 6, 2016.

Both papers find that because the peria/para vascular spaces are narrow; bulk flow or dissipation effects will be small

# Glymphatic system: the garbage truck of the brain



... of the drainage

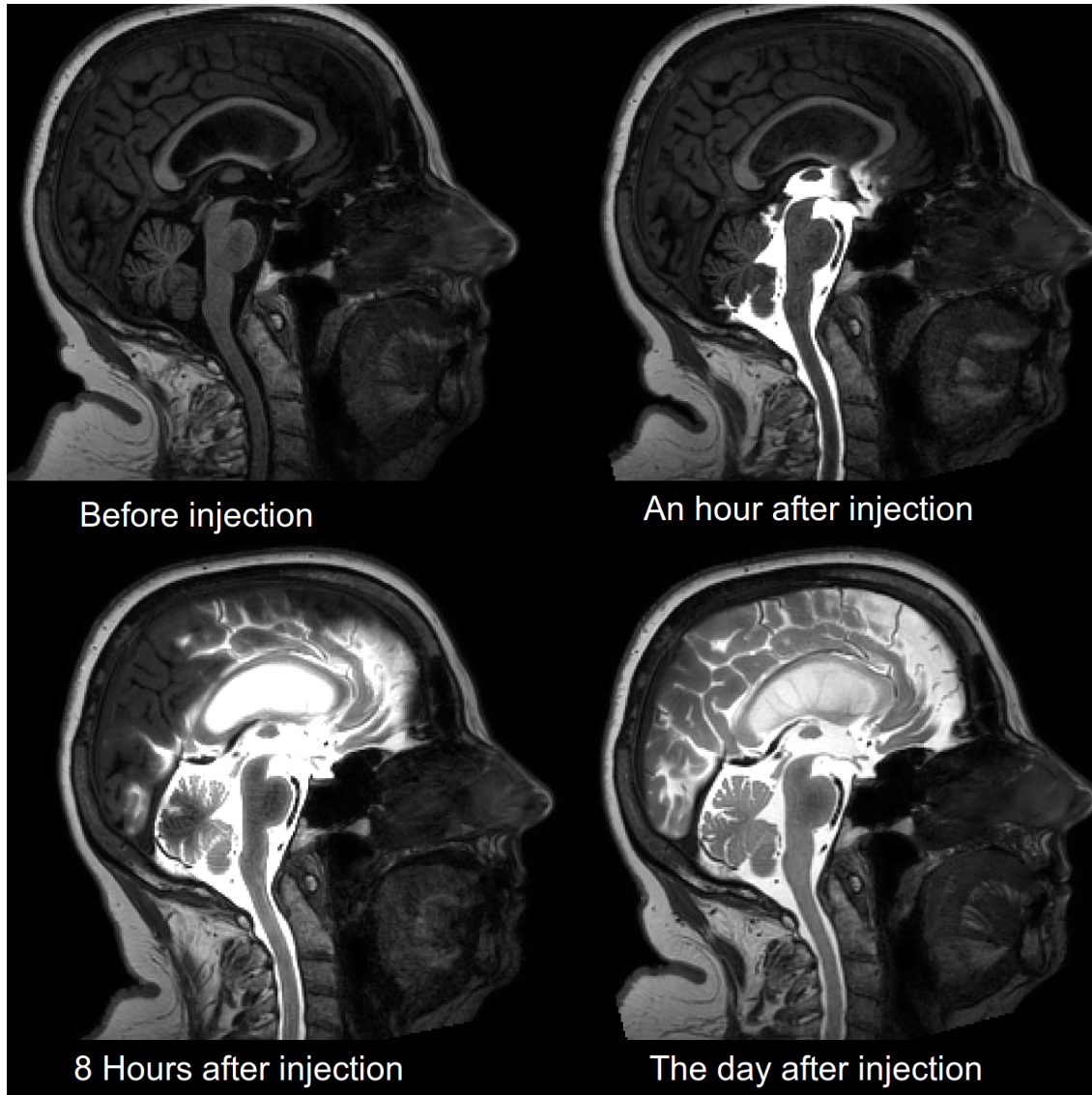
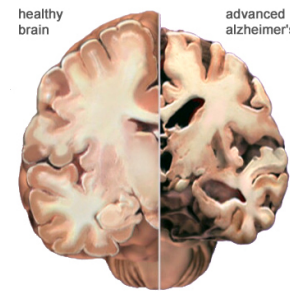
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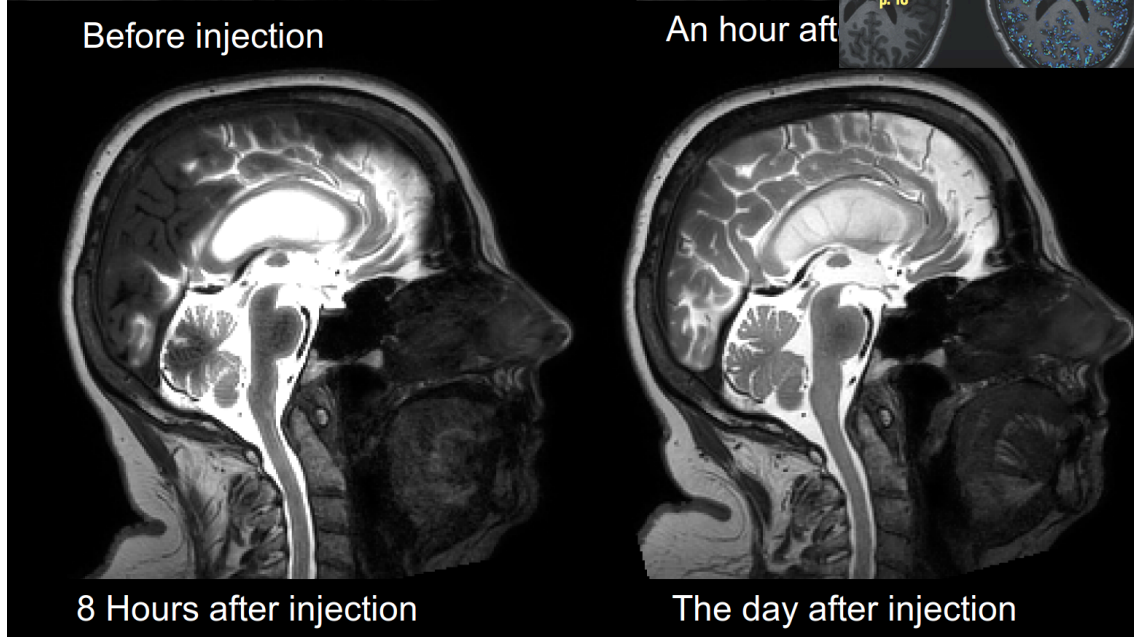
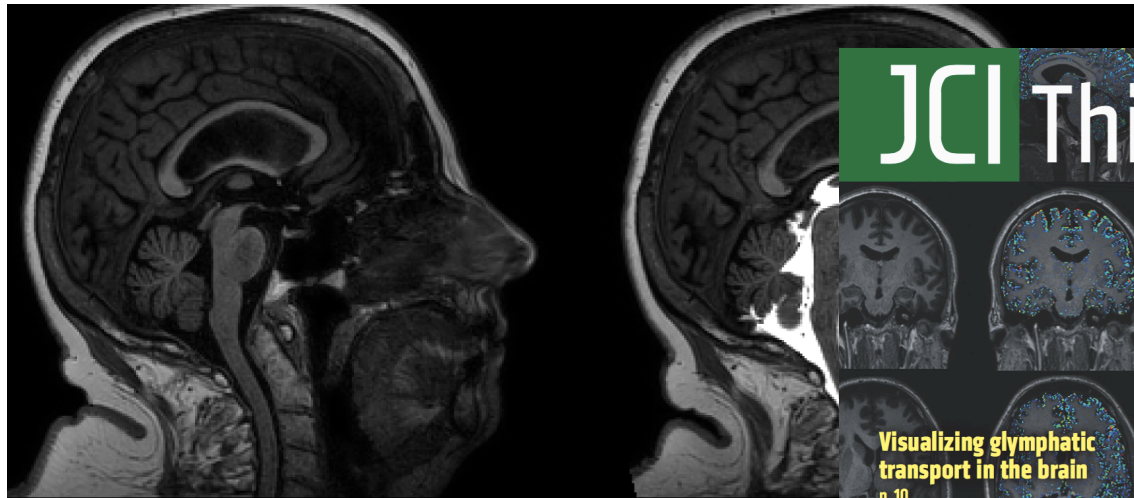
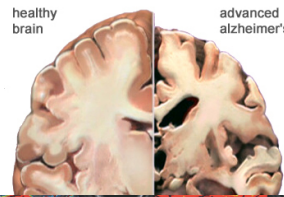
# New MRI investigations

# Intrathecal MR-contrast



With Lars Magnus Valnes, Geir Ringstad, Per Kristian Eide

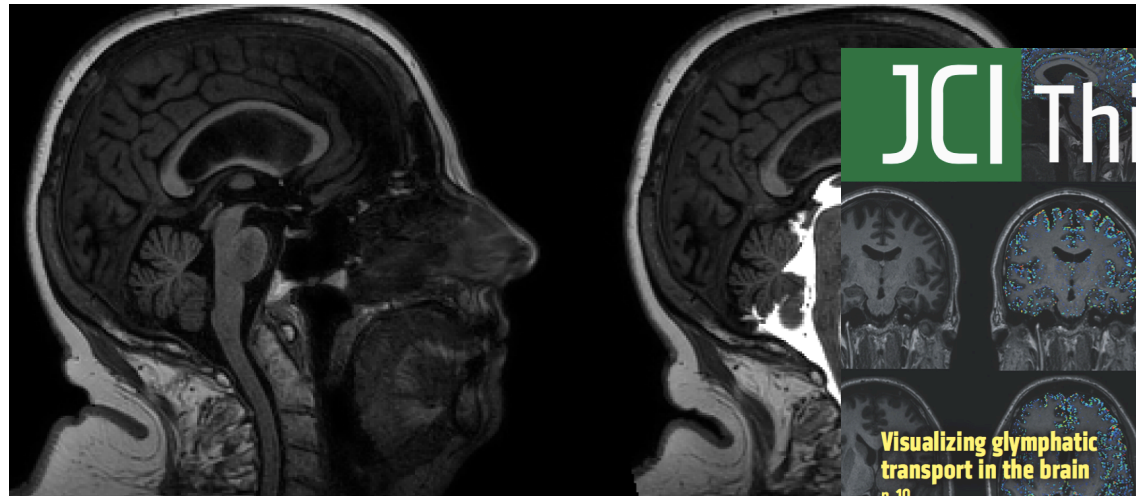
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With Lars Magnus Valnes, Geir Ringstad, Per Kristian Eide

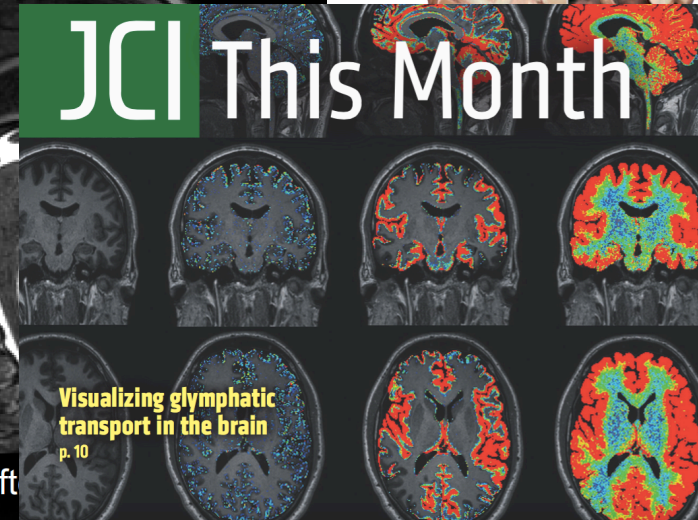


# Intrathecal MR-contrast

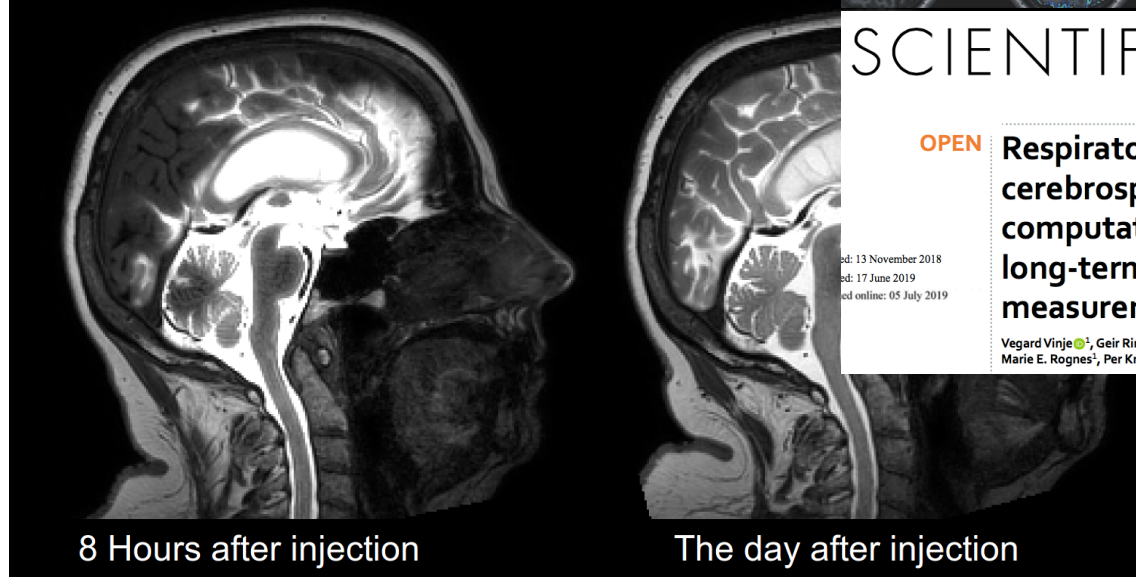


Before injection

An hour after



Visualizing glymphatic transport in the brain p. 10



8 Hours after injection

The day after injection

## SCIENTIFIC REPORTS

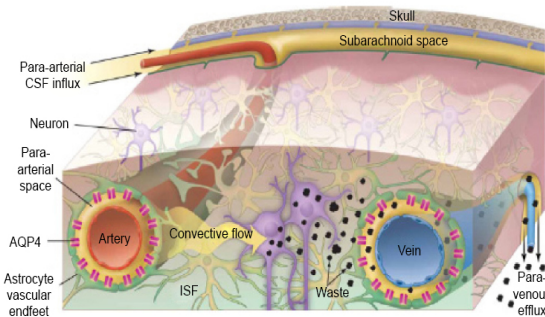
**OPEN** Respiratory influence on cerebrospinal fluid flow – a computational study based on long-term intracranial pressure measurements

Published: 13 November 2018  
Revised: 17 June 2019  
Accepted online: 05 July 2019

Vegard Vinje<sup>1</sup>, Geir Ringstad<sup>2</sup>, Erika Kristina Lindström<sup>3</sup>, Lars Magnus Valnes<sup>4</sup>, Marie E. Rognes<sup>1</sup>, Per Kristian Eide<sup>1,2,3</sup> & Kent-Andre Mardal<sup>1,4</sup>

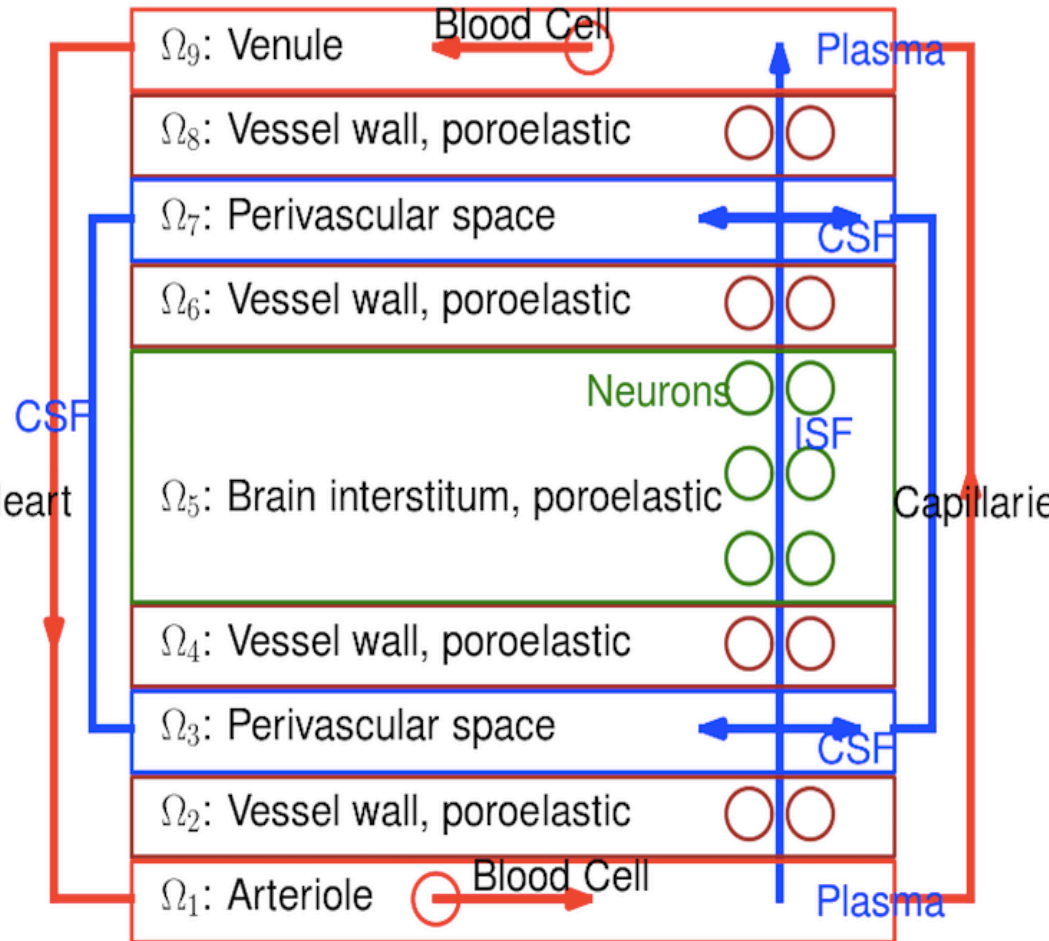
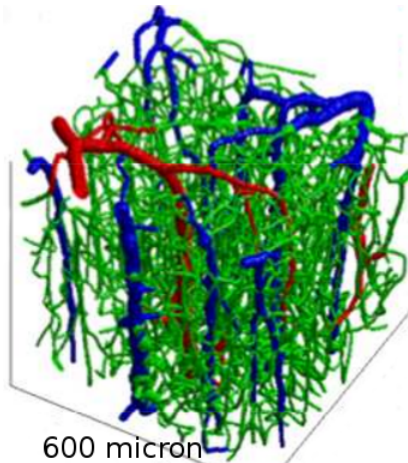
With Lars Magnus Valnes, Geir Ringstad, Per Kristian Eide

# Roadmap for model development (?)

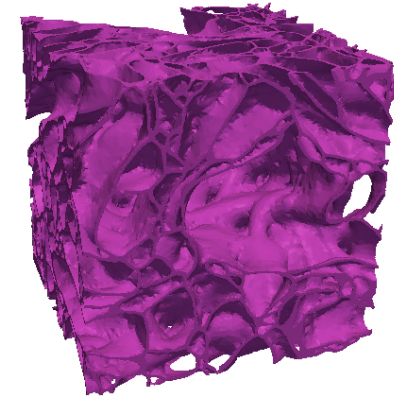
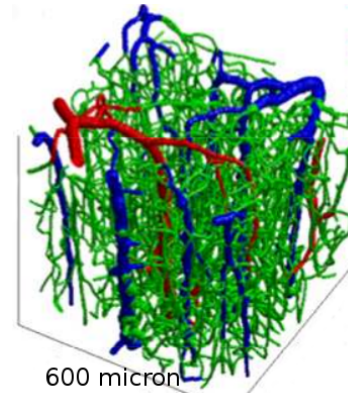
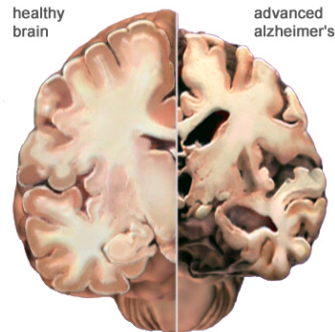


Take into account:

- poroelasticity
- complex, realistic geometries
- multiscale/multiphysics



# Requirements for the new models



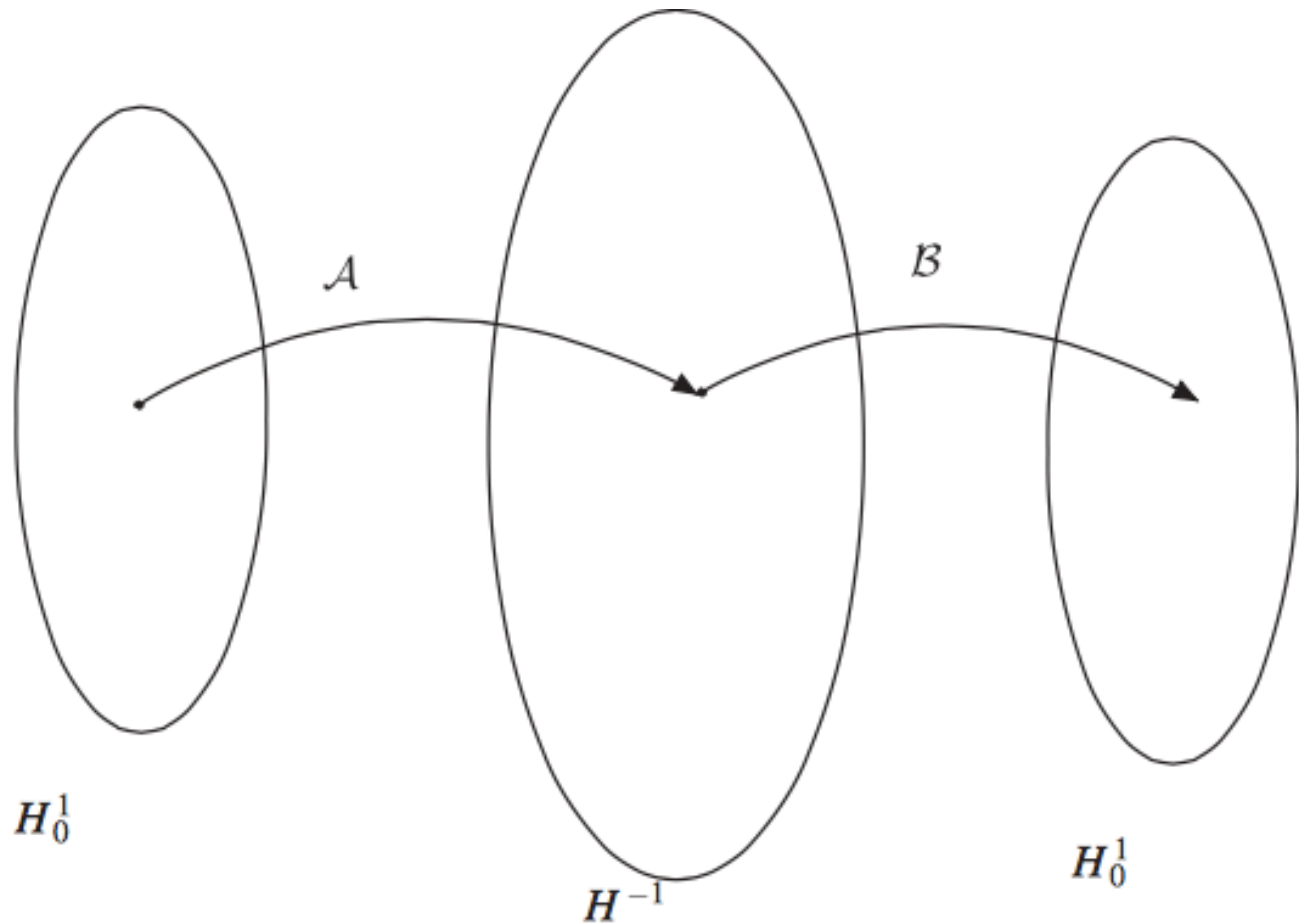
## Features of the new modeling:

- geometry is complex at all interesting scales: HPC needed
- poroelasticity has not yet been taken into account
- the problem is a multiscale/multiphysics problem and the dynamics is slow

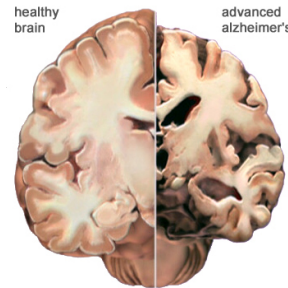
# Main tool for designing efficient algorithms: Operator preconditioning

- Explain concepts of operator preconditioning in the context of coupled problems (viscous – porous flow)
- The need for fractional derivatives
- Extend to 3D-1D problems

# Operator preconditioning in a nutshell



Mardal KA, Winther R. Preconditioning discretizations of systems of partial differential equations. Numerical Linear Algebra with Applications. 2011 Jan;18(1):1-40



# Coupling of viscous and porous flow

$$\begin{aligned}
 \mu \Delta \mathbf{u}_f - \nabla p_f &= 0 \text{ on } \Omega_f, \\
 \nabla \cdot \mathbf{u}_f &= 0 \text{ on } \Omega_f, \\
 \frac{\mu}{\kappa} \mathbf{u}_p - \Delta p_p &= 0 \text{ on } \Omega_p, \\
 \nabla \cdot \mathbf{u}_p &= 0 \text{ on } \Omega_p, \\
 \mathbf{u}_f \cdot \mathbf{n} &= \mathbf{u}_p \cdot \mathbf{n} \text{ on } \Gamma, \\
 -\mu \frac{\partial \mathbf{u}_f}{\partial \mathbf{n}} \cdot \mathbf{n} + p_f &= p_p \text{ on } \Gamma, \\
 -\mu \frac{\partial \mathbf{u}_f}{\partial \mathbf{n}} \cdot \mathbf{t} - D \mathbf{u}_f \cdot \mathbf{t} &= 0 \text{ on } \Gamma.
 \end{aligned}$$

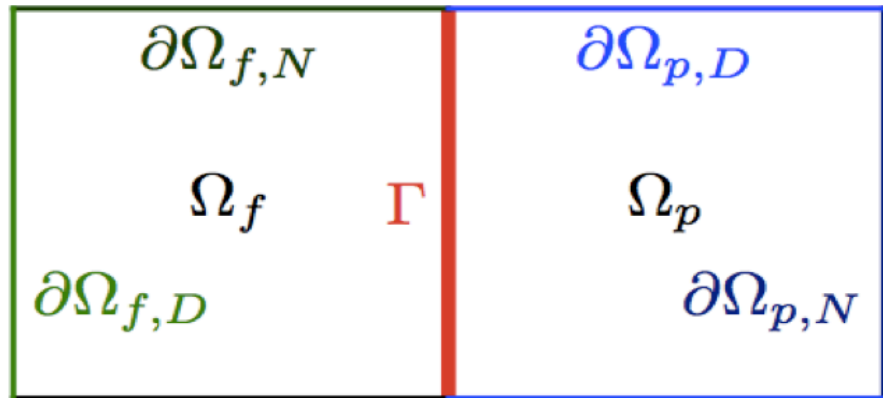


FIGURE 1. Schematic domain of Darcy-Stokes problem. Dirichlet conditions shown in green/blue, and interface in red.

## Joint work with Karl Erik Holter and Miro Kuchta

Well-posedness, error estimates already done:

W. J. Layton, F. Schieweck, and I. Yotov, Coupling fluid flow with porous media flow, SIAM Journal on Numerical Analysis, 40 (2002)

J. Galvis and M. Sarkis, Non-matching mortar discretization analysis for the coupling Stokes-Darcy equations, Electron. Trans. Numer. Anal, 26 (2007),

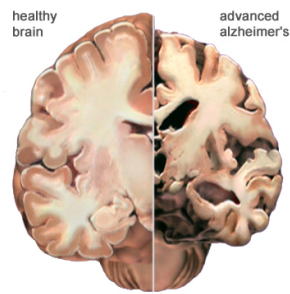
# Stokes problem – wellposedness is well known

$$\Delta \mathbf{u} - \nabla p = \mathbf{f} \quad \text{in } \Omega$$

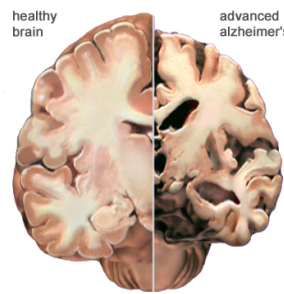
$$\nabla \cdot \mathbf{u} = 0 \quad \text{in } \Omega$$

$$\mathbf{u} = 0 \quad \text{on } \partial\Omega$$

$$\rightarrow \mathbf{u} \in H_0^1, p \in L_0^2$$



# Stokes problem weighted by viscosity is not much different



$$\Delta \mathbf{u} - \nabla p = \mathbf{f} \quad \text{in } \Omega$$

$$\nabla \cdot \mathbf{u} = 0 \quad \text{in } \Omega$$

$$\mathbf{u} = 0 \quad \text{on } \partial\Omega$$

$$\rightarrow \mathbf{u} \in H_0^1, p \in L_0^2$$

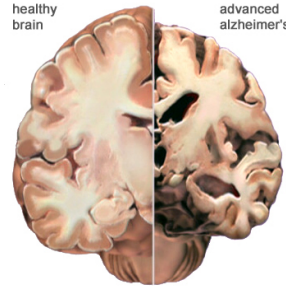
$$\mu \Delta \mathbf{u} - \nabla p = \mathbf{f} \quad \text{in } \Omega$$

$$\nabla \cdot \mathbf{u} = 0 \quad \text{in } \Omega$$

$$\mathbf{u} = 0 \quad \text{on } \partial\Omega$$

$$\rightarrow \mathbf{u} \in \mu^{1/2} H_0^1, p \in \mu^{-1/2} L_0^2$$





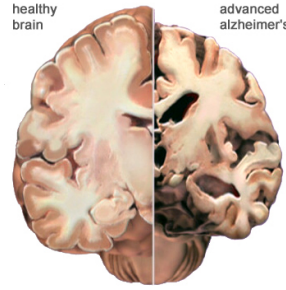
# Stokes problem (some details about the weighted wellposedness)

$$\|\mathbf{u}\|_{\mu^{1/2}H_0^1} = \left( \int_{\Omega} \mu (\nabla \mathbf{u})^2 dx \right)^{1/2}$$

$$\|p\|_{\mu^{-1/2}L_0^2} = \left( \int_{\Omega} \frac{1}{\mu} p^2 dx \right)^{1/2}$$

$$\begin{aligned} \int_{\Omega} \mu \nabla \mathbf{u} : \nabla \mathbf{v} dx &= \int_{\Omega} \mu^{1/2} \nabla \mathbf{u} : \mu^{1/2} \nabla \mathbf{v} dx \\ &\leq \|\mathbf{u}\|_{\mu^{1/2}H_0^1} \|\mathbf{v}\|_{\mu^{1/2}H_0^1} \end{aligned}$$

$$\begin{aligned} \int_{\Omega} \nabla \cdot \mathbf{u} q dx &= \int_{\Omega} (\mu^{1/2} \nabla \cdot \mathbf{u}) \mu^{-1/2} q dx \\ &\leq \|\mathbf{u}\|_{\mu^{1/2}H_0^1} \|p\|_{\mu^{-1/2}L_0^2} \end{aligned}$$



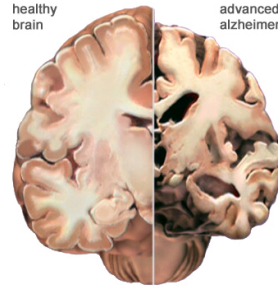
Darcy Problem well-posedness with permeability parameter is similar

$$\begin{aligned}\frac{1}{K}\mathbf{u} - \nabla p &= \mathbf{f} && \text{in } \Omega \\ \nabla \cdot \mathbf{u} &= g && \text{in } \Omega\end{aligned}$$

$$\rightarrow \mathbf{u} \in K^{-1/2}\mathbf{H}_0(\text{div}), p \in K^{1/2}L_0^2$$

$$\|\mathbf{u}\|_{K^{-1/2}\mathbf{H}(\text{div})} = \left( \int_{\Omega} \frac{1}{K} (\nabla \mathbf{u})^2 + \frac{1}{K} (\nabla \cdot \mathbf{u})^2 dx \right)^{1/2}$$

$$\|p\|_{K^{1/2}L_0^2} = \left( \int_{\Omega} K p^2 dx \right)^{1/2}$$



# Coupling of viscous and porous flow

$$\begin{aligned}
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 \mathbf{u}_f \cdot \mathbf{n} &= \mathbf{u}_p \cdot \mathbf{n} \text{ on } \Gamma, \\
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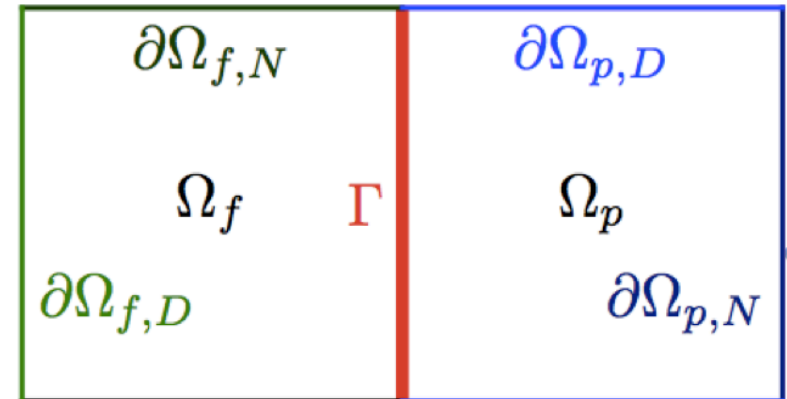
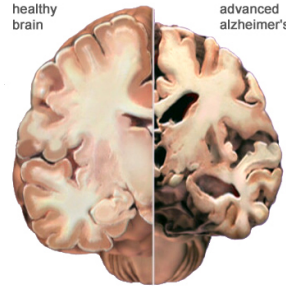


FIGURE 1. Schematic domain of Darcy-Stokes problem. Dirichlet conditions shown in green/blue, and interface in red.



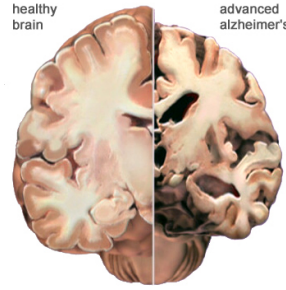
What is happening on the interface?

$$T(\mu^{1/2} H^1) = \mu^{1/2} H^{1/2}$$

$$T_n(K^{-1/2} \mathbf{H}(\text{div})) = K^{-1/2} H^{-1/2}$$

$$\mu^{1/2} H^{1/2} \ni \mathbf{u}_f \cdot \mathbf{n} = \mathbf{u}_p \cdot \mathbf{n} \in K^{-1/2} H^{-1/2} \text{ on } \Gamma$$

$$(T_n \mathbf{u}_f - T_n \mathbf{u}_p, q) = 0, \forall q$$



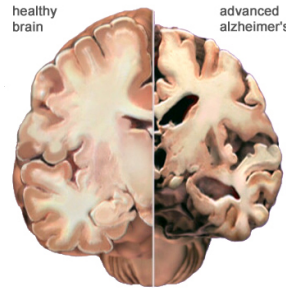
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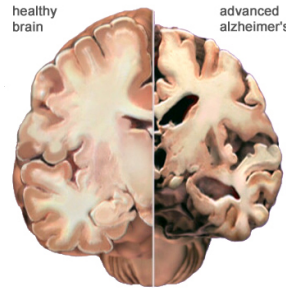
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$$(T_n \mathbf{u}_f - T_n \mathbf{u}_p, q) = 0, \forall q$$

$$T_n \mathbf{u}_f - T_n \mathbf{u}_p \in \mu^{1/2} H^{1/2}(\Gamma) + K^{-1/2} H^{-1/2}(\Gamma)$$

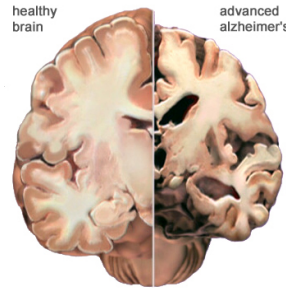


What is happening on the interface?

$$(T_n \mathbf{u}_f - T_n \mathbf{u}_p, q) = 0, \forall q$$

$$T_n \mathbf{u}_f - T_n \mathbf{u}_p \in \mu^{1/2} H^{1/2}(\Gamma) + K^{-1/2} H^{-1/2}(\Gamma)$$

$$q \in \mu^{-1/2} H^{-1/2}(\Gamma) \cap K^{1/2} H^{1/2}(\Gamma)$$



## What happens on the interface $\Gamma$ ?

$$(T_n \mathbf{u}_f - T_n \mathbf{u}_p, q) = 0, \forall q$$

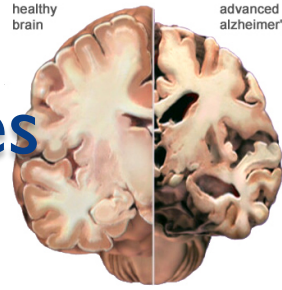
$$T_n \mathbf{u}_f - T_n \mathbf{u}_p \in \mu^{1/2} H^{1/2}(\Gamma) + K^{-1/2} H^{-1/2}(\Gamma)$$

$$q \in \mu^{-1/2} H^{-1/2}(\Gamma) \cap K^{1/2} H^{1/2}(\Gamma)$$

The sum of two Hilbert spaces  $X$  and  $Y$  is a Hilbert space denoted by  $X+Y$

And its dual is the intersection of the dual spaces!

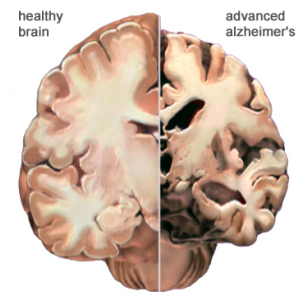




# A preconditioner for the Darcy-Stokes problem (robust in all parameters)

$$\mathcal{A} = \left( \begin{array}{cc|cc} -\mu\Delta & & -\nabla & T'_n \\ & -1/K & & -\nabla T'_n \\ \hline \nabla\cdot & & & \\ & \nabla\cdot & & \\ T_n & T_n & & \end{array} \right) \begin{pmatrix} \mathbf{u}_f \\ \mathbf{u}_p \\ p_f \\ p_p \\ q \end{pmatrix} = \dots$$

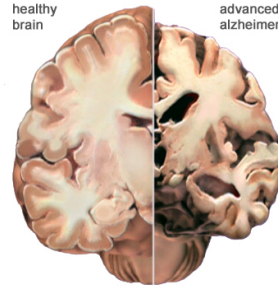
$$\mathcal{B} = \left( \begin{array}{cc|c} -\mu\Delta & & \\ \hline \frac{1}{K}(I - \nabla\nabla\cdot) & & \\ & \frac{1}{\mu} & \\ & & K \\ & & \frac{1}{\mu}(-\Delta)^{-1/2} + K(-\Delta)^{1/2} \end{array} \right)^{-1}$$



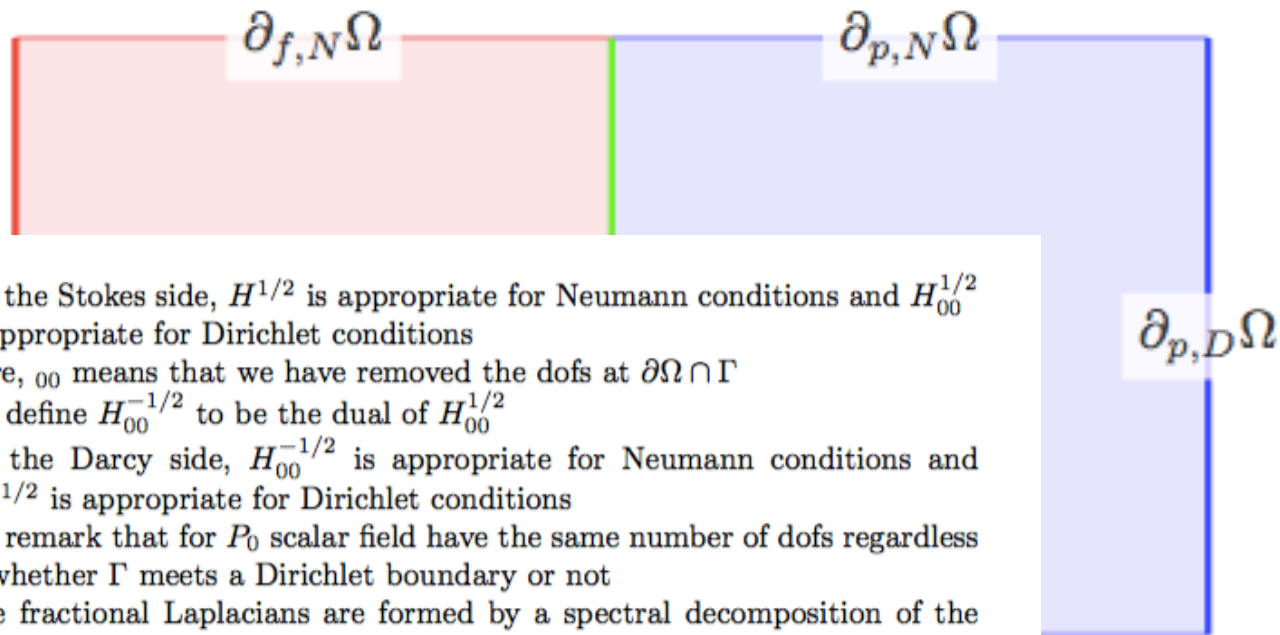
# Iteration counts....

$\alpha_{BJS}$	$\mu$	$K$	$h$				
1	1	1	38	38	36	36	36
		$10^{-2}$	41	39	39	37	37
		$10^{-4}$	40	40	41	41	40
		$10^{-6}$	36	36	35	35	36
		$10^{-8}$	31	31	31	31	30
	$10^{-2}$	1.0	44	43	42	41	40
		$10^{-2}$	42	43	45	45	43
		$10^{-4}$	38	38	39	41	41
		$10^{-6}$	34	34	34	34	35
		$10^{-8}$	29	29	29	29	27
	$10^{-4}$	1.0	52	53	55	55	55
		$10^{-2}$	48	49	50	52	52
		$10^{-4}$	42	44	45	47	47
		$10^{-6}$	38	38	39	39	41
		$10^{-8}$	34	34	34	34	35
	$10^{-6}$	1.0	52	53	56	56	58
		$10^{-2}$	52	53	54	56	56
		$10^{-4}$	50	50	50	50	52
		$10^{-6}$	42	44	45	47	48
		$10^{-8}$	38	38	39	39	41
$10^{-8}$	1.0	52	55	56	56	58	
	$10^{-2}$	52	55	56	56	58	
	$10^{-4}$	52	54	55	56	56	
	$10^{-6}$	50	50	50	50	52	
	$10^{-8}$	42	44	45	47	48	

MinRes with an appropriate preconditioner



# Final comment: boundary conditions for the Lagrange multiplier at the interface



- On the Stokes side,  $H^{1/2}$  is appropriate for Neumann conditions and  $H_{00}^{1/2}$  is appropriate for Dirichlet conditions
- Here,  $_{00}$  means that we have removed the dofs at  $\partial\Omega \cap \Gamma$
- We define  $H_{00}^{-1/2}$  to be the dual of  $H_{00}^{1/2}$
- On the Darcy side,  $H_{00}^{-1/2}$  is appropriate for Neumann conditions and  $H^{-1/2}$  is appropriate for Dirichlet conditions
- We remark that for  $P_0$  scalar field have the same number of dofs regardless of whether  $\Gamma$  meets a Dirichlet boundary or not
- The fractional Laplacians are formed by a spectral decomposition of the Laplacian as described in detail in [Kuchta et.al, SISC, 2016], where the Laplacian on piecewise constant field  $Q_h$  is defined as

$$(-\Delta p_h, q_h) = \sum_{E_I} \int_{E_I} \{\{h\}\}^{-1} [p][q] ds + \sum_{E_D} \int_{E_D} h^{-1} p q ds \quad p_h, q_h \in Q_h$$

where  $E_I$  is the set of internal facets of the mesh, while  $E_D$  is the set of facets associated with the Dirichlet boundary. Operators  $[ ]$  and  $\{\{ \}$  are the standard jump and average operators. Note that for operator  $(-\Delta + I)^{-1/2}$  the set  $E_D$  is empty.

blem. Setting  $\Gamma \cap$

# Fractional Problems

- They show up at the interface in multi-physics/multi-scale problems
- Let us therefore consider fast solvers for:

$$(-\Delta)^s u = f$$

There has been a tremendous effort to discretize fractional Laplacians, but not so much about solving them

We have looked into how they can be solved with multilevel algorithms

# Fractional Problems

- They show up at the interface in multi-physics/multi-scale problems
- Let us therefore consider fast solvers for:

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## MULTIGRID METHODS FOR DISCRETE FRACTIONAL SOBOLEV SPACES\*

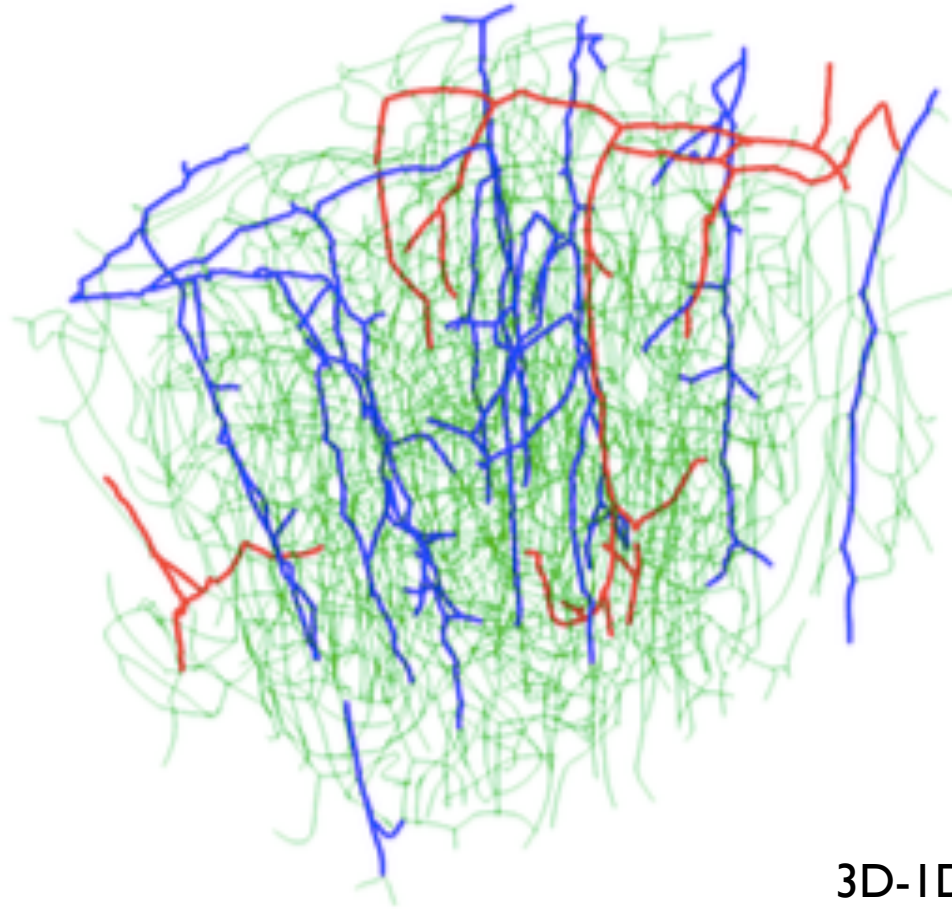
TRYGVE BÆRLAND<sup>†</sup>, MIROSLAV KUČHTA<sup>†</sup>, AND KENT-ANDRE MARDAL<sup>†</sup>

**Abstract.** Coupled multiphysics problems often give rise to interface conditions naturally formulated in fractional Sobolev spaces. Here, both positive and negative fractionality are common. When designing efficient solvers for discretizations of such problems it would therefore be useful to have a preconditioner for the fractional Laplacian. In this work, we develop an additive multigrid preconditioner for the fractional Laplacian with positive fractionality and show a uniform bound on the condition number. For the case of negative fractionality, we reuse the preconditioner developed for the positive fractionality and left-right multiply a regular Laplacian with a preconditioner with positive fractionality to obtain the desired negative fractionality. Implementational issues are outlined in detail as the differences between the discrete operators and their corresponding matrices must

There has been a tremor  
but not so much about s

We have looked into ho

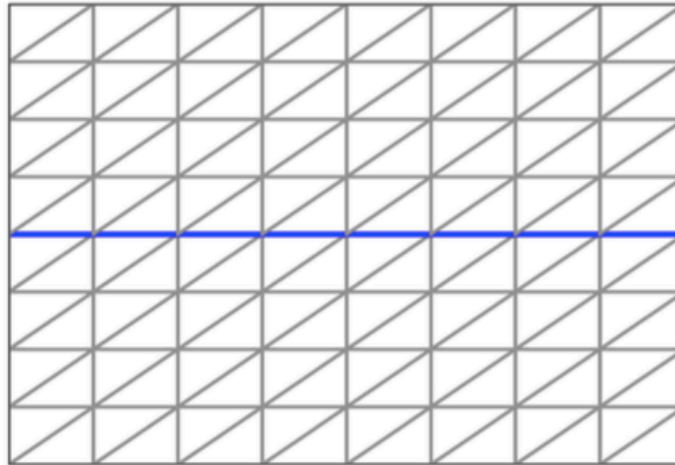
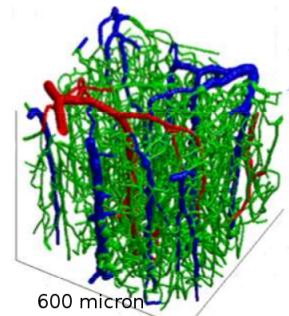
# Vessels in a $(0.6\text{mm})^3$ cube: 3D-ID coupled problem



Boas, David A., et al. *Neuroimage* 40.3 (2008):  
1116-1129.

3D-ID couplings:  
D'Angelo, Quarteroni,  
Zunino: weighted spaces  
with distance functions

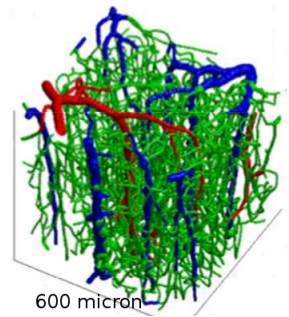
# Simple test example 2D-1D problem



► Strong form

$$\begin{aligned} -\Delta u_1 &= f_1 && \text{in } \Omega \subset \mathbb{R}^2 \\ -u_2'' &= f_2 && \text{on } \Gamma = \{(x(s), y(s)) \in \Omega, s = [s_0, s_1]\} \\ \epsilon u_1 &= u_2 && \text{on } \Gamma \end{aligned}$$

# 2D-1D weak form



- ▶ Strong form

$$-\Delta u_1 = f_1 \quad \text{in } \Omega \subset \mathbb{R}^2$$

$$-u_2'' = f_2 \quad \text{on } \Gamma = \{(x(s), y(s)) \in \Omega, s = [s_0, s_1]\}$$

$$\epsilon u_1 = u_2 \quad \text{on } \Gamma$$

$$u_1 = 0 \quad \text{on } \partial\Omega$$

$$u_2 = 0 \quad \text{on } \partial\Gamma$$

- ▶ Weak form using Lagrange multipliers. Find

$$u_1 \in V_1 := H_0^1(\Omega), u_2 \in V_2 := H_0^1(\Gamma), p \in Q := H^{-1/2}(\Gamma):$$

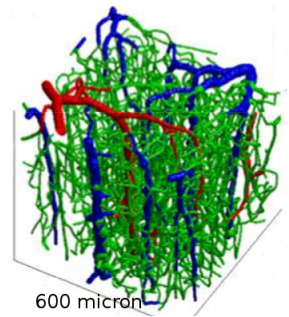
$$(\nabla u_1, \nabla v_1)_\Omega + \langle p, \epsilon T v_1 \rangle = (f_1, v_1)$$

$$(u_2', v_2')_\Gamma - \langle p, v_2 \rangle = (f_2, v_2)$$

$$\langle q, \epsilon T u_1 - u_2 \rangle = 0$$



# 2D-1D Preconditioner



The original problem was

$$\mathcal{A} = \begin{bmatrix} -\Delta_{\Omega} & 0 & \epsilon T^* \\ 0 & -\Delta_{\Gamma} & I \\ \epsilon T & I & 0 \end{bmatrix} \begin{bmatrix} u \\ v \\ p \end{bmatrix} = \begin{bmatrix} f \\ g \\ 0 \end{bmatrix}$$

an appropriate preconditioner would then be

$$\mathcal{B} = \begin{bmatrix} -\Delta_{\Omega} & 0 & 0 \\ 0 & -\Delta_{\Gamma} & 0 \\ 0 & 0 & \epsilon^2(-\Delta_{\Gamma}^{-1/2}) + -\Delta_{\Gamma}^{-1} \end{bmatrix}^{-1}$$

- ▶ Robust preconditioner requires parameter-dependent spaces

$$V_1 = H_0^1(\Omega), V_2 = H_0^1(\Gamma), Q = \frac{1}{\epsilon} H^{-1/2}(\Gamma) \cap H^{-1}(\Gamma)$$

# The preconditioner is good

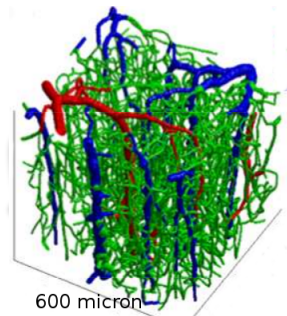
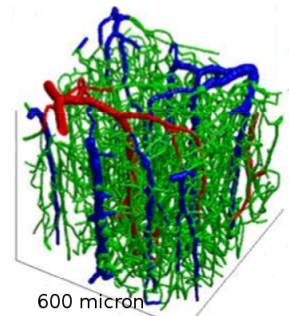


Table: Condition numbers

$n_{3D}$	$n_{1D}$	$\log_{10} \epsilon$						
		-3	-2	-1	0	1	2	3
99	9	2.655	2.969	4.786	6.979	7.328	7.357	7.360
323	17	2.698	3.323	5.966	7.597	7.697	7.715	7.717
1155	33	2.778	3.905	7.031	7.882	7.818	7.816	7.816
4355	65	2.932	4.769	7.830	8.016	7.855	7.843	7.843
16899	129	3.217	5.857	8.343	8.081	7.868	7.854	7.852
66563	257	3.710	6.964	8.637	8.113	7.872	7.856	7.855

Kuchta, Miroslav, et al. "Preconditioners for saddle point systems with trace constraints coupling 2d and 1d domains."  
SIAM Journal on Scientific Computing 38.6 (2016):

# 3D-1D problem



The original problem was

$$\mathcal{A} = \begin{bmatrix} -\Delta_{\Omega} & 0 & \epsilon T^* \\ 0 & -\Delta_{\Gamma} & I \\ \epsilon T & I & 0 \end{bmatrix} \begin{bmatrix} u \\ v \\ p \end{bmatrix} = \begin{bmatrix} f \\ g \\ 0 \end{bmatrix}$$

an appropriate preconditioner would then be

$$\mathcal{B} = \begin{bmatrix} -\Delta_{\Omega} & 0 & 0 \\ 0 & -\Delta_{\Gamma} & 0 \\ 0 & 0 & \epsilon^2(-\Delta_{\Gamma}^{-0.14}) + -\Delta_{\Gamma}^{-1} \end{bmatrix}^{-1}$$

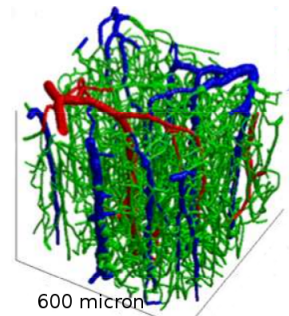
- ▶ Robust preconditioner requires parameter-dependent spaces

$$V_1 = H_0^1(\Omega), V_2 = H_0^1(\Gamma), Q = \frac{1}{\epsilon} H^{-0.14}(\Gamma) \cap H^{-1}(\Gamma)$$

Kuchta, M., Mardal, K.A., & Mortensen, M. (2019). Preconditioning trace coupled 3d-1d systems using fractional Laplacian.

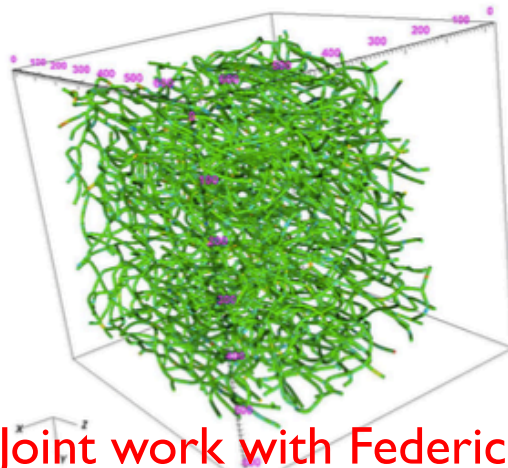
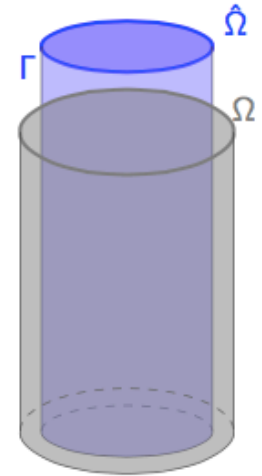
Numerical Methods for Partial Differential Equations, 35(1)

# Simple multiscale 3d-1d models of viscous – porous coupling



Vasculature resolved as a three-dimensional structure

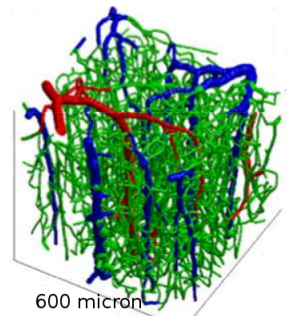
$$\begin{aligned} -\nabla \cdot (\kappa \nabla u) &= f && \text{in } \Omega, \\ -\nabla \cdot (\hat{\kappa} \nabla \hat{u}) &= \hat{f} && \text{in } \hat{\Omega}, \\ u - \hat{u} &= g && \text{on } \Gamma, \\ \kappa \nabla u \cdot n - \hat{\kappa} \nabla \hat{u} \cdot n &= h && \text{on } \Gamma. \end{aligned}$$



*Impractical for real geometries*

Joint work with Federica Laurino, Miroslav Kuchta and Paolo Zunino

# Multiscale 3d-1d model by dimensional reduction



Current models lead non-typical elliptic operators

$$(\Pi_R u)(y) = (2\pi R)^{-1} \int_{C_R(y)} u \circ C_R dl, R \ll \text{diam}(\Omega)$$

- D'Angelo, Quarteroni: asymmetric continuous problem  
 $\mathcal{A} : V \mapsto \hat{V}'$

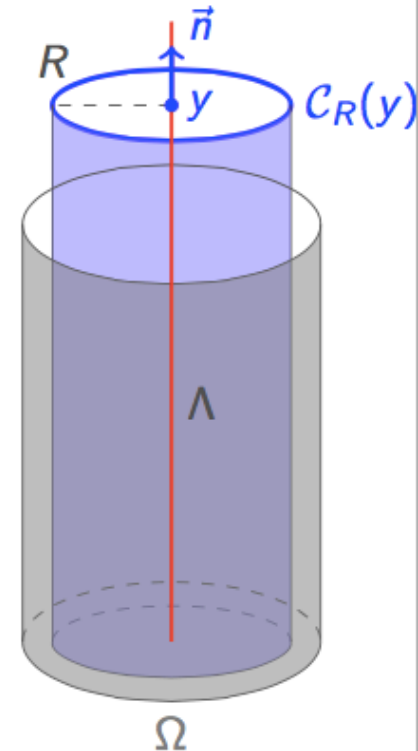
$$\mathcal{A} = \begin{pmatrix} -\kappa \Delta_\Omega & -T' \\ -\beta \Pi_R & -R^2 \hat{\kappa} \Delta_\Lambda \end{pmatrix}$$

with  $V = H_\alpha^1(\Omega) \times H^1(\Gamma)$ ,  $\hat{V} = H_{-\alpha}^1(\Omega) \times H^1(\Gamma)$

- Cerroni, Laurino, Zunnino: symmetric problem  
 $\mathcal{A} : V \mapsto V'$

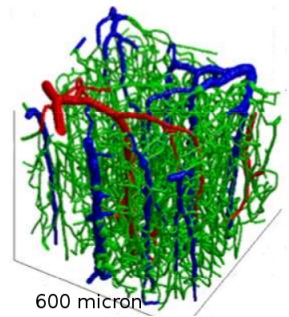
$$\mathcal{A} = \begin{pmatrix} -\kappa \Delta_\Omega + \Pi_{R'} \Pi_R & -\beta \Pi_{R'} \\ -\Pi_R & -R^2 \hat{\kappa} \Delta_\Lambda \end{pmatrix}$$

with  $V = H^1(\Omega) \times H^1(\Gamma)$



*Can we use common black-box preconditioners?*

# Lagrange multiplier 3d-1d formulation



Offers possibly more flexible coupling

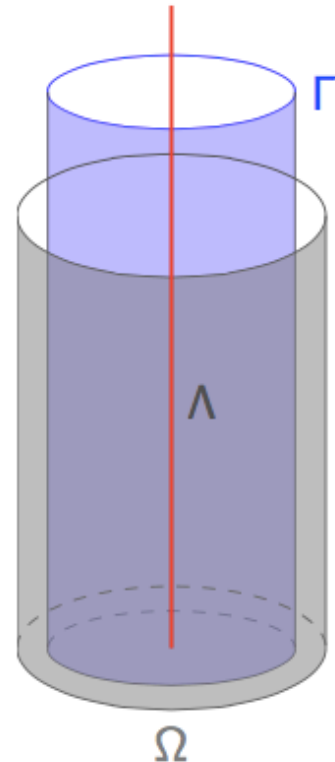
Consider  $\mathcal{A} : H^1(\Omega) \times H^1(\Lambda) \times Q$

$$\mathcal{A} = \begin{pmatrix} -\kappa\Delta_{\Omega} & & \Pi' \\ & -R^2\hat{\kappa}\Delta_{\Lambda} & -\hat{\Pi}' \\ \Pi & & -\hat{\Pi} \end{pmatrix}$$

Two options for the Lagrange multiplier space

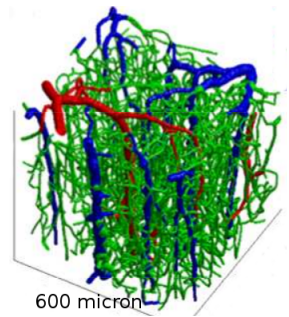
- ▶  $Q$  defined on  $\Lambda$
- ▶  $Q$  defined in *virtual* coupling surface  $\Gamma$

*We wish to construct block-diagonal preconditioners*



# Formulation with line multiplier, conforming PI

Riesz map preconditioner I



$$\mathcal{B} = \begin{pmatrix} -\Delta_\Omega & & \\ & -R^2\Delta_\Lambda & \\ & & (-\Delta_\Gamma)^{-1/2} \end{pmatrix}^{-1}$$

$h$	$2^{-2}$	$2^{-3}$	$2^{-4}$	$2^{-5}$
$\text{cond}(\mathcal{B}\mathcal{A})$	40.5	40.6	40.6	40.6

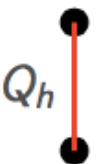
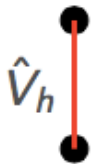
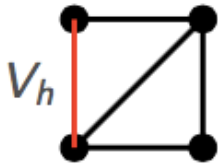
Schur complement of  $\mathcal{A}$  is  $R$  dependent,  $\Pi = \Pi_R$ ,  $\hat{\Pi} = I$

$$R^2(\Pi)(-\Delta_\Omega)^{-1}(\Pi)' + (\hat{\Pi})(-\Delta_\Lambda)^{-1}(\hat{\Pi})'$$

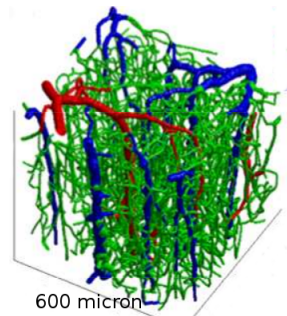
$R$ -robust preconditioner

$$\mathcal{B} = \begin{pmatrix} -\Delta_\Omega & & \\ & -R^2\Delta_\Lambda & \\ & & R^2(-\Delta_\Gamma)^{-1/2} + (-\Delta_\Gamma)^{-1} \end{pmatrix}^{-1}$$

$\alpha$	$h$			
	$2^{-2}$	$2^{-3}$	$2^{-4}$	$2^{-5}$
$10^{-1}$	4.5162	4.5201	4.5608	4.6189
$10^{-2}$	4.5314	4.5366	4.5574	4.6137
$10^{-3}$	4.5311	4.5312	4.5315	4.5328

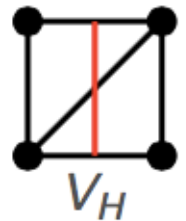


# Nonconforming line multiplier, PI-PI-P0 elements



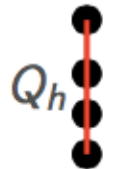
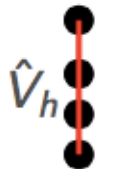
Stabilized FEM formulation

$$\mathcal{A} = \begin{pmatrix} -\kappa \Delta_{\Omega} & & \Pi' \\ \Pi & -R^2 \hat{\kappa} \Delta_{\Lambda} & -\hat{\Pi}' \\ & -\hat{\Pi} & -h^3 \Delta_{\Gamma, h} \end{pmatrix} \langle p, -\Delta_{\Gamma, h} q \rangle = \sum \{ \{h\} \}^{-1} [p][q]$$



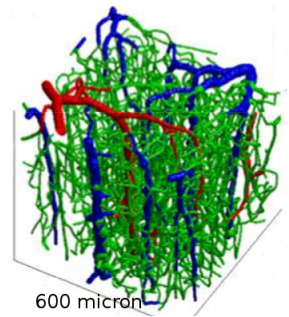
Conforming-case preconditioner with stabilization term

$\alpha$	$h$			
	$2^{-2}$	$2^{-3}$	$2^{-4}$	$2^{-5}$
$10^{-1}$	4.5316	4.5319	4.5289	4.5506
$10^{-2}$	4.5412	4.5399	4.5364	4.5337
$10^{-3}$	4.5413	4.5310	4.5364	4.5439





# Formulation with surface multiplier, conforming PI



Coupling via

- ▶  $\Pi = T$  (standard 3d-2d trace)
- ▶  $\hat{\Pi}$  extension operator  $\Lambda \rightarrow \Gamma$

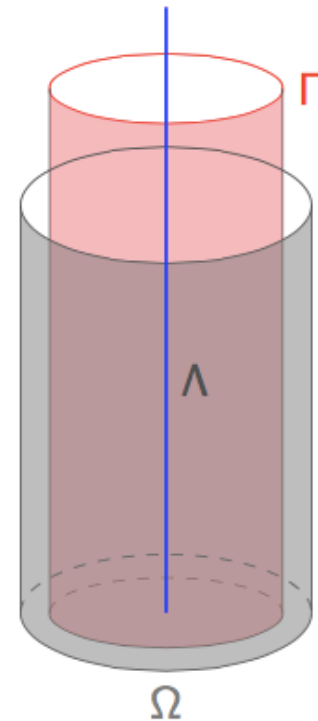
Riesz map preconditioner |

$$\mathcal{B} = \begin{pmatrix} -\Delta_{\Omega} & & \\ & -R^2 \Delta_{\Lambda} & \\ & & (-\Delta_{\Gamma})^{-1/2} \end{pmatrix}^{-1}$$

At the moment only  $h$ -robust

$h$	$2^{-2}$	$2^{-3}$	$2^{-4}$	$2^{-5}$
$\text{cond}(\mathcal{B}\mathcal{A})$	27.4	27.5	27.6	27.6

*Fractional preconditioner computationally expensive*



# Conclusion

- Alzheimer's disease and the glymphatic system are in need of new modeling
- Waste clearance, porous media flow seems a powerful framework
- Numbers don't add up, permeability and fluid velocities seem to low: A lot of open questions!
- Multiscale (3D-1D) and multi-physics approach is warranted
- Operator preconditioning is a powerful way of unraveling the underlying structures and create efficient algorithms

# Further readings, acknowledgement

*Trygve Bærland*

**Miro Kuchta**

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**Lars Magnus Valnes**

**Per Kristian Eide**

**Federica Laurino**

**Geir Ringstad**

*Vegard Vinje*

**Karl Erik Holter**

*John Lee*

**Paolo Zunino**

*Ragnar Winther*

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