Serendipity discrete de Rham method

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ICOSAHOM 2023, Yonsei University, Seoul, Korea 16 August 2023

(joint work with D. Di Pietro [mostly])

1 Motivation for continuous and discrete complexes

2 Finite Elements approach, and its limitations

3 Overview of the Discrete De Rham complexes

- Principles guiding arbitrary-order polytopal complexes
- DDR regular version
- DDR serendipity version

4 Numerical illustration

The Stokes problem in curl-curl formulation

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Given Ω contractible, $\nu > 0$ and $f \in L^2(\Omega)$, the Stokes problem reads: Find the velocity $u : \Omega \to \mathbb{R}^3$ and pressure $p : \Omega \to \mathbb{R}$ s.t.

$$\frac{\nabla (\operatorname{curl}\operatorname{curl} u - \operatorname{grad}\operatorname{div} u)}{\operatorname{v}(\operatorname{curl}\operatorname{curl} u - \operatorname{grad}\operatorname{div} u)} + \operatorname{grad} p = f \quad \text{in } \Omega, \quad (\text{momentum conservation}) \\ \operatorname{div} u = 0 \quad \text{in } \Omega, \quad (\text{mass conservation}) \\ \operatorname{curl} u \times n = 0 \text{ and } u \cdot n = 0 \quad \text{on } \partial\Omega, \quad (\text{boundary conditions}) \\ \int_{\Omega} p = 0$$

• Weak formulation: Find $(u, p) \in H(\operatorname{curl}; \Omega) \times H^1(\Omega)$ s.t. $\int_{\Omega} p = 0$ and

$$\begin{split} \int_{\Omega} \boldsymbol{\nu} \operatorname{curl} \boldsymbol{u} \cdot \operatorname{curl} \boldsymbol{\nu} + \int_{\Omega} \operatorname{grad} p \cdot \boldsymbol{\nu} &= \int_{\Omega} \boldsymbol{f} \cdot \boldsymbol{\nu} \quad \forall \boldsymbol{\nu} \in \boldsymbol{H}(\operatorname{curl}; \Omega), \\ &- \int_{\Omega} \boldsymbol{u} \cdot \operatorname{grad} q = 0 \qquad \quad \forall q \in H^{1}(\Omega) \end{split}$$

The Stokes problem in curl-curl formulation

• Given Ω contractible, $\nu > 0$ and $f \in L^2(\Omega)$, the Stokes problem reads: Find the velocity $u : \Omega \to \mathbb{R}^3$ and pressure $p : \Omega \to \mathbb{R}$ s.t.

 $\overline{v(\operatorname{curl}\operatorname{curl} u - \operatorname{grad}\operatorname{div} u)} + \operatorname{grad} p = f \quad \text{in } \Omega, \quad (\text{momentum conservation})$ $\operatorname{div} u = 0 \quad \text{in } \Omega, \quad (\text{mass conservation})$ $\operatorname{curl} u \times n = 0 \text{ and } u \cdot n = 0 \quad \text{on } \partial\Omega, \quad (\text{boundary conditions})$ $\int_{\Omega} p = 0$

• Weak formulation: Find $(u, p) \in H(\operatorname{curl}; \Omega) \times H^1(\Omega)$ s.t. $\int_{\Omega} p = 0$ and

$$\underbrace{\int_{\Omega} v \operatorname{curl} u \cdot \operatorname{curl} v}_{+ \int_{\Omega} \operatorname{grad} p \cdot v = \int_{\Omega} f \cdot v \quad \forall v \in H(\operatorname{curl}; \Omega),$$

controls curl u only ...

 $-\nu\Delta u$

$$-\int_{\Omega} \boldsymbol{u} \cdot \operatorname{\mathbf{grad}} q = 0 \qquad \quad \forall q \in H^1(\Omega)$$

The Stokes problem in curl-curl formulation

• Given Ω contractible, $\nu > 0$ and $f \in L^2(\Omega)$, the Stokes problem reads: Find the velocity $\boldsymbol{u} : \Omega \to \mathbb{R}^3$ and pressure $p : \Omega \to \mathbb{R}$ s.t.

$$\frac{-\nu\Delta u}{\nu(\operatorname{curl}\operatorname{curl} u - \operatorname{grad}\operatorname{div} u) + \operatorname{grad} p} = f \quad \text{in } \Omega, \quad (\text{momentum conservation}) \\ \operatorname{div} u = 0 \quad \text{in } \Omega, \quad (\text{mass conservation}) \\ \operatorname{curl} u \times n = 0 \text{ and } u \cdot n = 0 \quad \text{on } \partial\Omega, \quad (\text{boundary conditions}) \\ \int_{\Omega} p = 0$$

$$Weak \text{ formulation:} \quad \operatorname{Find}(u, p) \in H(\operatorname{curl}; \Omega) \times H^1(\Omega) \text{ s.t. } \int_{\Omega} p = 0 \\ \operatorname{and} \quad \underbrace{\int_{\Omega} \nu \operatorname{curl} u \cdot \operatorname{curl} v}_{\text{controls curl} u} + \int_{\Omega} \operatorname{grad} p \cdot v = \int_{\Omega} f \cdot v \quad \forall v \in H(\operatorname{curl}; \Omega), \\ \operatorname{controls curl} u \text{ only...} \quad u \perp \operatorname{grad} H^1(\Omega)$$

De Rham complex

The de Rham sequence is

$$\mathbb{R} \xrightarrow{i_{\Omega}} H^{1}(\Omega) \xrightarrow{\operatorname{grad}} H(\operatorname{curl}; \Omega) \xrightarrow{\operatorname{curl}} H(\operatorname{div}; \Omega) \xrightarrow{\operatorname{div}} L^{2}(\Omega) \xrightarrow{0} \{0\}$$

- It is a complex: the range of each operator is included in the kernel of the next one (*i.e.* $\operatorname{grad} i_{\Omega} = 0$, $\operatorname{curl} \operatorname{grad} = 0$, $\operatorname{div} \operatorname{curl} = 0$).
- It is exact (inclusions \rightsquigarrow equalities) if Ω has a trivial topology:

 $\mathbb{R} = \ker \operatorname{\mathbf{grad}}, \ \operatorname{Im} \operatorname{\mathbf{grad}} = \ker \operatorname{\mathbf{curl}}, \ \operatorname{Im} \operatorname{\mathbf{curl}} = \ker \operatorname{div}, \ \operatorname{Im} \operatorname{div} = L^2(\Omega).$

De Rham complex

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$$\mathbb{R} \xrightarrow{i_{\Omega}} H^{1}(\Omega) \xrightarrow{\operatorname{grad}} H(\operatorname{curl}; \Omega) \xrightarrow{\operatorname{curl}} H(\operatorname{div}; \Omega) \xrightarrow{\operatorname{div}} L^{2}(\Omega) \xrightarrow{0} \{0\}$$

- It is a complex: the range of each operator is included in the kernel of the next one (*i.e.* grad $i_{\Omega} = 0$, curl grad = 0, div curl = 0).
- It is exact (inclusions \rightsquigarrow equalities) if Ω has a trivial topology:

 $\mathbb{R} = \ker \operatorname{\mathbf{grad}}, \ \overline{\operatorname{Im} \operatorname{\mathbf{grad}}} = \ker \operatorname{\mathbf{curl}}, \ \operatorname{Im} \operatorname{\mathbf{curl}} = \ker \operatorname{div}, \ \operatorname{Im} \operatorname{div} = L^2(\Omega).$

• Exactness \Rightarrow well-posedness of the Stokes problem in curl-curl form (same for the Stokes problem in Δ form...).

Reproducing this exactness at the discrete level is instrumental to designing stable numerical approximations.

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The Finite Element way

Global complex



 $\mathcal{T}_h = \{T\}$ conforming tetrahedral/hexahedral mesh of Ω .

Define local polynomial spaces on each element, and glue them together to form a sub-complex of the de Rham complex:

- Example: conforming *P^k*-Nédélec-Raviart-Thomas spaces (see [Arnold, 2018] for a generic approach).
- Gluing only works on special meshes!

The Finite Element way

Shortcomings



- Approach limited to conforming meshes with standard elements
 - \implies local refinement requires to trade mesh size for mesh quality
 - ⇒ complex geometries may require a large number of elements
 - \implies the element shape cannot be adapted to the solution
- Need for (global) basis functions
 - \implies significant increase of DOFs on hexahedral elements

Polytopal meshes I



- Local refinement (to capture geometry or solution features) is seamless, and can preserve mesh regularity.
- Agglomerated elements are also easy to handle (and useful, e.g., in multi-grid methods).
- High-level approach can lead to leaner methods (fewer DOFs).

Polytopal meshes II

Example of efficiency: Reissner-Mindlin plate problem.



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Key ideas for a discrete complex

- Finite-dimensional spaces of vectors made of polynomials on relevant mesh entities: vertices, edges, faces, elements.
- Interpolators give meaning to these polynomials/DOFs.
- **Bespoke operators between the spaces, that represent grad, curl**, div.

$$(\mathsf{PC}): \mathbb{R} \longrightarrow \underline{X}_{\mathsf{grad},h}^{k} \xrightarrow{\operatorname{grad}_{h}^{k}} \underline{X}_{\mathsf{curl},h}^{k} \xrightarrow{\operatorname{curl}_{h}^{k}} \underline{X}_{\mathrm{div},h}^{k} \xrightarrow{\operatorname{div}_{h}^{k}} X_{h,L^{2}}^{k} \xrightarrow{0} \{0\}$$

$$\xrightarrow{I_{\mathsf{grad},h}^{k}} \underbrace{I_{\mathsf{curl},h}^{k}}_{\mathsf{curl},h}^{k} \xrightarrow{I_{\mathrm{div},h}^{k}} H_{L^{2},h}^{k} \xrightarrow{0} \{0\}$$

$$(\mathsf{dR}): \mathbb{R} \longleftrightarrow H^{1}(\Omega) \xrightarrow{\operatorname{grad}} H(\mathsf{curl};\Omega) \xrightarrow{\operatorname{curl}} H(\operatorname{div};\Omega) \xrightarrow{\operatorname{div}} L^{2}(\Omega) \xrightarrow{0} \{0\}$$

Note: interpolators are actually well-defined on smaller (more regular) subspaces.

Key ideas for a discrete complex



Main properties:

- Cohomology of (PC) ~ cohomology of (dR), on generic topologies [Di Pietro et al., 2022].
- Local polynomial consistency: for $\mathcal{D} \in \{ \text{grad}, \text{curl}, \text{div} \}$ and $T \in \mathcal{T}_h$, there is $P_{\mathcal{D},T}^k : \underline{X}_{\mathcal{D},T}^k \to \mathcal{P}^k(T)$ s.t.

$$\boldsymbol{P}^{k}_{\mathcal{D},T}\underline{I}^{k}_{\mathcal{D},T}\omega = \omega, \quad \mathcal{D}^{k}_{T}\underline{I}^{k}_{\mathcal{D},T}\omega = \mathcal{D}\omega \qquad \forall \omega \in \mathcal{P}^{k}(T).$$

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Degrees of freedom and interpolator

 Degrees of freedom: (trimmed) polynomials on vertices, edges, faces, elements.

Space	V	E	F	Т
$\underline{X}_{\mathrm{grad},T}^k$	R	$\mathcal{P}^{k-1}(E)$	$\mathcal{P}^{k-1}(F)$	$\mathcal{P}^{k-1}(T)$
$\underline{X}_{\operatorname{curl},T}^k$		$\mathcal{P}^k(E)$	$\mathcal{R}^{k-1}(F) \oplus \mathcal{R}^{\mathrm{c},k}(F)$	$\mathcal{R}^{k-1}(T) \oplus \mathcal{R}^{\mathrm{c},k}(T)$
$\underline{X}^k_{\mathrm{div},T}$			$\mathcal{P}^k(F)$	$\boldsymbol{\mathcal{G}}^{k-1}(T) \oplus \boldsymbol{\mathcal{G}}^{\mathrm{c},k}(T)$
$\mathcal{P}^k(T)$				$\mathcal{P}^k(T)$

 $\begin{aligned} & \mathcal{R}^{k-1}(\mathsf{P}) = \operatorname{curl} \mathcal{P}^{k}(\mathsf{P}), \quad \mathcal{R}^{\mathsf{c},k}(\mathsf{P}) = (\boldsymbol{x} - \boldsymbol{x}_{T})\mathcal{P}^{k-1}(\mathsf{P}) \quad (\mathsf{P} = F, T) \\ & \boldsymbol{\mathcal{G}}^{k-1}(T) = \operatorname{grad} \mathcal{P}^{k}(T), \quad \boldsymbol{\mathcal{G}}^{\mathsf{c},k}(T) = (\boldsymbol{x} - \boldsymbol{x}_{T}) \times \mathcal{P}^{k-1}(T). \end{aligned}$

Degrees of freedom and interpolator

 Degrees of freedom: (trimmed) polynomials on vertices, edges, faces, elements.

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$\underline{X}^k_{\mathrm{grad},T}$	R	$\mathcal{P}^{k-1}(E)$	$\mathcal{P}^{k-1}(F)$	$\mathcal{P}^{k-1}(T)$
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$\underline{X}^k_{\mathrm{div},T}$			$\mathcal{P}^k(F)$	$\boldsymbol{\mathcal{G}}^{k-1}(T) \oplus \boldsymbol{\mathcal{G}}^{\mathrm{c},k}(T)$
$\mathcal{P}^k(T)$				$\mathcal{P}^k(T)$

■ Interpolators: L²-projections of (traces) of functions. E.g.:

$$\forall \boldsymbol{\nu} \in C^{0}(\overline{\Omega})^{3}, \quad \underline{I}_{\operatorname{curl},h}^{k} \boldsymbol{\nu} = ((\pi_{\mathcal{P},E}^{k}(\boldsymbol{\nu} \cdot \boldsymbol{t}_{E}))_{E \in \mathcal{E}_{h}}, \\ (\pi_{\mathcal{R},F}^{k-1}(\boldsymbol{\nu}_{t,F}), \pi_{\mathcal{R},F}^{c,k}(\boldsymbol{\nu}_{t,F}))_{F \in \mathcal{T}_{h}}, \\ (\pi_{\mathcal{R},T}^{k-1}\boldsymbol{\nu}, \pi_{\mathcal{R},T}^{c,k}\boldsymbol{\nu})_{T \in \mathcal{T}_{h}}).$$

Potential reconstructions and discrete operators

- Hierarchical constructions: from lowest-dimensional mesh entity to higher-dimensional entities.
- Enhancement: Discrete operator first (based on IBP, polynomially consistent), then used for potential reconstruction (also based on IBP, and also polynomially consistent).

Potential reconstructions and discrete operators

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- Enhancement: Discrete operator first (based on IBP, polynomially consistent), then used for potential reconstruction (also based on IBP, and also polynomially consistent).

Example with curl:

• Face curl: $C_F^k \underline{\nu}_F \in \mathcal{P}^k(F)$ such that

$$\int_F C_F^k \underline{\boldsymbol{v}}_F \ \boldsymbol{r}_F = \int_F \boldsymbol{v}_{\mathcal{R},F} \cdot \operatorname{rot}_F \boldsymbol{r}_F - \sum_{E \in \mathcal{E}_F} \omega_{FE} \int_E \boldsymbol{v}_E \boldsymbol{r}_F \qquad \forall \boldsymbol{r}_F \in \mathcal{P}^k(F).$$

• Tangential trace reconstruction: $\gamma^k_{t,F} \underline{\nu}_F \in \mathcal{P}^k(F)$ such that

$$\begin{split} \int_{F} \boldsymbol{\gamma}_{t,F}^{k} \underline{\boldsymbol{\nu}}_{F} \cdot (\mathbf{rot}_{F} \boldsymbol{r}_{F} + \boldsymbol{w}_{F}) &= \int_{F} C_{F}^{k} \underline{\boldsymbol{\nu}}_{F} \boldsymbol{r}_{F} + \sum_{E \in \mathcal{E}_{F}} \omega_{FE} \int_{E} \boldsymbol{\nu}_{E} \boldsymbol{r}_{F} + \int_{F} \boldsymbol{\nu}_{\mathcal{R},F}^{c} \cdot \boldsymbol{w}_{F} \\ \forall (\boldsymbol{r}_{F}, \boldsymbol{w}_{F}) \in \mathcal{P}^{0,k+1}(F) \times \mathcal{R}^{c,k}(F). \end{split}$$

DDR complex

Patch local spaces (no continuity between elements), project local (polynomial) operators on DOFs:

$$(\mathsf{DDR}): \mathbb{R} \longrightarrow \underline{X}_{\mathsf{grad},h}^{k} \xrightarrow{\underline{G}_{h}^{k}} \underline{X}_{\mathsf{curl},h}^{k} \xrightarrow{\underline{C}_{h}^{k}} \underline{X}_{\mathrm{div},h}^{k} \xrightarrow{D_{h}^{k}} \mathcal{P}^{k}(\mathcal{T}_{h}) \xrightarrow{0} \{0\}$$

$$\stackrel{I_{\mathsf{grad},h}^{k}}{\stackrel{I_{\mathsf{curl},h}^{k}}{\stackrel{I_{\mathsf{curl},h}^{k}}{\stackrel{I_{\mathsf{curl},h}^{k}}{\stackrel{I_{\mathsf{curl},h}^{k}}{\stackrel{I_{\mathsf{div},h}^{k}}{\stackrel{I_{\mathsf{div},h}^{k}}{\stackrel{I_{\mathsf{div},h}^{k}}{\stackrel{I_{\mathsf{curl},h}^{k}}{\stackrel{I_{\mathsf{curl},h}^{k}}{\stackrel{I_{\mathsf{curl},h}^{k}}{\stackrel{I_{\mathsf{div},h}^{k}}{\stackrel{I_{\mathsf{curl},h}}{\stackrel{I_{\mathsf{curl},h}}{\stackrel{$$

Properties for the design and analysis of stable numerical schemes:

- Cohomology and polynomial consistency.
- Analytical properties: Poincaré inequalities, primal and adjoint consistency, commutation properties of interpolators and differential operators, etc.

DDR scheme for Stokes in curl-curl formulation

• Weak formulation: Find $(\boldsymbol{u}, p) \in \boldsymbol{H}(\operatorname{curl}; \Omega) \times H^1(\Omega)$ s.t. $\int_{\Omega} p = 0$ and

$$\int_{\Omega} v \operatorname{curl} \boldsymbol{u} \cdot \operatorname{curl} \boldsymbol{v} + \int_{\Omega} \operatorname{grad} p \cdot \boldsymbol{v} = \int_{\Omega} \boldsymbol{f} \cdot \boldsymbol{v} \quad \forall \boldsymbol{v} \in \boldsymbol{H}(\operatorname{curl}; \Omega),$$
$$- \int_{\Omega} \boldsymbol{u} \cdot \operatorname{grad} q = 0 \qquad \quad \forall q \in H^{1}(\Omega)$$

Set

$$\underline{X}^k_{\operatorname{grad},h,0} \coloneqq \left\{ \underline{q}_h \in \underline{X}^k_{\operatorname{grad},h} \ \colon \ (\underline{q}_h, \underline{I}^k_{\operatorname{grad},h}1)_{\operatorname{grad},h} = 0 \right\}.$$

DDR scheme: Find $\underline{u}_h \in \underline{X}_{\operatorname{curl},h}^k$ and $\underline{p}_h \in \underline{X}_{\operatorname{grad},h,0}^k$ such that

$$\begin{split} \nu(\underline{C}_{h}^{k}\underline{u}_{h},\underline{C}_{h}^{k}\underline{v}_{h})_{\mathrm{div},h} + (\underline{G}_{h}^{k}\underline{p}_{h},\underline{v}_{h})_{\mathrm{curl},h} &= (\underline{I}_{\mathrm{curl},h}^{k}f,\underline{v}_{h})_{\mathrm{curl},h} \quad \forall \underline{v}_{h} \in \underline{X}_{\mathrm{curl},h}^{k}, \\ &- (\underline{G}_{h}^{k}\underline{q}_{h},\underline{u}_{h})_{\mathrm{curl},h} = 0 \qquad \qquad \forall \underline{q}_{h} \in \underline{X}_{\mathrm{grad},h,0}^{k}. \end{split}$$

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Lemma

Let $k \ge 0$, take T a polyhedron with η_T faces that are not pairwise parallel, and set $\ell_T = k + 1 - \eta_T$. Any $q \in \mathcal{P}^{k+1}(T)$ is entirely determined by $(q_{|F})_{F \in \mathcal{F}_T}$ and $\pi_{\mathcal{P},T}^{\ell_T} q$, and $\|q\|_{L^2(T)} \le \|\pi_{\mathcal{P},T}^{\ell_T} q\|_{L^2(T)} + h_T^{\frac{1}{2}} \sum_{F \in \mathcal{F}_T} \|q_{|F}\|_{L^2(F)}.$

- If $\eta_T > k + 1$, then $\pi_{\mathcal{P},T}^{\ell_T} q = 0$ (only face values are required).
- Also works with $T \rightsquigarrow F$ polygon.

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- If $\eta_T > k + 1$, then $\pi_{\mathcal{P},T}^{\ell_T} q = 0$ (only face values are required).
- Also works with $T \rightsquigarrow F$ polygon.
- DDR spaces already fully encode traces on faces/elements boundaries
 >> polynomial consistency should not require that much information *inside* the faces/elements.

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Space	V	Ε	F	Т
$\frac{\underline{X}_{\text{grad},T}^{k}}{\underline{X}_{\text{curl},T}^{k}}$	R	$\mathcal{P}^{k-1}(E)$ $\mathcal{P}^k(E)$	$\mathcal{P}^{k-1}(F)$ $\mathcal{R}^{k-1}(F) \oplus \mathcal{R}^{\mathrm{c},k}(F)$	$\mathcal{P}^{k-1}(T)$ $\mathcal{R}^{k-1}(T) \oplus \mathcal{R}^{c,k}(T)$
$\frac{\underline{X}_{\mathrm{div},T}^{k}}{\mathcal{P}^{k}(T)}$			$\mathcal{P}^k(F)$	$\mathcal{G}^{k-1}(T) \oplus \mathcal{G}^{c,k}(T)$ $\mathcal{P}^{k}(T)$

Space	V	E F		Т
$\underline{\widehat{X}}_{\text{grad},T}^k$	R	$\mathcal{P}^{k-1}(E)$	$\mathcal{P}^{\boldsymbol{\ell_F}}(F)$	$\mathcal{P}^{\ell_T}(T)$
$\underline{\widehat{X}}_{\operatorname{curl},T}^{k}$		$\mathcal{P}^k(E)$	$\mathcal{R}^{k-1}(F) \oplus \mathcal{R}^{\mathrm{c},\ell_F+1}(F)$	$\mathcal{R}^{k-1}(T) \oplus \mathcal{R}^{\mathrm{c},\ell_T+1}(T)$
$\underline{X}_{\mathrm{div},T}^k$			$\mathcal{P}^k(F)$	$\boldsymbol{\mathcal{G}}^{k-1}(T) \oplus \boldsymbol{\mathcal{G}}^{\mathrm{c},k}(T)$
$\mathcal{P}^k(T)$				$\mathcal{P}^k(T)$

• Note that $\ell_F < k - 1$ and $\ell_T < k - 1$.

Space	V	Ε	F	Т
$\underline{\widehat{X}}_{\mathrm{grad},T}^k$	R	$\mathcal{P}^{k-1}(E)$	$\mathcal{P}^{\ell_{F}}(F)$	$\mathcal{P}^{\ell_T}(T)$
$\underline{\widehat{X}}_{\operatorname{curl},T}^{k}$		$\mathcal{P}^k(E)$	$\mathcal{R}^{k-1}(F) \oplus \mathcal{R}^{\mathrm{c}, \ell_F+1}(F)$	$\mathcal{R}^{k-1}(T) \oplus \mathcal{R}^{\mathrm{c},\ell_T+1}(T)$
$\underline{X}_{\mathrm{div},T}^k$			$\mathcal{P}^k(F)$	$\boldsymbol{\mathcal{G}}^{k-1}(T) \oplus \boldsymbol{\mathcal{G}}^{\mathrm{c},k}(T)$
$\mathcal{P}^k(T)$				$\mathcal{P}^k(T)$

• Note that $\ell_F < k - 1$ and $\ell_T < k - 1$.

■ Why can't we reduce more (e.g. the *R*^{k-1} components, or <u>X</u>^k_{div,h})? Due to the constraints of preserving the complex properties...

DDR vs. SDDR vs. Raviart-Thomas-Nédélec

Discrete space	k = 0	k = 1	k = 2
$H^1(T)$	4	15	32
$\boldsymbol{H}(\mathbf{curl};T)$	6	28	65
$\boldsymbol{H}(\operatorname{div};T)$	4	18	44
$L^2(T)$	$1 \diamond 1 \diamond 1$	4	10

Table: Tetrahedron: dimensions of the local spaces in the DDR \diamond SDDR \diamond RTN.

Discrete space	k = 0	k = 1	k = 2
$H^1(T)$	8	27	54
$\boldsymbol{H}(\mathbf{curl};T)$	12 \propto 12 \propto 12	46	99
$\boldsymbol{H}(\operatorname{div};T)$	6	24	56
$L^2(T)$	$1 \diamond 1 \diamond 1$	4	10

Table: Hexahedron: dimensions of the local spaces in the DDR \diamond SDDR \diamond RTN.

SDDR complex

$$\mathbb{R} \longrightarrow \underline{\widehat{X}}_{\operatorname{grad},h}^{k} \xrightarrow{\underline{\widehat{G}}_{h}^{k}} \underline{\widehat{X}}_{\operatorname{curl},h}^{k} \xrightarrow{\underline{\widehat{C}}_{h}^{k}} \underline{X}_{\operatorname{div},h}^{k} \xrightarrow{D_{h}^{k}} \mathcal{P}^{k}(\mathcal{T}_{h}) \xrightarrow{0} \{0\}$$

 SDDR scheme: exactly as a DDR scheme, substituting spaces and operators with those above.

SDDR: analysis



Extensions and reduction link the two complexes.

SDDR: analysis



- Extensions and reduction link the two complexes.
- Designed to ensure transfer of homological and analytical properties: isomorphism of cohomologies, Poincaré inequalities, primal and adjoint consistency, etc.

SDDR: analysis



- Extensions and reduction link the two complexes.
- Designed to ensure transfer of homological and analytical properties: isomorphism of cohomologies, Poincaré inequalities, primal and adjoint consistency, etc.
- Generic blueprint that is applicable in many circumstances (e.g.: analysis of cohomology of various discrete complexes, etc.).

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Convergence of (S)DDR scheme for the Stokes problem in curl-curl formulation

Theorem (Pressure-robust estimates [Beirão da Veiga et al., 2022])

Setting the graph norms

$$\begin{split} \|\cdot\|_{\operatorname{curl},1,h}^2 &= \|\cdot\|_{\operatorname{curl},h}^2 + \|\underline{C}_h^k\cdot\|_{\operatorname{div},h}^2 \quad \text{on } \underline{X}_{\operatorname{curl},h}^k \,, \\ \|\cdot\|_{\operatorname{grad},1,h}^2 &= \|\cdot\|_{\operatorname{grad},h}^2 + \|\underline{C}_h^k\cdot\|_{\operatorname{curl},h} \quad \text{on } \underline{X}_{\operatorname{grad},h}^k, \end{split}$$

we have:

$$\|\underline{\boldsymbol{u}}_{h} - \underline{\boldsymbol{I}}_{\operatorname{curl},h}^{k} \boldsymbol{u}\|_{\operatorname{curl},1,h} + \|\underline{\boldsymbol{p}}_{h} - \underline{\boldsymbol{I}}_{\operatorname{grad},h}^{k} \boldsymbol{p}\|_{\operatorname{grad},1,h} \lesssim C_{1}(\boldsymbol{u})h^{k+1}.$$

with $C_1(\mathbf{u})$ depending \mathbf{u} and some of its derivatives, but not p.

Choice of discrete source term & commutation properties of DDR operators ensures pressure robustness...

Convergence test



Figure: Relative errors in discrete $H(\operatorname{curl}; \Omega) \times H^1(\Omega)$ norm vs. h: DDR (continuous lines) and SDDR (dashed lines).

Wall and CPU times on the finest meshes



Conclusion I

 DDR: discrete complex, of arbitrary degree of accuracy, applicable on polytopal meshes, yields stable schemes even for models with "incomplete" differential operators
 [Di Pietro et al., 2020][Di Pietro and Droniou, 2021a].

Other approach: virtual element complexes [Beirão da Veiga et al., 2018][Beirão da Veiga et al., 2022]

- Systematic serendipity reduction of number of DOFs (on any polytopal mesh) [Di Pietro and Droniou, 2022b].
- Leaner complexes than FE approches on certain meshes (*and fully compatible with FE complexes on hybrid meshes*).

 Full set of homological and analytical results: cohomology, Poincaré inequalities, primal and adjoint consistency, commutation properties, etc.

(Facilitated by a generic framework to transfer properties from one complex to another one.)

- Some other applications/complexes:
 - div-div plates complex and serendipity version
 [Di Pietro and Droniou, 2022a][Botti et al., 2023].
 - Magnetostatics equations [Di Pietro and Droniou, 2021b].
 - Yang-Mills equations [Droniou et al., 2023].
 - Stokes complex [Hanot, 2021].
 - Rot-rot complex [Di Pietro, 2023].

• Notes and series of introductory lectures to DDR:

https://math.unice.fr/~massonr/Cours-DDR/Cours-DDR.html



COURSE OF JEROME DRONIOU FROM MONASH UNIVERSITY, INVITED PROFESSOR AT UCA

- Introduction to Discrete De Rham complexes
 - Short description (in french)
 - Summary of notations and formulas
 - Part 1, first course: the de Rham complex and its usefulness in PDEs, 22/09/22 (video)
 - Part 1, second course: Low order case, 29/09/22 (video)
 - Part 1, third course: Design of the DDR complex in 2D, 07/10/22 (video)
 - Part 1, fourth course: Exactness of the DDR complex in 2D, 10/10/22 (video)
 - Part 2, fifth course: DDR in 3D, analysis tools, 17/11/22 (video)

Thank you!

References I



accepted for publication.

References II

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5 Extension: transferring homological and analytical properties between two complexes

Starting point: a complex with some analytical properties (including some polynomial consistency).



Objective: link a second complex, to ensure that homological and analytical properties are also satisfied by this second complex.



Homological properties



Theorem

If the extensions and reductions satisfy

$$\blacksquare \hat{R}_i E_i = \text{Id for all } i,$$

- $(E_{i+1}\hat{R}_{i+1} \operatorname{Id})(\ker d_{i+1}) \subset \operatorname{Im} d_i \text{ for all } i,$
- E and R are cochain maps (each one commutes with the differential operators),

then:

* the cohomologies of $(X_i, d_i)_i$ and $(\hat{X}_i, \hat{d}_i)_i$ are isomorphic.

Analytical properties I

Take $\mathcal{H}_i \supset \mathcal{P}^{k_i}$ (Sobolev-like space) and $(\cdot, \cdot)_i L^2$ -like inner products on the first complex.



Analytical properties II

Theorem

If the extensions and reductions satisfy

- $\hat{R}_i: X_i \to \hat{X}_i$ is continuous,
- (polynomial consistency) $E_i \hat{R}_i I_i = I_i$,
- $I_i : \mathcal{H}_i \to X_i$ is continuous,

then the following properties are transferred from $(X_i, d_i)_i$ to $(\hat{X}_i, \hat{d}_i)_i$:

- ★ Poincaré inequalities,
- ★ Consistency of the inner product (polynomial and in L²-like norm on H_i),
- ★ Consistency of potential reconstruction,

and, under cochain map property:

- ★ Commutation property and consistency of differential operators,
- * Adjoint consistency (controls error in discrete IBP).

- \blacksquare Construction of extensions and reductions for the SDDR complex \rightsquigarrow limits on reduction of number of DOFs.
- Gives all the properties required for analysis of schemes based on SDDR:
 - SDDR has the same cohomology as the de Rham complex.
 - SDDR satisfies all analytical properties: Poincaré inequalities, primal and adjoint consistency, commutation properties of interpolator and differential operators...