

Implementation of the $k - \omega$ SST model in Aironum

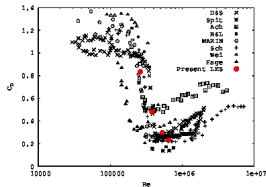
Stephen Wornom¹, Florian Miralles¹, Bruno Koobus¹, Alain Dervieux^{2,3}

¹ IMAG, Université de Montpellier, France,

² Société LEMMA, Sophia-Antipolis, France,

³ INRIA Sophia-Antipolis, France.

NORMA Progress meeting of April, 2023



(Drag crisis : Experimental data as of 2014)

Slide-0: $k-\omega$ SST model

The $k-\omega$ SST model

is a hybrid model obtained by blending the standard $k-\epsilon$ and $k-\omega$ models to eliminate the disadvantages of each model when applied separately, which are:

- $k-\epsilon$ model: poor performance with strong adverse pressure gradients.
- $k-\omega$ model: main disadvantage, sensitivity to the far-field BC on ω .

Pressure gradient	$k-\omega$	$k-\epsilon$
favorable	2.6%	7.2%
mild adverse	3.2%	27.2%
moderate adverse	5.9%	39.8%
strong adverse	2.4%	41.8%
all	3.5%	29.0%

Table 1: Wilcox(1998) Computed skin friction errors using the $k-\epsilon$ and $k-\omega$ models.

What are the standard $k-\epsilon$ and $k-\omega$ models?

We start by discussing the $k-\epsilon$ and the $k-\omega$ models, then the $k-\omega$ SST model.

Slide-1: k - ϵ model - early development

Is there a standard k - ϵ model? Not really, many contributors

Early contributors to the k - ϵ model - Wilcox(1998)

- Chou(1945)
- Davidov(1961)
- Harlow and Nakayama(1968)
- Jones and Launder(1972) (often referred to as the standard k - ϵ model)
- Launder and Sharma(1974) (strictly speaking, the standard k - ϵ model.)
 - 1) added viscous damping terms absent in the Jones and Launder model
 - 2) retuned model coefficients.

Slide-2: Standard k - ϵ model of Jones and Launder(1972)

Wilcox (1998, p 124) written in non-conservative variables k, ϵ

$$\begin{aligned}\frac{Dk}{Dt} &= \frac{\partial}{\partial x_j} \left[\left(\nu + \frac{\nu_t}{\sigma_k} \right) \frac{\partial k}{\partial x_j} \right] + P_k - \epsilon \\ \frac{D\epsilon}{Dt} &= \frac{\partial}{\partial x_j} \left[\left(\nu + \frac{\nu_t}{\sigma_\epsilon} \right) \frac{\partial \epsilon}{\partial x_j} \right] + C_{\epsilon 1} \frac{\epsilon}{k} P_k - C_{\epsilon 2} \frac{\epsilon^2}{k}\end{aligned}\quad (0)$$

where k = the turbulent kinetic energy

ϵ = the turbulence dissipation rate

P_k = the turbulence production term

ν_t = the turbulent eddy viscosity

$$P_k = \tau_{ij} \frac{\partial U_i}{\partial x_j}, \quad \nu_t = C_\mu \frac{k^2}{\epsilon}, \quad (1)$$

The constants C_μ , σ_k , σ_ϵ , $C_{\epsilon 1}$, and $C_{\epsilon 2}$ will be discussed later.

Slide-2 continued: Standard k - ϵ model of Jones and Launder(1972)

Closure Coefficients and Auxiliary Relations

$$C_{\epsilon 1} = 1.44, \quad C_{\epsilon 2} = 1.92, \quad C_{\mu} = 0.09, \quad \sigma_k = 1.0, \quad \sigma_{\epsilon} = 1.3$$

$$\omega = \epsilon / (C_{\mu} k) \quad \text{and} \quad l = C_{\mu} \frac{k^{3/2}}{\epsilon}$$

where k = the turbulent kinetic energy

ϵ = the turbulence dissipation rate

l = the turbulence length scale

ω = definition-1: the RMS fluctuation vorticity

ω = definition-2: simply the ratio ϵ/k

Slide-3: Standard k - ϵ model - conservative variables

Wilcox (1998) conservative variables $\rho k, \rho \epsilon$

$$\frac{D\rho k}{Dt} = \frac{\partial}{\partial x_j} \left[\left(\mu + \frac{\mu_t}{\sigma_k} \right) \frac{\partial k}{\partial x_j} \right] + P_k - \rho \epsilon$$

$$\frac{D\rho \epsilon}{Dt} = \frac{\partial}{\partial x_j} \left[\left(\mu + \frac{\mu_t}{\sigma_\epsilon} \right) \frac{\partial \epsilon}{\partial x_j} \right] + C_{\epsilon 1} \frac{\epsilon}{k} P_k - C_{\epsilon 2} \rho \frac{\epsilon^2}{k}$$

where

k = the turbulent kinetic energy

ϵ = the turbulence dissipation rate

P_k = the turbulence production term

ν_t = the turbulent eddy viscosity

$$P_k = \tau_{ij} \frac{\partial U_i}{\partial x_j}, \quad \nu_t = C_\mu \frac{k^2}{\epsilon} \quad (1)$$

Slide-4: Original k - ω model - Wilcox(1998)

Wilcox (1998) conservative variables $\rho k, \rho \omega$

$$\frac{D\rho k}{Dt} = P_k - \beta^* \rho \omega k + \frac{\partial}{\partial x_j} \left[\left(\mu + \sigma_{k1} \mu_t \right) \frac{\partial k}{\partial x_j} \right]$$
$$\frac{D\rho \omega}{Dt} = \frac{\gamma_1}{\nu_t} P_k - \beta_1 \rho \omega^2 + \frac{\partial}{\partial x_j} \left[\left(\mu + \sigma_{\omega 1} \mu_t \right) \frac{\partial \omega}{\partial x_j} \right]$$

where $\beta^* = 0.09$, $\beta_1 = 0.075$, $\nu_t = \mu_t / \rho$, and P_k the turbulence production term

$$P_k = \tau_{ij} \frac{\partial U_i}{\partial x_j} \quad (2)$$

IMPORTANT: Menter's notation will be used in the slides that follow. $\frac{\mu_t}{\sigma_{k1}}$
re-written as: $\sigma_{k1} \mu_t$, $\frac{\mu_t}{\sigma_{\omega 1}}$ re-written as: $\sigma_{\omega 1} \mu_t$.

Slide-5: Transformed k - ϵ model

Obtained by replacing ϵ in the standard k - ϵ model with

$$\epsilon = \beta^* k \omega, \quad \text{Wilcox(1988)} \quad (2)$$

and solving for $\frac{\partial \rho k}{\partial t}$ and $\frac{\partial \rho \omega}{\partial t}$ to obtain

$$\frac{D \rho k}{Dt} = P_k - \beta^* \rho \omega k + \frac{\partial}{\partial x_j} \left[\left(\mu + \sigma_{k2} \mu_t \right) \frac{\partial k}{\partial x_j} \right]$$

$$\frac{D \rho \omega}{Dt} = \frac{\gamma_2}{\nu_t} P_k - \beta_2 \rho \omega^2 + \frac{\partial}{\partial x_j} \left[\left(\mu + \sigma_{\omega 2} \mu_t \right) \frac{\partial \omega}{\partial x_j} \right] + 2 \rho \sigma_{\omega 2} \frac{1}{\omega} \frac{\partial k}{\partial x_j} \frac{\partial \omega}{\partial x_j}$$

Slide-6: Comparison of k - ω and transformed k - ϵ models

Standard k - ω model - Wilcox(1998)

$$\frac{D\rho k}{Dt} = P_k - \beta^* \rho \omega k + \frac{\partial}{\partial x_j} \left[\left(\mu + \sigma_{k1} \mu_t \right) \frac{\partial k}{\partial x_j} \right]$$

$$\frac{D\rho \omega}{Dt} = \frac{\gamma_1}{\nu_t} P_k - \beta_1 \rho \omega^2 + \frac{\partial}{\partial x_j} \left[\left(\mu + \sigma_{\omega 1} \mu_t \right) \frac{\partial \omega}{\partial x_j} \right]$$

Transformed k - ϵ model

$$\frac{D\rho k}{Dt} = P_k - \beta^* \rho \omega k + \frac{\partial}{\partial x_j} \left[\left(\mu + \sigma_{k2} \mu_t \right) \frac{\partial k}{\partial x_j} \right]$$

$$\frac{D\rho \omega}{Dt} = \frac{\gamma_2}{\nu_t} P_k - \beta_2 \rho \omega^2 + \frac{\partial}{\partial x_j} \left[\left(\mu + \sigma_{\omega 2} \mu_t \right) \frac{\partial \omega}{\partial x_j} \right] + \boxed{2\rho \sigma_{\omega 2} \frac{1}{\omega} \frac{\partial k}{\partial x_j} \frac{\partial \omega}{\partial x_j}}$$

Slide-7: The k - ω SST model

k - ω model SST model

$$\frac{D\rho k}{Dt} = P_k - \beta^* \rho \omega k + \frac{\partial}{\partial x_j} \left[\left(\mu + \sigma_k \mu_t \right) \frac{\partial k}{\partial x_j} \right]$$

$$\frac{D\rho\omega}{Dt} = \frac{\gamma}{\nu_t} P_k - \beta \rho \omega^2 + \frac{\partial}{\partial x_j} \left[\left(\mu + \sigma_\omega \mu_t \right) \frac{\partial \omega}{\partial x_j} \right] + \phi \boxed{2\rho\sigma_\omega \frac{1}{\omega} \frac{\partial k}{\partial x_j} \frac{\partial \omega}{\partial x_j}}$$

The blended constants in the SST model are obtained as follows:

$$\sigma_k = \phi \sigma_{k1} + (1 - \phi) \sigma_{k2}$$

$$\sigma_\omega = \phi \sigma_{\omega 1} + (1 - \phi) \sigma_{\omega 2}$$

$$\beta = \phi \beta_1 + (1 - \phi) \beta_2$$

$$\gamma = \beta / \beta^* - \sigma_\omega \kappa^2 / \sqrt{\beta^*}$$

where the subscripts 1,2 denote:

1= k - ω values and, 2= k - ϵ values and ϕ the blending function.

Slide-8: Blending function ϕ constants

Set 1 constants for $\sigma_k, \sigma_\omega, \beta$ ($k-\omega$ model):

$$\sigma_{k1} = 0.85, \quad \sigma_{\omega1} = 0.5, \quad \beta_1 = 0.0750,$$

Set 2 constants for $\sigma_k, \sigma_\omega, \beta$ ($k-\epsilon$ model):

$$\sigma_{k2} = 1.0, \quad \sigma_{\omega2} = 0.856, \quad \beta_2 = 0.0828,$$

The turbulent eddy viscosity viscosity ν_t :

$$\nu_t = \frac{a_1 k}{\max(a_1 \omega; \Omega F_2)}$$

where $a_1 = 0.31$, $\kappa = 0.41$, $\beta^* = 0.09$.

Slide-9: Blending function ϕ

Blending function ϕ (k - ω SST model):

The function ϕ is given by

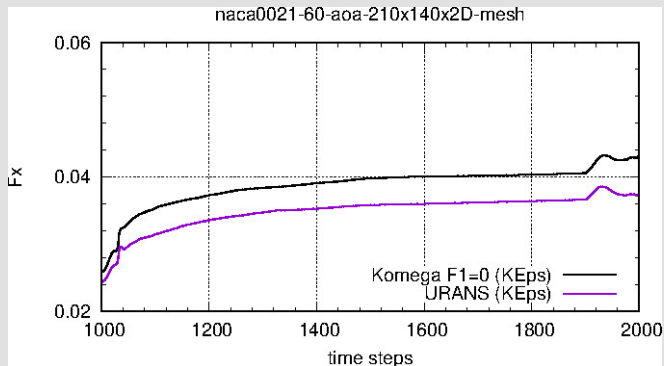
$$\phi = \tanh(\arg_1^4)$$
$$\arg_1 = \min \left[\max \left(\frac{\sqrt{k}}{0.09\omega y}, \frac{500\nu}{y^2\omega} \right), \frac{4\rho\sigma_\omega k}{CD_{k\omega} y^2} \right]$$

where

$$CD_{k\omega} = \max \left(2\rho\sigma_\omega \frac{1}{\omega} \frac{\partial k}{\partial x_j} \frac{\partial \omega}{\partial x_j}, 10^{-20} \right)$$

Slide-10: Validation of $k-\omega$ SST model

Validation step 1: set $\phi = 0$ to recover KEps solution:

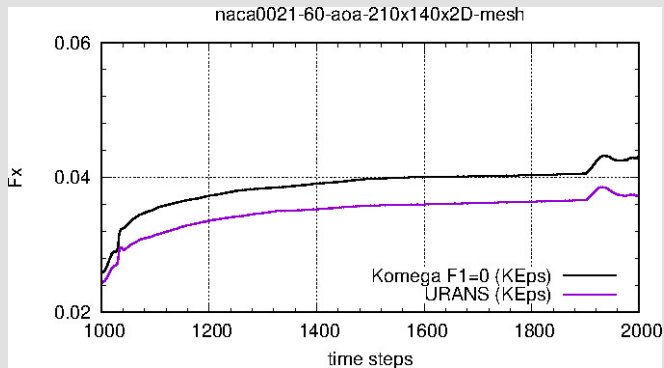


Validation step 2: set $\phi = 1$ to recover $k-\omega$ solution:

Validation step 3: ϕ varies across the field

Slide-11: Validation of $k-\omega$ SST model

Validation step 2: set $\phi = 1$ to recover $k-\omega$ solution:



Slide-12: Validation of $k-\omega$ SST model

Validation step 3: $\phi = \text{varies across the field}$:

