

# Theory of matroids and applications : III

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# Tutte Polynomial

The **Tutte polynomial** of a matroid  $M$  is the generating function defined as follows

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$$\begin{aligned} t(U_{2,3}; x, y) &= \sum_{X \subseteq E, |X|=0} (x-1)^{2-0} (y-1)^{0-0} + \sum_{X \subseteq E, |X|=1} (x-1)^{2-1} (y-1)^{1-1} \\ &+ \sum_{X \subseteq E, |X|=2} (x-1)^{2-2} (y-1)^{2-2} + \sum_{X \subseteq E, |X|=3} (x-1)^{2-2} (y-1)^{3-2} \\ &= (x-1)^2 + 3(x-1) + 3(1) + y - 1 \\ &= x^2 - 2x + 1 + 3x - 3 + 3 + y - 1 = x^2 + x + y. \end{aligned}$$

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The Tutte polynomial can be expressed recursively as follows

$$t(M; x, y) = \begin{cases} t(M \setminus e; x, y) + t(M/e; x, y) & \text{if } e \neq \text{isthmus, loop,} \\ x \cdot t(M \setminus e; x, y) & \text{if } e \text{ is an isthmus,} \\ y \cdot t(M/e; x, y) & \text{if } e \text{ is a loop.} \end{cases}$$

# Acyclic Orientations

Let  $G = (V, E)$  be a connected graph. An **orientation** of  $G$  is an orientation of the edges of  $G$ .

We say that the orientation is **acyclic** if the oriented graph do not contain an oriented cycle (i.e., a cycle where all its edges are oriented clockwise or anti-clockwise).

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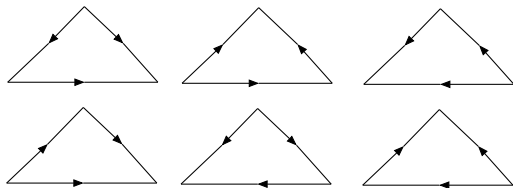
**Theorem** The number of acyclic orientations of  $G$  is equals to

$$t(M(G); 2, 0).$$



# Acyclic Orientations

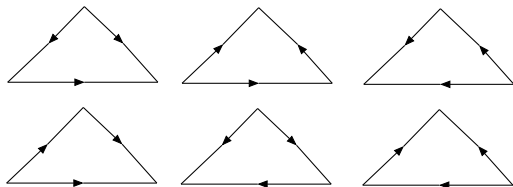
Example : There are 6 acyclic orientations of  $C_3$



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Since  $t(U_{2,3}; x, y) = x^2 + x + y$  then the number of acyclic orientations of  $C_3$  is  $t(U_{2,3}; 2, 0) = 2^2 + 2 + 0 = 6$ .

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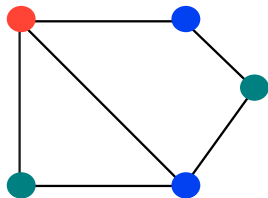
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**Theorem**  $\chi(G, \lambda)$  is a polynomial on  $\lambda$ . Moreover

$$\chi(G, \lambda) = \sum_{X \subseteq E} (-1)^{|X|} \lambda^{\omega(G[X])}$$

where  $\omega(G[X])$  denote the number of connected components of the subgraph generated by  $X$ .

**Proof (idea)** By using the inclusion-exclusion formula.



# Chromatic Polynomial

The **chromatic polynomial** has been introduced by Birkhoff as a tool to attack the **4-color problem**.

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**Theorem** If  $G$  is a graph with  $\omega(G)$  connected components. Then,

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**Exemple** :  $\chi(K_3, 3) = 3^1 (-1)^{3-1} t(K_3; 1 - 3, 0)$

$$= 3 \cdot 1 \cdot t(U_{2,3}; -2, 0) = 3((-2)^2 - 2 + 0) = 6.$$

# Ehrhart Polynomial

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A polytope is called **integer** if all its vertices have integer coordinates.

Ehrhart studied the function  $i_P$  that counts the number of integer points in the polytope  $P$  *dilated* by a factor of  $t$

$$\begin{aligned}i_P : \mathbb{N} &\longrightarrow \mathbb{N}^* \\ t &\mapsto |tP \cap \mathbb{Z}^d|\end{aligned}$$

# Ehrhart Polynomial

Theorem (Ehrhart)  $i_P$  is a polynomial on  $t$  of degree  $d$ ,

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All others coefficients remain a mystery !!

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The **Minkowski's sum** of two sets  $A$  and  $B$  of  $\mathbb{R}^d$  is

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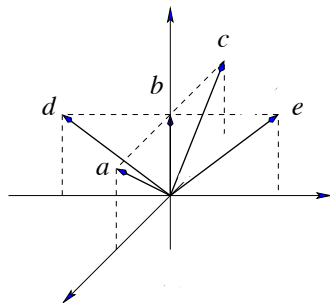
$$A + B = \{a + b \mid a \in A, b \in B\}.$$

Let  $A = \{v_1, \dots, v_k\}$  be a finite set of elements of  $\mathbb{R}^d$ .

A **zonotope** generated by  $A$ , denoted by  $Z(A)$ , is a polytope formed by the Minkowski's sum of line segments

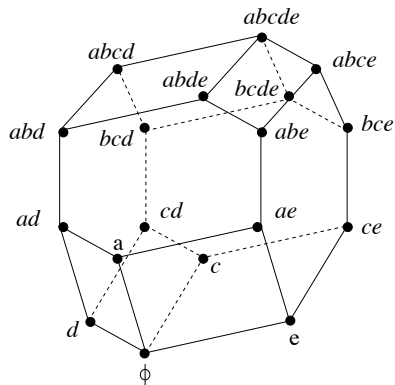
$$Z(A) = \{\alpha_1 v_1 + \dots + \alpha_k v_k \mid \alpha_i \in [0, 1]\}.$$

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## Permutahedron



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**Theorem** Let  $M$  be a regular matroid and let  $A$  be one of its representation matrix. Then, the Ehrhart polynomial associated to the zonotope  $Z(A)$  is given by

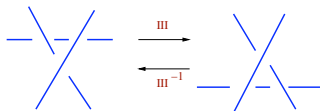
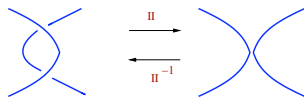
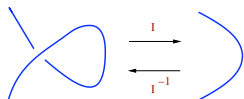
$$i_{Z(A)}(q) = q^{r(M)} t \left( M; 1 + \frac{1}{q}, 1 \right).$$



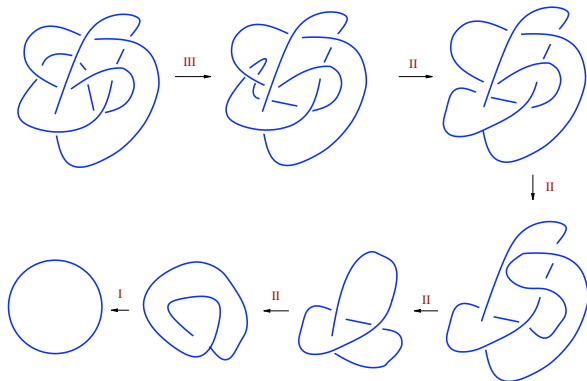
# Knots



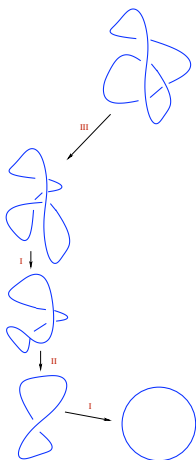
## Reidemeister moves



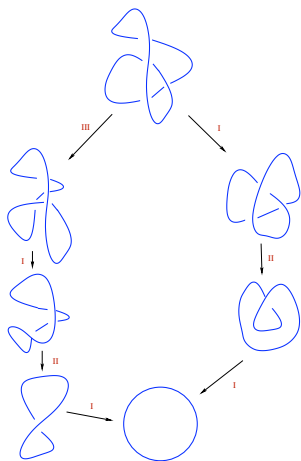
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## Bracket polynomial

For any link diagram  $D$  define a Laurent polynomial  $\langle D \rangle$  in one variable  $A$  which obeys the following three rules where  $U$  denotes the **unknot** :

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$$i) \quad \langle U \rangle = 1$$

$$ii) \quad \langle U + D \rangle = -(A^2 + A^{-2}) \langle D \rangle$$

$$iii) \quad \langle \begin{array}{c} \diagup \quad \diagdown \\ \diagdown \quad \diagup \end{array} \rangle = A \langle \begin{array}{c} \diagdown \quad \diagup \\ \diagdown \quad \diagup \end{array} \rangle + A^{-1} \langle \rangle \langle \rangle$$

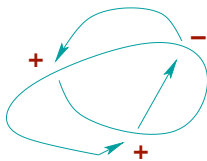
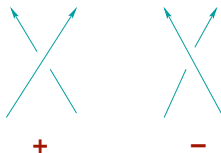
**Theorem** For any link  $L$  the bracket polynomial is independent of the order in which rules (i) – (iii) are applied to the crossings. Further, it is invariant under the Reidemeister moves II and III but it is not invariant under Reidemeister move I!!



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The **writhe** of an oriented link diagram  $D$  is the sum of the signs at the crossings of  $D$  (denoted by  $\omega(D)$ ).

# Knots



$$\omega(D)=1$$

**Theorem** For any link  $L$  define the Laurent polynomial

$$f_D(A) = (-A^3)^{\omega(D)} \langle L \rangle$$

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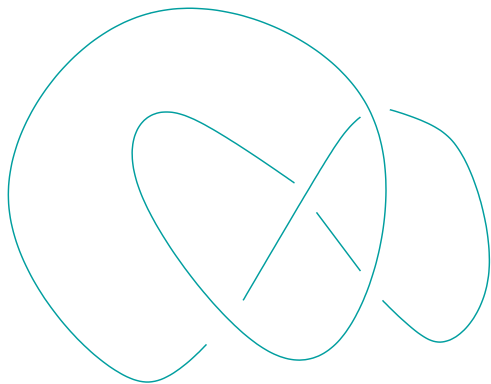
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Now, define for any link  $L$

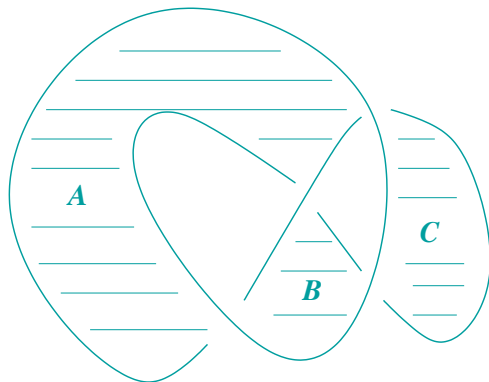
$$V_L(z) = f_D(z^{-1/4})$$

where  $D$  is any diagram representing  $L$ . Then  $V_L(z)$  is the **Jones polynomial** of the oriented link  $L$ .

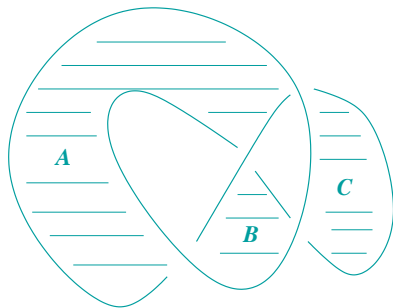
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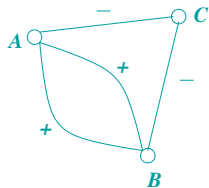
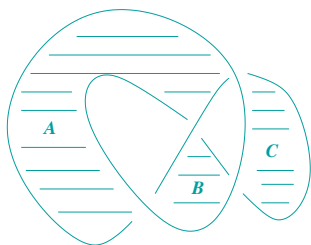
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**Theorem (Thistlethwaite 1987)** If  $D$  is an oriented alternating link diagram then

$$V_L(z) = (z^{-1/4})^{3\omega(D)-2} t(M(G); -z, -z^{-1})$$

where  $G$  is the graph associated to the knot diagram.

# More applications

- Code theory
- Flow polynomial
- Bicycle space of a graph
- Statistical mechanics
- Arrangements of hyperplanes

⋮